This document is intended to meet the requirements documented in section 1968.2 of Title 13, California Code of Regulations entitled Modifications to Malfunction and Diagnosis System Requirements for 2004 and Subsequent Model-Year Passenger Cars, Light-Duty Trucks, and Medium-Duty Vehicles and Engines (OBD II), paragraphs (i)(2.2) for a table detailing calibration parameter data for OBD II Group 13OBDG09.

Section 1: S1-130BDG09

Contains information that is common to all applications within 13OBDG09

GMT911 - Chevrolet Silverado HD

GMT610 - Chevrolet Express

GMT912 - GMC Sierra HD

Section 2: S2-13OBDG09_Glow Plug Module

Contains diagnostic information that is performed within the Glow Plug Control Module and common to all applications within 13OBDG09

The diagnostic algorithms are contained within the Glow Plug Control Module, but the Fault Code storage handling and MIL Illumination are performed within the ECM

Section 3: S3-13OBDG09-LML_Specific

Contains information that is specific to the LML applications within 13OBDG09

GMT911 - Chevrolet Silverado HD

GMT912 - GMC Sierra HD

Parameter Definition

Contains definitions of secondary parameters which are used in the parameter document.

These secondary parameters conditions are shown in the respective physical parameters which define each condition.

Calibration Look-Up Tables

Contains the calibration look-up tables from both the Section 1, Section 3, and the Parameter Definitions

Inhibit Tables

Contains the matrix of diagnostics which are inhibited from being executed if an active DTC is stored in the ECM

Enable Tables

Contains the matrix of additional enable conditions which need to be satisfied for each diagnotic to be enabled

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	_ogic and		Parameters		Conditions	S	Required	Illum.
Crankshaft to Camshaft Correlation	P0016	Detects a shift of the camshaft angle by monitoring the average offset angle.	average value of camshaft offset	<	-20.00		ignition on and basic enable conditions met:	=	TRUE see sheet enable tables	- : -	fail conditions exists for more than 4 events test performed continuously 0.01 s rate	В
Turbocharger Boost Control Position Not Learned		Detects in range vane position errors during a vane sweep initiated to learn minimum and maximum vane position values.		<	5.54	%	injection quantity and injection quantity	>=	0.00	mm^ 3/rev	fail conditions exists for 0.01 s monitor runs once per trip with 0.01 s rate whenever enable conditions are met	В
			mean offset learned value at fully open valve position	>	36.94	%	and		100	3/rev		
							accelerator pedal position and	<=	0.10	%		
							Engine Speed and Engine Speed	>=	500.00 760.00	rpm		
							and Vehicle speed	>=	0.00	mph		
							and Vehicle speed and	<=	3.11	mph		
							Battery voltage and	>=	10.00	V		
							Engine Coolant Temperature	>=	71.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Valu	е	Parameters	Conditions		Required	Illum.
						and Engine Coolant Temperature and	<= 99.96	°C		
						Barometric pressure and	>= 65.00	kPa		
						Barometric pressure and	<= 110.00	kPa		
						time since start and	> 10.08	sec		
						Regeneration Active and	= FALSE	-		
						Adaptation is finished for this driving cycle and	= FALSE	-		
						valve open and	= TRUE	-		
						turbocharger offset adaptation timer and	>= 0.60	sec		
						NO Pending or Confirmed DTCs:	= see sheet inhibit tables	-		
						and basic enable conditions met:	= see sheet enable tables	-		
			Path 2:			injection quantity	>= 0.00	mm^		
			time taken to learn the	> 30.00	200	and		3/rev		
			mean offset learned value at fully open valve position	> 30.00	sec	aliu				
						injection quantity	<= 100	mm^ 3/rev		
						and accelerator pedal position and	<= 0.10	%		
						Engine Speed and	>= 500.00	rpm		
	I					Engine Speed	<= 760.00	rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and Vehicle speed and		mph	
					Vehicle speed and Battery voltage	<= 3.11 r >= 10.00	mph V	
					and Engine Coolant		°C	
					Temperature and			
					Engine Coolant Temperature and	<= 99.96	°C	
					Barometric pressure and	>= 65.00	kPa	
					Barometric pressure and		kPa	
					time since start and		sec	
					Regeneration Active and	= FALSE	-	
					Adaptation is finished for this driving cycle and	= FALSE	-	
					valve open and	= TRUE	-	
					turbocharger offset adaptation timer and	>= 0.60	sec	
					NO Pending or Confirmed DTCs:	= see sheet inhibit tables	-	
					and basic enable conditions met:	= see sheet enable tables	-	
			Path 3:		injection quantity		mm^ B/rev	
			mean offset learned value at fully closed valve position	< 68.01 %	and			

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \	/alue	Parameters		Conditions	S	Required	Illum.
			or mean offset learned value at fully closed valve position	>	95.61	%	injection quantity	\ =	100	mm^ 3/rev		
							accelerator pedal position and Engine Speed	<= >=	0.10 500.00	% rpm		
							and Engine Speed and	<=	760.00	rpm		
							Vehicle speed and Vehicle speed	>=	0.00 3.11	mph mph		
							and Battery voltage	>=	10.00	V		
							and Engine Coolant	>=	71.96	°C		
							Temperature and Engine Coolant Temperature	<=	99.96	°C		
							and Barometric pressure and	>=	65.00	kPa		
							Barometric pressure and	<=	110.00	kPa		
							time since start and	>	10.08	sec		
							Regeneration Active and Adaptation is finished for this driving cycle	=	FALSE FALSE	-		
							and valve closed and	=	TRUE	-		
							turbocharger offset adaptation timer	>=	0.60	sec		
							and mean offset learned value at fully open valve position and	>=	5.54	%		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					mean offset learned value at fully open valve position and NO Pending or Confirmed DTCs: and basic enable conditions met:	<= 36.94 % = see sheet - inhibit tables = see sheet - enable tables		
			Path 4:		injection quantity	>= 0.00 mm^		
			1 4.11		injoodon quantity	3/rev		
			time taken to learn the mean offset learned value at fully closed valve position	> 30.00 sec	and			
					injection quantity	<= 100 mm^ 3/rev		
					and accelerator pedal position and	<= 0.10 %		
					Engine Speed and	>= 500.00 rpm		
					Engine Speed and	<= 760.00 rpm		
					Vehicle speed and	>= 0.00 mph		
					Vehicle speed and	<= 3.11 mph		
					Battery voltage and	>= 10.00 V		
					Engine Coolant Temperature	>= 71.96 °C		
					and Engine Coolant Temperature	<= 99.96 °C		
					and Barometric pressure and	>= 65.00 kPa		
					Barometric pressure and	<= 110.00 kPa		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					time since start and Regeneration Active	> 10.08 sec = FALSE -		
					and Adaptation is finished for this driving cycle	= FALSE -		
					and valve closed and	= TRUE -		
					turbocharger offset adaptation timer and	>= 0.60 sec		
					mean offset learned value at fully open valve position and	>= 5.54 %		
					mean offset learned value at fully open valve position and	<= 36.94 %		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					and basic enable conditions met:	= see sheet - enable tables		
Turbocharger Boost Control Circuit	P0045	Diagnoses the Turbo Charger Boost Circuit low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit: ≥ 200 K Ω impedanc e between ECU pin and load	battery voltage	> 11.00 V	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В
					for time and starter is active cranking	> 3.00 sec = FALSE -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not		battery voltage for time and starter is active cranking	> 11.00 V > 3.00 sec = FALSE -	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	
Turbocharger Boost Control Circuit Low Voltage	P0047	low side driver circuit	Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	for time and starter is active cranking	> 11.00 V > 3.00 sec = FALSE -	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger Boost Control Circuit High Voltage		Diagnoses the Turbo Charger Boost Circuit low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	battery voltage	> 11.00 V	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	В
					for time and starter is active cranking	> 3.00 sec = FALSE -		
Turbocharger Boost High Control Circuit Low Voltage		Diagnoses the Turbo Charger Boost Circuit high side driver circuit for circuit faults.	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 1.5 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Valu	ıe	Secondary Parameters	Ena Condi		Time Required	MIL Illum.
Turbocharger Boost High Control Circuit High Voltage	P006F	Diagnoses the Turbo Charger Boost Circuit high side driver circuit for circuit faults.	Voltage high during driver off state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	1	battery voltage	> 11.	00 V	fail conditions exists for 0.1 s monitor runs with 0.1 s rate whenever enable conditions are met	В
						for time and starter is active cranking	> 3.0 = FAL			
CAC Temperature Sensor Circuit Low Voltage	P007C	Detects a CAC temperature sensor circuit short to ground.	CAC downstream temperature sensor voltage same as downstream CAC temperature	< 0.11 > 150	°C	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= TR = see s ena tab = see s inh tab	heet - ble les heet - ibit	fail conditions exists for 5 s test performed continuously 0.1 s rate	A
CAC Temperature Sensor Circuit High Voltage	P007D	Detects a CAC temperature sensor circuit short to high voltage or a sensor open circuit	CAC downstream temperature sensor voltage	> 4.93	V	ignition on	= TR	UE -	fail conditions exists for 5 s test performed continuously 0.1 s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value		Conditions	Required	Illum.
			downstream CAC temperature	< -53 °	basic enable conditions met: and NO Pending or Confirmed DTCs:	= see sheet - enable tables = see sheet - inhibit tables		
Fuel Rail Pressure [FRP] Too Low	P0087	Measured rail pressure is checked against desired rail pressure to detect low rail pressure conditions.	rail pressure deviation from set point calculated out of difference between desired and actual value (see Look-Up- Table #68)	> 11000 to k	state machine rail pressure control equal to metering unit control mode	= TRUE -	fail conditions exists for 8 s monitor runs with 0.02 s rate whenever enable conditions are met	В
					and basic enable conditions met: and metering unit actuator test active and NO Pending or Confirmed DTCs:	see sheet - enable tables = FALSE - see sheet - inhibit tables		
			rail pressure deviation from set point calculated out of difference between desired and actual value (see Look-Up-Table #71)	> 11000 to ki 80000	state machine rail pressure control equal to pressure control valve or	= TRUE -	fail conditions exists for 8 s monitor runs with 0.02 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value		Parameters		Conditions		Required	Illum.
						state machine rail pressure control equal coupled pressure control (rail pressure is controlled by metering unit and pressure control valve)	=	TRUE			
						and basic enable conditions met: and	=	see sheet enable tables	-		
						metering unit actuator test active and	=	FALSE	-		
						NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Fuel Rail Pressure	P0088	Measured rail	rail pressure deviation	< -80000 to - kl	Pa	current injection quantity	>	8.00	mm^	fail conditions	В
[FRP] Too High	P0088	pressure is checked against desired rail pressure to detect high rail pressure conditions.	from set point calculated out of difference between desired and actual value (see Look-Up- Table #69)	10000 to - Ki	Pa	current injection quantity	,		mm^ 3/rev		В
						and state machine rail pressure control equal to metering unit control mode	=	TRUE	-	met	
						and basic enable conditions met:	=	see sheet enable tables	-		
						and metering unit actuator test active and	=	FALSE	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	rail pressure deviation from set point calculated out of difference between desired and actual value	< -10000.00 kPa	Parameters NO Pending or Confirmed DTCs: (state machine rail pressure control equal to pressure control valve or state machine rail pressure control equal coupled pressure control equal coupled pressure is controlled by metering unit and pressure control valve))) and basic enable conditions met: and NO Pending or Confirmed DTCs:	= See sheet - inhibit tables = TRUE - = TRUE - = TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exists for 8 s monitor runs with 0.02 s rate whenever enable conditions are met	Illum.
Engine Coolant Temperature (ECT)- Fuel Temperature Not Plausible		Detects a biased ECT or fuel temperature by comparing start-up temperatures between the two sensors.		> 100 to °C 999	minimum engine-off time and ambient temperature	>= 28800.00 sec > -60.04 °C	fail conditions exists for 0.2 s monitor runs once per trip with 0.2 s rate whenever enable conditions are met	В

Component /	Fault Code	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable Conditions		Time	MIL Illum.
System	Code	Description	Criteria		Logic and Va	aiue	Parameters		Conditions		Required	illum.
			(a) captured engine coolant temperature at start	=	measured parameter	-	and					
			and				engine speed (see Look-Up- Table #91)	>	600 to 850	rpm		
			(b) captured fuel temperature at start	=	measured parameter	-	for					
)				time and	>	0.00	sec		
			or Path 2:				engine post drive/ afterun and	=	FALSE	-		
			(a) - (b) (see Look- Up-Table #15)	<=	100 to 999	°C	diagnostic performed in current dc	=	FALSE	-		
			with (a) captured engine coolant temperature at start	=	measured parameter	-	and basic enable conditions met:	=	see sheet enable tables	-		
			and (b) captured fuel temperature at start	=	measured parameter	-	and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
			and (a) - (b) (see Look- Up-Table #16)	>	20 to 999	°C						
			where (a) captured engine coolant temperature at start	=	measured parameter	-						
			and (b) captured fuel temperature at start	=	measured parameter	-						
			and (

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Gystein	Odd	Description	status of block heater (see parameter definition)	= FALSE -	ranneters	Conditions	required	mam.
Fuel Pressure Regulator 1 Control Circuit/Open	P0090	Diagnoses the Fuel Pressure Regulator 1 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	for time and starter is active cranking for time and basic enable conditions met:	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec = see sheet - enable tables	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	A
			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		for time and starter is active cranking for time and	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Gyotoliii		Joseph Marie		20gio ana valac	basic enable conditions met:	= see sheet - enable tables	required	
Fuel Pressure Regulator 1 Control Circuit Low	P0091	Diagnoses the Fuel Pressure Regulator 1 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	battery voltage	> 11.00 V	fail conditions exists for 0.75 s monitor runs with 0.01 s rate whenever enable conditions are met	A
					time and starter is active cranking for time and basic enable conditions met:	> 3.00 sec = FALSE - > 3.00 sec = see sheet - enable tables		
Fuel Pressure Regulator 1 Control Circuit High	P0092	Diagnoses the Fuel Pressure Regulator 1 low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	battery voltage for time	> 11.00 V	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshologic and Va		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
System	Ode	Description	Ontena		ogic and ve		starter is active cranking for time and basic enable conditions met:	> =	FALSE - 3.00 sec see sheet - enable tables	Required	mum.
Intake Air Temperature (IAT) Sensor 2 Circuit Low Voltage	P0097	Detects low voltage readings on the MAF IAT circuit, indicating an OOR low condition on the MAF IAT circuit (IAT #2)	MAF intake air temperature sensor voltage same as intake air temperature	>	0.08	V °C	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 5 s test performed continuously with 0.1 s rate	А
Intake Air Temperature (IAT) Sensor 2 Circuit High Voltage	P0098	Detects high voltage readings on the MAF IAT circuit, indicating an OOR high condition on the MAF IAT circuit (IAT#2)	MAF intake air temperature sensor voltage same as intake air temperature	>	4.93 -52	°C	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 5 s test performed continuously with 0.1 s rate	А

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 1 High Control Circuit Low Voltage	P00C9	Diagnoses the Fuel	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	basic enable conditions met:	= see sheet - enable tables	fail conditions exists for 0.5s monitor runs with 0.01 s rate whenever enable conditions are met	A
Fuel Rail Pressure Regulator 1 High Control Circuit High Voltage	P00CA	high side driver circuit	Voltage high during driver off state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and starter is active cranking for time and engine post drive/ afterun for time and basic enable conditions met:	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec = TRUE - > 2.00 sec = see sheet - enable tables	fail conditions exists for 0.1 s monitor runs with 0.1 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria	L	ogic and Va	alue	Parameters	Co	nditions	Required	Illum.
Intake Air Temperature Sensor 3 Circuit Low Voltage	P00EA	Detects low voltage readings on the intake air temperature sensor 3 circuit, indicating an OOR low condition.	intake air temperature sensor 3 voltage	<	0.03	V	ignition on	=	TRUE -	fail conditions exists for 5 s test performed continuously 0.1 s rate	В
			same as temperature of intake air temperature sensor 3	>	250	°C	and basic enable conditions met: and NO Pending or Confirmed DTCs:	= S	ee sheet - enable tables ee sheet - inhibit tables		
Intake Air Temperature Sensor 3 Circuit High Voltage	P00EB	Detects high voltage readings on the intake air temperature sensor 3 circuit, indicating an OOR high condition.		>	4.93	V	ignition on	=	TRUE -	fail conditions exists for 5 s test performed continuously 0.1 s rate	В
			same as temperature of intake air temperature sensor 3	<	-53	°C	and basic enable conditions met: and NO Pending or Confirmed DTCs:	= S	ee sheet - enable tables ee sheet - inhibit tables		
Humidity Sensor Circuit Low	P00F4	Detects a low duty cycle signal from the humidity sensor, indicating an OOR low condition on the humidity sensor circuit	Humidity Sensor Duty Cycle	<	5.00	%	Engine Running (please see the definition)	=	TRUE -	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
			same as relative humidity	>	100.00	%	and following conditions for time: battery voltage battery voltage and basic enable conditions met: and no pending or confirmed DTCs	>	1.00 11.00 655.34 see sheet enable tables see sheet inhibit tables	sec V V		
		The internal ECM PWM circuit driver detects either a duty cycle which has not been received or the maximum period has been exceeded, indicating short low condition on the humidity sensor circuit.	and ECM PWM circuit maximum period detected or Internal ECM PWM period not received	= =	TRUE TRUE	-	Engine Running (please see the definition) and following conditions for time: battery voltage battery voltage	= ^ ^ V	1.00 11.00 655.34	sec V	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	
			репои постесевчей				and basic enable conditions met: and no pending or confirmed DTCs	=	see sheet enable tables see sheet inhibit tables	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	ı	Threshol ogic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Humidity Sensor Circuit High	P00F5	Detects a high duty cycle signal from the humidity sensor, indicating an OOR high condition on the humidity sensor circuit	Humidity Sensor Duty Cycle	>	95.00	%	Engine Running (please see the definition)	=	TRUE	-	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	В
			same as relative humidity	<	0.00	%	and following conditions for time: battery voltage battery voltage and basic enable conditions met: and no pending or confirmed DTCs	>	1.00 11.00 655.34 see sheet enable tables see sheet inhibit tables			
		The internal ECM PWM circuit driver detects either a duty cycle which has not been received or the maximum period has been exceeded, indicating short high condition on the humidity sensor circuit.	and ECM PWM circuit high voltage and ECM PWM circuit maximum period detected or Internal ECM PWM period not received	= =	TRUE TRUE	-	Engine Running (please see the definition) and following conditions for time: battery voltage battery voltage	>	1.00 11.00 655.34	sec V	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions	;	Required	Illum.
							basic enable conditions met: and no pending or confirmed DTCs	11	see sheet enable tables see sheet inhibit tables			
Humidity Sensor Circuit Intermittent / Erratic	P00F6	The humidity signal performance monitor monitors the humidity signal delta in a defined time interval. The sum of these signal delta's over a number of time intervals is compared to a threshold.	Cumulative Humidity Sensor signal delta accumulated over a defined time interval same as accumulated over time	>=	50.00 5.00 0.13	% counts	Engine Running (please see the definition) and basic enable conditions met: and no pending or confirmed DTCs	= =	see sheet enable tables see sheet inhibit tables		fail conditions exists for 4 out of 5 windows (x out of y), test is performed continuously with 0.1 s rate	В
Mass Air Flow (MAF) Sensor Performance	P0101	Detects skewed MAF sensor by comparing measured MAF to calculated expected MAF based on volumetric efficiency of the engine	(measured air mass flow signal with	<	(a) - (b)	-	ambient pressure	>	74.80	kPa	fail conditions exists for 10 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions		Required	Illum.
•		·	(a) engine load dependent MAP for calculating lower threshold and with (b) air temperature dependent correction factor curve (see Look-	=	0.8 0 to 0.05	-	engine coolant temperature and engine coolant temperature	>=	69.96	°C		
			Up-Table #1) or measured air mass flow signal	>	(c) + (b)	-	and					
			with (c) Engine load dependent MAP for calculating higher threshold	=	1.2	-	gradient of the charge-air temperature	>=	-2.00	°C / sec		
			and with (b) air temperature dependent correction factor curve (see Look- Up-Table #1)	=	0 to 0.05	-	and gradient of the charge-air temperature	<=	2.00	°C / sec		
)				and (
							Engine Running (see parameter definition) for	=	TRUE	-		
							time since start) and	>	90.00	sec		
							control value of the throttle valve and	>=	-400.00	%		
							control value of the throttle valve and	<=	5.00	%		
							setpoint valve position of exhaust-gas recirculation and	>=	-400.00	%		
							setpoint valve position of exhaust-gas recirculation for	<=	2.00	%		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Va	lue	Parameters		Conditions		Required	Illum.
							time) and (^	3.00	sec		
							and injection quantity	<=		mm^ 3/rev		
							and air pressure in the induction volume	<=	280.00	kPa		
							and					
							engine speed and	>=	-16384.00	rpm		
							engine speed	<=	3100.00	rpm		
							and					
							intake air temperature and	>=	-7.04	°C		
							intake air temperature	<=	51.96	°C		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Mass Air Flow (MAF) Sensor Circuit High Voltage		readings on the MAF	signal period of air mass flow sensor (MAF)	>	881.00	us	ignition on	=	TRUE	-	fail conditions exists for 3 s monitor runs 0.01 s rate whenever	A
			same as air mass flow	<	3.9	kg/h	and basic enable conditions met:	=	see sheet enable tables	-	enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions	3	Required	Illum.
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Mass Air Flow (MAF) Sensor Circuit Low Voltage	P0103	Detects high frequency readings on the MAF circuit, indicating an OOR high condition on the MAF circuit	or signal period of air mass flow sensor (MAF) same as air mass flow	= <	TRUE 50.00	us kg/h	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables		fail conditions exists for 3 s monitor runs 0.01 s rate whenever enable conditions are met	A
Manifold Absolute Pressure (MAP) Sensor Performance	P0106	Detects a skewed MAP or BARO sensor by comparing MAP readings to the BARO sensor	Path 1: (a) - (b) or Path 2: (a) - (b) where (a) MAP sensor measured pressure and	< > =	-15.00 15.00 measured parameter	kPa kPa	measured coolant engine downstream temperature and current injection quantity and actuator position of throttle valve and turbo charger (VNT) wiping is active and	> < <= =	-3549.94 1308.00 327.67 FALSE	°C mm^ 3/rev %	fail conditions exists for 5 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		ogic and Va		Parameters		Conditions		Required	Illum.
			(b) BARO sensor measured pressure		measured parameter		engine speed and engine speed) and vehicle speed and basic enable conditions met: and NO Pending or Confirmed DTCs:	>= <= =	100.00 դ	pm nph -		
Manifold Absolute Pressure (MAP) Sensor Circuit Low Voltage	P0107	readings on the MAP circuit, indicating an OOR low condition on the MAP circuit	Path 1: (sensor voltage of manifold absolute pressure same as manifold absolute pressure and actuator position of throttle valve) or Path 2: (sensor voltage of manifold absolute pressure	< <= <	0.91 44.9 20.00	V kPa %	engine synchronization completed and basic enable conditions met:	=	TRUE see sheet enable tables		fail conditions exists for 5 s test performed continuously 0.01 s rate	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Thresho Logic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Gystem	Ode	Description	same as manifold absolute pressure and actuator position of throttle valve)	>	-0.3 20.00	kPa %	r arameters		Soliditions		Required	mum.
Manifold Absolute Pressure (MAP) Sensor Circuit High Voltage	P0108	readings on the MAP	sensor voltage of manifold absolute pressure same as manifold absolute pressure	>	4.75 371.3	V kPa	engine synchronization completed and basic enable conditions met:	=	TRUE see sheet enable tables		fail conditions exists for 5 s test performed continuously 0.01 s rate	A
Intake Air Temperature Sensor 1 Circuit Low	P0112		Humidity Temperature sensor period same as humidity temperature	>	0.00260	sec °C	Engine Running (please see the definition) and following conditions for time: battery voltage battery voltage and basic enable conditions met: and	-	1.00 11.00 655.34 see sheet enable tables	sec V	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Thresho		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
							no pending or confirmed DTCs	=	see sheet inhibit tables	-		
		The internal ECM PWM circuit driver detects either a duty cycle which has not been received or the maximum period has been exceeded, indicating short low condition on the humidity sensor circuit.	Internal ECM PWM circuit low voltage	=	TRUE	-	Engine Running (please see the definition)	=	TRUE	-	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	
			and ECM PWM circuit maximum period detected	=	TRUE	-	and following conditions for time:	>	1.00	sec		
			or Internal ECM PWM period not received	=	TRUE	-	battery voltage battery voltage and	> <	11.00 655.34	V V		
							basic enable conditions met:	=	see sheet enable tables	-		
							and no pending or confirmed DTCs	=	see sheet inhibit tables	-		
Intake Air Temperature Sensor 1 Circuit High	P0113		Humidity Temperature sensor period	>	0.10	sec	Engine Running (please see the definition)	=	TRUE	-	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	В

Component /	Fault	Monitor Strategy	Primary Malfunction			Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Va		Parameters	Conditions	Required	Illum.
			humidity temperature	< -65.00	°C	following conditions for time: battery voltage battery voltage and basic enable conditions met: and no pending or confirmed DTCs	> 1.00 sec > 11.00 V < 655.34 V = see sheet - enable tables = see sheet - inhibit tables		
		The internal ECM PWM circuit driver detects either a duty cycle which has not been received or the maximum period has been exceeded, indicating short high condition on the humidity sensor circuit.	and ECM PWM circuit high voltage ECM PWM circuit maximum period detected or Internal ECM PWM period not received	= TRUE = TRUE	-	Engine Running (please see the definition) and following conditions for time: battery voltage battery voltage and basic enable conditions	= TRUE - > 1.00 sec > 11.00 V < 655.34 V = see sheet -	fail conditions exists for 0.1 s test performed continuously with 0.1 s rate	
						met: and no pending or confirmed DTCs	enable tables = see sheet - inhibit tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshold ogic and Va		Secondary Parameters	C	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature (ECT) Sensor Circuit Low Voltage	P0117	Detects low voltage readings on the ECT circuit, indicating an OOR low condition on the ECT circuit	voltage of engine coolant temperature sensor same as engine coolant temperature	^	0.51 68	°C	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 15 s test performed continuously 0.2 s rate	A
Engine Coolant Temperature (ECT) Sensor Circuit High Voltage	P0118	Detects high voltage readings on the ECT circuit, indicating an OOR high condition on the ECT circuit	voltage of engine coolant temperature sensor same as engine coolant temperature	> <	4.90 -53	v °C	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 60 s test performed continuously 0.2 s rate	A
Engine Coolant Temperature (ECT) Below Thermostat Regulating Temperature	P0128	Detects a stuck open thermostat by comparing actual engine coolant heat up profile to an expected modeled heat up profile. The targets are dependent on start up conditions (high and low regions)	coolant temperature at start, and ambient	>=	59.96 49.96	°C	engine pre drive and time since start	= <	FALSE -	fail conditions exists for 0.2 s monitor runs once per trip with 0.2 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
		Low Region Engine Temperature at start < 31 degC AND ambient air temperature <= 10 degC.			measured engine coolant temperature and	>=	-40.04	°C		
		acgo.			captured value of coolant temperature during start and	<=	30.96	°C		
					(ambient temperature and	>	-7.04	°C		
					ambient temperature) and	<	59.96	°C		
					ambient temperature (used for low region determination)	<=	9.96	°C		
					and engine idle time ratio which is defined by (idle time divided by time since start) where idle time is incremented when:	<	0.50	%		
					accelerator pedal value and	<=	10.01	%		
					vehicle speed and	<=	9.94	mph		
					engine speed) and diagnostic performed in current dc	<= =	750.00 FALSE	rpm -		
					and					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Val	ue	Parameters		Conditions		Required	Illum.
							basic enable conditions met: and NO Pending or Confirmed DTCs:	11	see sheet enable tables see sheet inhibit tables			
		thermostat by comparing actual engine coolant heat up profile to an expected	coolant temperature at start, and ambient	>=	81.96	°C	engine pre drive	=	FALSE	-		
		High region Engine Temperature at start < 52 degC AND ambient air temperature > 10 degC	and measured engine coolant temperature	<	70.96	°C	and time since start and measured engine coolant temperature and	< >=	1440.00 -40.04	sec °C		
							captured value of coolant temperature during start and (ambient temperature and ambient temperature) and	<= > <	51.96 -7.04 59.96	ô ô		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and V	alue	Parameters		Conditions		Required	Illum.
						ambient temperature (used for high region determination) and	>	9.96	Ô		
						engine idle time ratio which is defined by (idle time divided by time since start) where idle time is incremented when: (<	0.50	%		
						accelerator pedal value and	<=	10.01	%		
						vehicle speed and	<=	9.94	mph		
						engine speed) and diagnostic performed in current dc	=	750.00 FALSE	rpm -		
						and basic enable conditions met: and	=	see sheet enable tables	-		
						NO Pending or Confirmed DTCs:	II	see sheet inhibit tables	-		
HO2S Bank 1 Sensor 1 Circuit Low	P0131	Detects an out of range low fault of the upstream Nox sensor lambda signal	Upstream Nox sensor lambda signal received via CAN	< -150.00	counts	Valid upstream NOx signal from CAN is received (no Nox sensor communication failures)	=	TRUE	-	fault exists for more than 10 sec; monitor runs at 0.1 s	В
				(-150 counts = 1100 Lambda = ~27 %O2)	-	Engine Running (see parameter definition)	=	TRUE	1	when enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Thresho		Secondary		Enable	Time	MIL
System	Code	Description	Criteria	Logic and \	/alue	Parameters		Conditions	Required	Illum.
						for time (required for the NOx sensor to give valid response) and basic enable conditions met:	> =	20.00 sec see sheet - enable tables		
HO2S Bank 1 Sensor 1 Circuit High	P0132	Detects an out of range high fault of the upstream Nox sensor lambda signal	Upstream Nox sensor lambda signal received via CAN	> 1550.00 (1550 counts = 0.65 Lambda = -0.1178 %O2)	counts	Valid upstream NOx signal from CAN is received (no Nox sensor communication failures) Engine Running (see parameter definition)	=	TRUE -	fault exists for more than 3 sec; monitor runs at 0.1 s when enable conditions are met	В
						for time (required for the NOx sensor to give valid response) and basic enable conditions met:	=	20.00 sec see sheet - enable tables		
HO2S Bank1 Sensor2 Circuit Low	P0137	Detects an out of range low fault of the downstream Nox sensor lambda signal	Downstream Nox sensor lambda signal received via CAN	 -150.00 (-150 counts = 1100 Lambda = ~27 %O2) 	counts	Valid downstream NOx signal from CAN is received (no Nox sensor communication failures) Engine Running (see parameter definition)	=	TRUE -	fault exists for more than 3 sec; monitor runs at 0.1 s when enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria	Logic and Va		Parameters for time (required for the NOx sensor to give valid response) and basic enable conditions met:	> =	20.00 second	Required	Illum.
HO2S Bank1 Sensor2 Circuit High	P0138	Detects an out of range high fault of the downstream Nox sensor lambda signal	Downstream Nox sensor lambda signal received via CAN	> 1550.00 (1550 counts = 0.65 Lambda = -0.1178 %O2)		Valid downstream NOx signal from CAN is received (no Nox sensor communication failures) Engine Running (see parameter definition) for time (required for the NOx sensor to give valid response) and basic enable conditions met:	=	TRUE - TRUE - 20.00 second see sheet enable tables	fault exists for more than 3 sec; monitor runs at 0.1 s when enable conditions are met	В
O2 Sensor Slow Response - Rich to Lean Bank 1 Sensor 1	P014C	NOx sensor monitoring; transition time is too high to achieve an expected amount of oxygen	Measured O2 concentration at NOx sensor for transition time	< Calculate d O2 concentra tion at NOx sensor >= 2.00	sec	### Basic enable conditions ### Engine speed and	<	4000.00 rpm	fault exists for more than 0.1 sec; monitor runs at 0.1 s when enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
					Battery voltage and Ambient Air Pressure Ambient Air Pressure	> >= <=	11.00 74.80 106.00	V kPa kPa		
					and Ambient Air Temperature Ambient Air Temperature and	>= <=	-7.04 124.96	°C		
					Regeneration Active and Oxygen Concentration Signal and	=	FALSE active	-		
					NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
					Active Communication with NOx Sensor and	=	TRUE	-		
					DOC Upstream Temperature	>=	-0.04	°C		
					DOC Upstream Temperature	<=	1299.96	°C		
					### Additional enable conditions during "wait for calibrated time to exclude dynamic effects" ####					
					calculated O2 signal (based on injection quantity, air mass and fuel density) and	<	0.12	-		
					Fuel Injection Quantity and	>	120.00	mm^ 3/rev		
					Engine speed for time	>	600.00 1.80	rpm sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					### Additional enable conditions during "calculate O2 threshold dependent on injection quantity, air mass and fuel density for evaluation of transition time" ###			
					Fuel Injection Quantity with a) Measured and stored Fuel Injection Quantity at start of diagnosis	< (a) + (b) - = measured - parameter		
					 b) Decline of Injection Quantity from stored fuel quantity at start of diagnosis and 	>= 18.00 mm^ 3/rev		
					Fuel Injection Quantity with a) Measured and stored Fuel Injection Quantity at start of diagnosis	> (a) - (b) = measured - parameter		
					 b) Decline of Injection Quantity from stored fuel quantity at start of diagnosis and 	>= 18.00 mm^ 3/rev		
					### Additional enable conditions during "wait for calibrated time dependent on exhaust gas mass flow to concern exhaust gas transfer time" ###	> 600.00 rpm		
					Fuel Injection Quantity with a) Measured and stored Fuel Injection Quantity at start of diagnosis	<= (a) - (b) - = measured - parameter		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					 b) Decline of Injection Quantity from stored fuel quantity at start of diagnosis 	>= 18.00 mm [^] 3/rev		
					and Fuel Injection Quantity with a) Measured and stored Fuel Injection Quantity at start of diagnosis	< (a) + (b) = measured - parameter		
					 b) Decline of Injection Quantity from stored fuel quantity at start of diagnosis for exhaust gas transfer time 	>= 18.00 mm [^] 3/rev > 0.5 sec		
					### Additional enable conditions during "measure transition time needed to achieve calibrated oxygen threshold" ####			
					actual valve position of exhaust-gas recirculation and	>= 0.00 %		
					actual valve position of exhaust-gas recirculation and	<= 80.00 %		
					Fuel Injection Quantity	< 16.00 mm^ 3/rev		
					### Additional enable conditions during "validate measurement of transition time by excluding dynamic effects" ###			
					Deviation from maximum O2 concentration during overrun and	< 0.06 -		
					Fuel Injection Quantity with	< (a) + (b) -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	a) Measured Minimum Fuel Injection Quantity b) Maximum fluctuation of Injection Quantity ### Additional enable conditions during "set fault" or "clear fault" process ### Deviation from maximum O2 concentration during overrun and Fuel Injection Quantity with a) Measured Minimum Fuel Injection Quantity b) Maximum fluctuation	 16.00 mm[^] 3/rev 0.06 - (a) + (b) measured - parameter 16.00 mm[^] 	Required	Illum.
Fuel Trim System Lean		Monitors the fuel mass observer correction quantity. Detects if the correction quantity exceeds the feedback limit.	Fuel mass observer emission correction quantity (see Look-Up-Table #47)	<= -164.64 to mm^3/rev -46.42	of Injection Quantity Status of the Observer function's lambda-signal means (lambda signal from NOx sensor ready (see parameter definition) fuel system is in fuel cut off (see parameter definition) Particulate Filter Regeneration Mode ((component of combusted fuel in the engine or	3/rev = TRUE - = TRUE - = FALSE - = FALSE - >= 1 -	fail conditions exists for 12 s monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					calculated EGR rate) for time)) and Controller status of the observer	>= 0 - > 1.00 sec = TRUE -		
					means (Load dependent release state (see look up table #) (see Look-Up-Table #48) and Component Protection release state	= 0 to 1 -		
					(see look up table #) (see Look-Up-Table #43)) engine coolant temperature engine coolant temperature Normal Injection Mode Barometric pressure Ambient temperature NO Pending or Confirmed DTCs: basic enable conditions met:	<= 199.96 °C >= 64.96 °C = TRUE >= 74.80 kPa >= -7.04 °C = see sheet - inhibit tables = see sheet - enable tables		
Fuel Trim System Rich	P0172	Monitors the fuel mass observer correction quantity. Detects if the correction quantity exceeds the feedback limit.	Fuel mass observer emission correction quantity (see Look-Up- Table #46)	>= 46.42 to mm^3/re	v Status of the Observer function's lambda-signal means	= TRUE -	fail conditions exists for 12 s monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					lambda signal from NOx sensor ready (see parameter definition) fuel system is in fuel cut off (see parameter	= TRUE = FALSE	-	
					definition) Particulate Filter Regeneration Mode	= FALSE	-	
					((component of combusted fuel in the engine or	>= 1	-	
					calculated EGR rate)	>= 0	-	
					for time)) and	> 1.00 s	ec	
					Controller status of the observer means	= TRUE	-	
					Load dependent release state (see look up table #) (see Look-Up-Table #48) and	= 0 to 1	-	
					Component Protection release state (see look up table #) (see Look-Up-Table #43)	> 0 to 1	-	
					engine coolant temperature engine coolant temperature engine coolant temperature Normal Injection Mode Barometric pressure Ambient temperature NO Pending or Confirmed DTCs: basic enable conditions met:	>= 64.96 = TRUE >= 74.80 k >= -7.04	Pa Pa PC -	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshol ogic and V		Secondary Parameters		Enable onditions	Time Required	MIL Illum.
Fuel Temperature Sensor 1 Circuit Low	P0182	Detects low voltage readings in the fuel pump temperature sensor 1 circuit, indicating an OOR low condition on the fuel pump temperature sensor 1 circuit	voltage of fuel temperature sensor 1 or same as fuel temperature	~	0.60	°C	ignition on and basic enable conditions met:	= = s	TRUE - eee sheet - enable tables	fail conditions exists for 5 s test performed continuously 0.2 s rate	В
Fuel Temperature Sensor 1 Circuit High	P0183	Detects high voltage readings in the fuel pump temperature sensor 1 circuit, indicating an OOR high condition on the fuel pump temperature sensor 1 circuit	voltage of fuel temperature sensor 1	>	4.71	V	ignition on	=	TRUE -	fail conditions exists for 5 s test performed continuously 0.2 ms rate	В
			same as fuel temperature	<	- 50	°C	and basic enable conditions met:	= s	ee sheet - enable tables		
Fuel Temperature Sensor 2 Circuit Low	P0187	Detects low voltage condition of the fuel temperature sensor circuit, indicating an OOR low condition	fuel temperature sensor voltage	<	0.60	V	ignition on	=	TRUE -	fail conditions exists for 5 s test performed continuously 0.2 s rate	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary	E	nable		Time	MIL
System	Code	Description	Criteria	L	ogic and		Parameters		nditions		Required	Illum.
			same as fuel temperature	>	150	°C	and basic enable conditions met:	€	e sheet enable ables	-		
Fuel Temperature Sensor 2 Circuit High	P0188	Detects high voltage condition of the fuel temperature sensor circuit, indicating an OOR high condition	fuel temperature sensor voltage same as fuel temperature	> <	4.75 -50	V °C	ignition on and basic enable conditions met:	= se	TRUE e sheet enable ables		fail conditions exists for 5 s test performed continuously 0.2 s rate	В
Fuel Rail Pressure [FRP] Sensor Performance	P0191	rail pressure sensor by determining the adaptation factor of the fuel rail pressure regulator 2.	fuel pressure regulator 2 adaptation factor or fuel pressure regulator 2 adaptation factor	>= <=	0.75	factor	fuel pressure regulator 2 in closed loop control and adaptation for fuel pressure regulator 2 active means (counter for successful adaptation			- oun ts	fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					or counter for the successful calculation of the adaptation and	> 9.00 coun ts		
					(engine speed and	> 400.00 rpm		
					engine speed)	< 1000.00 rpm		
					and vehicle speed and (<= 1.86 mph		
					state machine rail pressure control equal to pressure control valve or	= TRUE -		
					state machine rail pressure control equal coupled pressure control (rail pressure is controlled by metering unit and pressure control valve)	= TRUE -		
					and basic enable conditions met:	= see sheet - enable tables		
		Detects a biased sensor by determining the FRP sensor voltage to be in the correct range for atmospheric pressure at engine off and with sufficient pressure bleed-off time.	rail pressure sensor	< 0.35 V	engine post drive/ afterun	= TRUE -	ail conditions exists for more than 0.30 s monitor runs once per driving cycle with 0.01 s rate whenever enable conditions are met	
			or		fuel temperature	> -0.04 °C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		ogic and Va		Parameters		Conditions	5	Required	Illum.
			rail pressure sensor voltage)	>	0.65	V	and engine has already run in this driving cycle and	=	TRUE	-		
							rail pressure is reduced means	=	TRUE	-		
							rail pressure and	<	0.00	kPa		
							fuel pressure regulator 2 current and	<=	1.70	Amp s		
							time since engine off and number of fault	>	30.08 10.00	sec		
							measurements during engine postdrive/ afterun and			ts		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
					_				_			
Fuel Rail Pressure [FRP] Sensor Circuit Low	P0192	Detects low voltage readings on the FRP circuit, indicating an OOR low condition on the FRP circuit	rail pressure sensor voltage	<	0.19	V	ignition on	=	TRUE	-	fail conditions exists for 0.14 s monitor runs with 0.01 s rate whenever enable	A
			same as rail pressure	<	0	kPa	and basic enable conditions met: and	=	see sheet enable tables	-	conditions are met	

Component /	Fault Code	Monitor Strategy	Primary Malfunction Criteria		Threshold		Secondary		Enable Conditions		Time	MIL Illum.
System	Code	Description	Criteria		Logic and Va	nue	Parameters NO Pending or Confirmed DTCs:	=	see sheet inhibit tables		Required	mum.
Fuel Rail Pressure [FRP] Sensor Circuit High	P0193	Detects high voltage readings on the FRP circuit, indicating an OOR high condition on the FRP circuit	rail pressure sensor voltage same as rail pressure	۸	4.81 ####################################	V kPa	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:		TRUE see sheet enable tables see sheet inhibit tables		fail conditions exists for 0.2 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Cylinder 1 Injection Timing Retarded	P01CB	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point. Detects a fault when the corrected energizing time exceeds the allowed limit.		^ =	(a) - (b) 384.4	- US	environmental temperature and (fuel temperature and	>=	-7.04 0.06	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	;	Required	Illum.
			and with (b) offset of the maximum filtered energizing time	=	12	us	fuel temperature)	<=	79.96	°C		
)) for				and engine temperature	>	49.96	°C		
			rail pressure point	=	70000.00	kPa	and battery voltage	>	10.00	V		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94) and	>=	5 to 30	sec		
							intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed) and current gear (see Look-Up-	=	1850 0 to 1	rpm -		
							Table #93) and					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Va	ue	Parameters		Conditions	5	Required	Illum.
							vehicle speed and rail pressure deviation from setpoint calculated out of difference between desired and actual value	> <	0 5000.00	mph kPa		
							and rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 2 Injection	P01CD	Monitors the			_		environmental temperature	>	-7.04	°C	fail conditions	В
Timing Retarded	10100	correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	1				environmental temperature		-7.04	O	exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	U
		the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time	=	384.4	us	(fuel temperature and	>=	0.06	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	and with				fuel temperature	<=	79.96	°C	·	
			(b) offset of the maximum filtered	=	12	us)					
			energizing time))				and		40.00	°C		
			for rail pressure point	=	70000.00	kPa	engine temperature and	>	49.96	°C		
							battery voltage and	>	10.00	V		
							combustion chamber is not cold off means time since last combustion (see Look-Up-	>=	5 to 30	sec		
							Table #94) and intake manifold pressure	>	75.00	kPa		
							and intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position	<	0.05	%		
							and Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Val	ue	Parameters		Conditions	•	Required	Illum.
							vehicle speed and rail pressure deviation from setpoint calculated out of difference between desired and actual value	>	0 5000.00	mph kPa		
							and rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 7 Injection Timing Retarded	P01D7	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			with (a) maximum injection energizing time	=	384.4	us	fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	3	Required	Illum.
			(b) offset of the maximum filtered energizing time	=	12	us)					
) for				and engine temperature	>	49.96	°C		
			for rail pressure point	=	70000.00	kPa	and					
							battery voltage and combustion chamber is not cold off means	>	10.00	V		
							time since last combustion (see Look-Up- Table #94) and	>=	5 to 30	sec		
							intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed	=	950	rpm		
							and with (c) gear specific maximum engine speed)	=	1850	rpm		
							, and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	< ^	5000.00 0.10	kPa sec		
							least and no gear change is occurred	=	TRUE	000		
							and 4 wheel mode	=	FALSE	_		
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 8 Injection Timing Retarded	P01D9	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			with (a) maximum injection energizing time and with	=	384.4	us	fuel temperature and fuel temperature	>=	0.06 79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	,	Required	Illum.
			(b) offset of the maximum filtered energizing time	=	12	us) and					
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last	>=	5 to 30	sec		
							combustion (see Look-Up- Table #94) and intake manifold pressure	>	75.00	kPa		
							and intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position	<	0.05	%		
							and					
							Fuel system status and	=	Fuel cut off	-		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	e	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
				-		-						
Cylinder 4 Injection Timing Retarded		Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time	=	384.4	us	(fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	,	Required	Illum.
			(b) offset of the maximum filtered energizing time	=	12	us) and					
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last	>=	5 to 30	sec		
							combustion (see Look-Up- Table #94) and intake manifold pressure	>	75.00	kPa		
							and intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position	<	0.05	%		
							and					
							Fuel system status and	=	Fuel cut off	-		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Val	ue	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 5 Injection	P01D3	Monitors the	(environmental temperature	>	-7.04	°C	fail conditions	В
Timing Retarded		correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.									exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	
		Detects a fault when the corrected energizing time exceeds the allowed limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time	=	384.4	us	(fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	3	Required	Illum.
			(b) offset of the maximum filtered energizing time	=	12	us)					
))				and					
			for rail pressure point	=	70000.00	kPa	engine temperature and	>	49.96	°C		
							battery voltage and	>	10.00	V		
							combustion chamber is not cold off means time since last combustion (see Look-Up-	>=	5 to 30	sec		
							Table #94) and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with (a) value of engine speed	< =	(a) + (c) 30.00	- rnm		
							and with (b) gear specific minimum	=	950	rpm		
							engine speed and with					
							(c) gear specific maximum engine speed)	=	1850	rpm		
							and current gear (see Look-Up- Table #93)	=	0 to 1	-		
							and vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 6 Injection Timing Retarded	P01D5	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		Detects a fault when the corrected energizing time exceeds the allowed limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			with (a) maximum injection energizing time	=	384.4	us	fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	,	Required	Illum.
			(b) offset of the maximum filtered energizing time	=	12	us) and					
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last	>=	5 to 30	sec		
							combustion (see Look-Up- Table #94) and intake manifold pressure	>	75.00	kPa		
							and intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position	<	0.05	%		
							and					
							Fuel system status and	=	Fuel cut off	-		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and Valu	ue	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 3 Injection Timing Retarded	P01CF	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point. Detects a fault when	(corrected energizing	>	(a) - (b)	_	environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time	time for the rail pressure calibration points and cylinder 1		(a) (b)		(
			with (a) maximum injection energizing time	=	384.4	us	fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	,	Required	Illum.
- Oyelein	0000	2000.iptio.i	(b) offset of the maximum filtered energizing time	=	12	us)				rtoquilou	a.iii
))				and		40.00	0.0		
			for rail pressure point	=	70000.00	kPa	engine temperature and	>	49.96	°C		
							battery voltage	>	10.00	V		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	e	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	<	5000.00 0.10	kPa sec		
							least and	=	TRUE	300		
							no gear change is occurred and 4 wheel mode	=	FALSE	-		
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 1 Injection Timing Advanced	P01CC	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time falls	corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and					
			with (a) minimum injection energizing time and with	=	107.2	us	fuel temperature and fuel temperature	>=	0.06 79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	3	Required	Illum.
			(b) offset of the minimum filtered energizing time	=	60	us)					
))				and					
			for rail pressure point	=	70000.00	kPa	engine temperature and	>	49.96	°C		
							battery voltage	>	10.00	V		
							and combustion chamber is not cold off means					
							time since last combustion (see Look-Up- Table #94) and	>=	5 to 30	sec		
							intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	_	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	< ^	5000.00 0.10	kPa sec		
							least and no gear change is occurred	=	TRUE	_		
							and 4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 2 Injection Timing Advanced	P01CE	Monitors the correction values for the energizing time of each cylinder. A correction value for	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate	В
		the energizing time is learned for each cylinder at a calibrated rail pressure operating point.									whenever enable conditions are met	
		the corrected energizing time falls	corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and					
			(with (a) minimum injection energizing time	=	107.2	us	(fuel temperature and	>=	0.06	°C		
1	I		and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	(b) offset of the minimum filtered energizing time	=	60	us) and				·	
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 7 Injection Timing Advanced	P01D8	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time falls	corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and					
			(with (a) minimum injection energizing time	=	107.2	us	(fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	3	Required	Illum.
			(b) offset of the minimum filtered energizing time	=	60	us)					
)) for				and engine temperature	>	49.96	°C		
			rail pressure point	=	70000.00	kPa	and battery voltage	>	10.00	V		
							and combustion chamber is not cold off means time since last combustion (see Look-Up-	>=	5 to 30	sec		
							Table #94) and intake manifold pressure	>	75.00	kPa		
							and intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (/h) /-)			
							engine speed and engine speed	>	(b) - (a) (a) + (c)	-		
							with (a) value of engine speed	=	30.00	rpm		
							and with (b) gear specific minimum	=	950	rpm		
							engine speed and with (c) gear specific maximum engine speed	=	1850	rpm		
) and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
1			ı				vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and Valu	е	Parameters and		Conditions		Required	Illum.
							rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 8 Injection Timing Advanced	P01DA	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time falls	corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and					
			with (a) minimum injection energizing time	=	107.2	us	fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	(b) offset of the minimum filtered energizing time	=	60	us) and				·	
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	< ^	5000.00 0.10	kPa sec		
							least and no gear change is occurred	=	TRUE	_		
							and 4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 4 Injection Timing Advanced	P01D2	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and (
			with (a) minimum injection energizing time and with	=	107.2	us	fuel temperature and fuel temperature	>=	0.06 79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	(b) offset of the minimum filtered energizing time	=	60	us) and				·	
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	<	5000.00 0.10	kPa sec		
							least and no gear change is occurred	=	TRUE	_		
							and 4 wheel mode	=	FALSE	-		
							and basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 5 Injection Timing Advanced	P01D4	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and (
			with (a) minimum injection energizing time and with	=	107.2	us	fuel temperature and fuel temperature	>=	0.06 79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	(b) offset of the minimum filtered energizing time	=	60	us) and				·	
) for rail pressure point	=	70000.00	kPa	engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at	< ^	5000.00 0.10	kPa sec		
							least and no gear change is occurred	=	TRUE	_		
							and 4 wheel mode	=	FALSE	-		
							and basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 6 Injection Timing Advanced	P01D6	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and					
			with (a) minimum injection energizing time and with	=	107.2	us	fuel temperature and fuel temperature	>=	0.06 79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		onditions		Required	Illum.
		,	(b) offset of the minimum filtered energizing time	=	60	us)					
))				and 		40.00	° °		
			for rail pressure point	=	70000.00	kPa	engine temperature and	>	49.96	°C		
							battery voltage and combustion chamber is not	>	10.00	V		
							cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	= 1	Fuel cut off	-		
							and (
							engine speed and	>	(b) - (a)	-		
							engine speed with	< ((a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
) and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ie	Parameters		Conditions		Required	Illum.
							and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change is occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 3 Injection Timing Advanced	P01D0	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at a calibrated rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected energizing time falls	corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	and (
			with (a) minimum injection energizing time	=	107.2	us	tuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	3	Required	Illum.
		·	(b) offset of the minimum filtered energizing time	=	60	us)					
) for rail pressure point	=	70000	kPa	and engine temperature and battery voltage	>	49.96 10.00	°C		
							and combustion chamber is not cold off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
							and intake manifold pressure and	>	75.00	kPa		
							intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status and	=	Fuel cut off	-		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed	>	0	mph		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	,	Threshologic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Cystem -	Ode	Description	Ontona		ogio ana V	2.00	and rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<		kPa	Troquileu	mulli
							rail pressure is stable for at least and no gear change is occurred	>	TRUE	sec -		
							and 4 wheel mode	=	FALSE	-		
							and basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Coolant Temperature Dropped Below Diagnostic Monitoring Temperature	P01F0	Detects a stuck open thermostat by monitoring for a decrease of the engine coolant temperature below the OBD monitoring threshold during normal operating conditions	engine coolant temperature for fault counter	>=	70.96 400.00	°C	engine pre drive	=	FALSE	-	fail conditions exists for 0.2 s monitor runs with 0.2 s rate whenever enable conditions are met	В
			which is equivalent to fault time	>=	80.00	sec	ambient temperature and engine coolant temperature at least once in driving cycle and	>=	-7.04 70.96	°C		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		·			instantaneous fuel consumption (low-pass filtered) and basic enable conditions met: and NO Pending or Confirmed DTCs:	>= 9.00 l/h = see sheet - enable tables = see sheet - inhibit tables		
Injector 1 Control Circuit	P0201	low side driver circuit	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 2 Control Circuit	P0202	low side driver circuit	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Control Circuit	P0203	Diagnoses the Fuel Injector Cylinder #3 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open -	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 4 Control Circuit	P0204	Diagnoses the Fuel Injector Cylinder #4 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 5 Control Circuit	P0205	Diagnoses the Fuel Injector Cylinder #5 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 6 Control Circuit	P0206	Diagnoses the Fuel Injector Cylinder #6 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 7 Control Circuit	P0207	Diagnoses the Fuel Injector Cylinder #7 Iow side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 8 Control Circuit	P0208	Diagnoses the Fuel Injector Cylinder #8 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable nditions	Time Required	MIL Illum.
Gyotom	Couc	Весоприон	Ontona		Logio ana v	uluo	T di dillocoro	90	Haltions	Required	mami
Turbocharger Overboost	P0234	Detects an permanent negative control deviation of the boost pressure	control deviation of the boost pressure calculated out of difference between desired and actual value	<	a*b*c	kPa				fail conditions exists for 10 s monitor runs with 0.02 s rate whenever enable conditions are met	В
			with				offset learning for turbo charger (VNT) actuator position sensor is active during idling	=	FALSE -		
			(a) control deviation threshold (see Look- Up-Table #62)	=	-40 to - 12.5	kPa	- in order to compensate sensor drift and valve aging, the valve is closed and opened fully once in a driving cycle during engine idling, the read positions for opening and closing are averaged and used for the calculation of offset drift of the valve				
			(b) environmental pressure correction factor (see Look-Up- Table #60)	=	0.65 to 1	factor	and				
			(c) correction factor	II	1.00	factor	turbo charger (VNT) wiping is active - in order to prevent soot accumulation e.g. in a long idle operation under cold engine condition on the turbine the desired value of the boost pressure actuator position governor is assigned from the set-point value	=	FALSE -		
							and injection quantity is stable means	=	TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
					increase of injection	<		(mm		
					quantity			\3/str		
							(oke)/		
								S		
					and					
					engine speed is stable	=	TRUE	-		
					means					
					increase of engine speed	<	25.00	rpm/		
								s		
					and					
					injection Quantity	>=		mm^		
								3/rev		
					injection Quantity	<=		mm^		
							3	3/rev		
					and					
					engine Speed	>=		rpm		
					engine Speed	<=	3000.00	rpm		
					and					
						=	TRUE	-		
					pressure is in closed-loop					
					means					
					(550.00			
					engine speed	>	550.00	rpm		
					and		80.00 ı			
					injection quantity	>		mm^		
					,		•	3/rev		
					NO Pending or Confirmed	=	see sheet	_		
					DTCs:	Γ	inhibit	-		
					D103.		tables			
					\		labics			
					for time	>	1.00	sec		
					and	ĺ	1.00	550		
					basic enable conditions	l ₌	see sheet	_ [
					met:		enable			
							tables			

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	₋ogic and \	/alue	Parameters		Conditions	;	Required	Illum.
Cylinder 1 Balance System	P0263	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity	<	(a) * (b)	-	fuel balance control in closed loop (see closed loop conditions document for details)	П	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			or fuel balance correction quantity with	>	(c) * (b)	-	and current injection quantity current injection quantity	> <	52.00 380.00	mm^ 3/rev mm^		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev		>=	39.96	3/rev °C		
			and with (b) factor for correction quantity	=	0.95	factor	ambient pressure engine speed engine speed	\ \ \	0.00 590.00 3000.00	kPa rpm rpm		
			and with (c) upper limitation (see Look-Up-Table #39)	=	0 to 68	mm^3/rev	vehicle speed and	<=	186.45	mph		
			·				basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 2 Balance System	P0266	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity or	<	(a) * (b)	-	fuel balance control in closed loop (see closed loop conditions document for details)	-	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions	;	Required	Illum.
			fuel balance correction quantity with	^	(c) * (b)	1	current injection quantity current injection quantity	> V	52.00 380.00	mm^ 3/rev mm^ 3/rev		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	°C		
			and with				ambient pressure engine speed	>=	0.00 590.00	kPa rpm		
			(b) factor for correction quantity	=	0.95	factor	engine speed	<	3000.00	rpm		
			and with (c) upper limitation (see Look-Up-Table #39)	=	0 to 68	mm^3/rev	vehicle speed and	<=	186.45	mph		
			#00)				basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
					_	_			_	_		
Cylinder 3 Balance System	P0269	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity	<	(a) * (b)		fuel balance control in closed loop (see closed loop conditions document for details)	=	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			or fuel balance	>	(c) * (b)		and current injection quantity	>	52.00	mm^		
			correction quantity with		(5) (5)		current injection quantity	<	380.00	3/rev mm^		
				_	60 +- 0					3/rev °C		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	C		
			and with				ambient pressure engine speed	>= >	0.00 590.00	kPa rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	_ogic and	Value	Parameters		Conditions		Required	Illum.
			(b) factor for correction quantity and with (c) upper limitation (see Look-Up-Table	=	0.95 0 to 68		engine speed vehicle speed and	< <=	3000.00 186.45	rpm mph		
			#39)				basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 4 Balance System	P0272	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity	<	(a) * (b)	-	fuel balance control in closed loop (see closed loop conditions document for details)	=	TRUE		fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			or fuel balance correction quantity with	>	(c) * (b)	-	and current injection quantity current injection quantity	> <	52.00 380.00	mm^ 3/rev mm^ 3/rev		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	°C		
			and with (b) factor for correction quantity	=	0.95		ambient pressure engine speed engine speed	>= > <	0.00 590.00 3000.00	kPa rpm rpm		
			and with (c) upper limitation (see Look-Up-Table #39)	=	0 to 68	mm^3/rev	vehicle speed and	<=		mph		
							basic enable conditions met: and	=	see sheet enable tables	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Thresho		Secondary Parameters		Enable Conditions	,	Time Required	MIL Illum.
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables			
Cylinder 5 Balance System	P0275	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	or fuel balance correction quantity or fuel balance correction quantity with (a) lower limitation (see Look-Up-Table #38) and with (b) factor for correction quantity and with (c) upper limitation (see Look-Up-Table #39)	< 	(a) * (b) (c) * (b) -68 to 0 0.95 0 to 68	- factor mm^3/rev	fuel balance control in closed loop (see closed loop conditions document for details) and current injection quantity current injection quantity engine coolant temperature ambient pressure engine speed engine speed vehicle speed and basic enable conditions met: and NO Pending or Confirmed DTCs:		52.00 380.00 39.96 0.00 590.00 3000.00 186.45 see sheet enable tables see sheet inhibit tables		fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and	Value	Parameters		Conditions		Required	Illum.
Cylinder 6 Balance System	P0278	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity	V	(a) * (b)	-	fuel balance control in closed loop (see closed loop conditions document for details)	=	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			or fuel balance correction quantity with	>	(c) * (b)	-	and current injection quantity current injection quantity	>	52.00 380.00	mm^ 3/rev mm^		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	3/rev °C		
			and with (b) factor for correction quantity	=	0.95	factor	ambient pressure engine speed engine speed	>= > <	0.00 590.00 3000.00	kPa rpm rpm		
			and with (c) upper limitation (see Look-Up-Table #39)	=	0 to 68	mm^3/rev	vehicle speed and	<=	186.45	mph		
			,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,				basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 7 Balance System	P0281	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity or	<	(a) * (b)	-	fuel balance control in closed loop (see closed loop conditions document for details)	=	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions	;	Required	Illum.
			fuel balance correction quantity with	>	(c) * (b)	-	current injection quantity current injection quantity	> <	52.00 380.00	mm^ 3/rev mm^		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	3/rev °C		
			and with				ambient pressure engine speed	>= >	0.00 590.00	kPa rpm		
			(b) factor for correction quantity	=	0.95		engine speed	<	3000.00	rpm		
			and with (c) upper limitation (see Look-Up-Table #39)	=	0 to 68	mm^3/rev	vehicle speed and	<=	186.45	mph		
			#00)				basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 8 Balance System	P0284	Detects if the injector is leaking by Looking at the amount of fuel compensation (reduction) as determined by Fuel Balance Control (FBC)	fuel balance correction quantity	<	(a) * (b)		fuel balance control in closed loop (see closed loop conditions document for details)	=	TRUE	-	fail conditions exists for 30 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			or fuel balance correction quantity	>	(c) * (b)		and current injection quantity	>	52.00	mm^ 3/rev		
			with				current injection quantity	<	380.00	mm^ 3/rev		
			(a) lower limitation (see Look-Up-Table #38)	=	-68 to 0	mm^3/rev	engine coolant temperature	>=	39.96	°C		
			and with				ambient pressure engine speed	>= >	0.00 590.00	kPa rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and	Value	Parameters		Conditions		Required	Illum.
			(b) factor for correction quantity and with (c) upper limitation (see Look-Up-Table	=======================================	0.95 0 to 68	factor mm^3/rev	engine speed vehicle speed and	< <=	3000.00 186.45	rpm mph		
			#39)				basic enable conditions met:	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
				_	-	_		_	_			
CAC Efficiency Below Threshold	P026A	Detects insufficient charge-air cooler efficiency. The efficiency is calculated out of temperature upstream of the cooler, temperature downstream of the cooler and ambient temperature	filtered charge-air cooler efficiency	<	0.25	-	vehicle speed	>=	37.29	mph	fail conditions exists for 60 s monitor runs once per driving cycle with 100 ms rate whenever enable conditions are met	В
							and air mass flow air mass flow and engine temperature	>= <=	83.33 152.77 69.96	g/s g/s °C		
							engine temperature engine temperature and	>= <=	122.96	°C		
							(maximum value of (a) and (b)) the maximum value is then divided by (b) with (a) boost pressure	>=	-4.00	-		
							downstream compressor		parameter			

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(b) ambient pressure	= measured - parameter		
					and control value of the throttle valve and	<= 5.00 %		
					(a) - (b) with	>= 40.00 °C		
					(a) temperature after compressor	= measured - parameter		
					and with (b) ambient air temperature	= measured - parameter		
					and injection quantity	>= 80.00 mm^ 3/rev		
					injection quantity	<= 200.00 mm^ 3/rev		
					and ambient pressure and	> 74.80 kPa		
					ambient temperature and	> -7.04 °C		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Injection Quantity Too Low	P026C	Monitors the fuel mass	Unlimited fuel mass observer correction quantity - emission control correction quantity (see Look-Up-Table #45)	<= -34.8 to - mm^3/rev 20	((Status of the Observer function's lambda-signal means	= TRUE -	fail conditions exists for 12 s monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(lambda signal from NOx sensor ready (see parameter definition)	= TRUE -		
					fuel system is in fuel cut off (see parameter definition)	= FALSE -		
					Particulate Filter Regeneration Mode ((= FALSE -		
					component of combusted fuel in the engine or	>= 1 -		
					calculated EGR rate	>= 0 -		
					for time)) AND	> 1.00 sec		
					Controller status of the observer means	= TRUE -		
					Load dependent release state (see look up table #) (see Look-Up-Table #48)	= 0 to 1 -		
					AND Component Protection release state (see look up table #) (see Look-Up-Table #43)	> 0 to 1 -		
					engine coolant temperature engine coolant temperature Normal Injection Mode	<= 199.96 °C >= 64.96 °C = TRUE -		
					Barometric pressure Ambient temperature Vehicle speed	>= 74.80 kPa >= -7.04 °C < 1.86 mph		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					AND (
			l l		Engine speed	<= 1040 rpm	1	

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					AND Engine speed) AND	>= 476 rpm		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					for time	> 72.00 sec		
					basic enable conditions met:	= see sheet - enable tables		
lais ation Occartity	Dooch	Magitage the first see		40 to 04 0 gara40/gar	((Obstace of the Observer	TDUE	foil conditions	D.
Injection Quantity Too High	P026D		observer correction quantity - emission control correction	>= 16 to 34.8 mm^3/rev	((Status of the Observer function's lambda-signal means	= TRUE -	fail conditions exists for 12 s monitor runs with 0.02 s rate whenever enable conditions are met	В
					lambda signal from NOx sensor ready (see parameter definition)	= TRUE -		
					fuel system is in fuel cut off (see parameter	= FALSE -		
					definition) Particulate Filter Regeneration Mode	= FALSE -		
					((component of combusted fuel in the engine or	>= 1 -		
					calculated EGR rate	>= 0 -		
					for time	> 1.00 sec		
					AND Controller status of the observer	= TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					means (Load dependent release state (see look up table #) (see Look-Up-Table #48) AND Component Protection release state (see look up table #) (see Look-Up-Table #43)	= 0 to 1 -		
) engine coolant temperature engine coolant temperature Normal Injection Mode Barometric pressure Ambient temperature Vehicle speed NO Pending or Confirmed DTCs: AND	<= 199.96 °C >= 64.96 °C = TRUE - >= 74.80 kPa >= -7.04 °C < 1.86 mph = see sheet - inhibit tables		
					(Engine speed AND Engine speed) AND NO Pending or Confirmed DTCs:) for time basic enable conditions met:	<= 1040 rpm >= 476 rpm = see sheet - inhibit tables > 72.00 sec = see sheet - enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	s	Required	Illum.
Turbocharger Underboost	P0299	Detects an permanent		>	15 to 40	kPa	(fail conditions exists for 10 s monitor runs with 0.02 s rate whenever enable conditions are	В
			, and the second				offset learning for turbo charger (VNT) actuator position sensor is active during idling - in order to compensate sensor drift and valve aging, the valve is closed and opened fully once in a driving cycle during engine idling, the read positions for opening and closing are averaged and used for the calculation of offset drift of the valve	=	FALSE		met	
							and turbo charger (VNT) wiping is active - in order to prevent soot accumulation e.g. in a long idle operation under cold engine condition on the turbine the desired value of the boost pressure actuator position governor is assigned from the set-point value	П	FALSE	-		
							and injection quantity is stable means	=	TRUE	-		
							increase of injection quantity	<	24.00	(mm ^3/re v)/se c		
							and engine speed is stable means	=	TRUE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					increase of engine speed and injection Quantity injection Quantity and engine Speed engine Speed and working range of boost pressure is in closed-loop means (engine speed and injection quantity) NO Pending or Confirmed DTCs:) for time and basic enable conditions met:	<pre>< 25.00 rpm/ sec >= 112.00 mm^</pre>		
Cylinder 1 Injection Timing Reached Feedback Limit	P02CD	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	> -7.04 °C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	5	Required	Illum.
		Detects a fault when the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time (see Look-Up-Table #20) and with	=	353.2 to 670.8	us	(fuel temperature and fuel temperature	>=	0.06 79.96	°C		
			(b) offset of the maximum filtered energizing time (see Look-Up-Table #21))	II	10 to 16	us) and					
			OR (engine temperature and	>	49.96	°C		
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	battery voltage	>	10.00	V		
			with (a) minimum injection energizing time and with	=	107.2	us	and combustion chamber is not cooled off means					
			(b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	10 to 16	us	time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
)) for				and intake manifold pressure and	>	75.00	kPa		
			rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							for					

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					time and (> 0.00 sec		
					engine speed and	> (b) - (a) -		
					engine speed with	< (a) + (c) -		
					(a) value of engine speed and with	= 30.00 rpm		
					(b) gear specific minimum engine speed and with	= 950 rpm		
					(c) gear specific maximum engine speed	= 1850 rpm		
					and current gear (see Look-Up- Table #93)	= 0 to 1 -		
					and vehicle speed	> 0 mph		
					and rail pressure deviation from	< 5000.00 kPa		
					setpoint calculated out of difference between desired and actual value and			
					rail pressure is stable for at least and	> 0.10 sec		
					no gear change has occurred and	= TRUE -		
					4 wheel mode and	= FALSE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Va		Parameters		Conditions		Required	Illum.
Cylinder 2 Injection Timing Reached Feedback Limit	P02CF	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		Detects a fault when the corrected energizing time exceeds the feedback control limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			with (a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	fuel temperature and	>=	0.06	°C		
			and with (b) offset of the maximum filtered energizing time (see Look-Up-Table #21)	=	10 to 16	us	fuel temperature) and	<=	79.96	°C		
) OR (engine temperature and	>	49.96	°C		
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	battery voltage	>	10.00	V		
			with (a) minimum injection energizing time and with	=	107.2	us	and combustion chamber is not cooled off means					
			(b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	10 to 16	us	time since last combustion (see Look-Up- Table #94) and	>=	5 to 30	sec		
)				intake manifold pressure	>	75.00	kPa		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions		Required	Illum.
			for rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	and intake manifold pressure	<	150.00	kPa		
			#10)				and accelerator pedal position and	<	0.05	%		
							Fuel system status for	=	Fuel cut off	-		
							time and	>	0.00	sec		
							(engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed and	>	0	mph		
							rail pressure deviation from setpoint calculated out of difference between desired and actual value	<	5000.00	kPa		
							and rail pressure is stable for at least and	>	0.10	sec		
							no gear change has occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
							basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables			
Cylinder 7 Injection Timing Reached Feedback Limit	P02D9	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point. Detects a fault when the corrected energizing time exceeds the feedback control limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	^	(a) - (b)	-	environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			(with (a) maximum injection energizing time (see Look-Up-Table #20) and with (b) offset of the maximum filtered energizing time (see Look-Up-Table #21))	=	353.2 to 670.8 10 to 16	us us	(fuel temperature and fuel temperature)	>= <=	0.06 79.96	°C		
			OR (corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	engine temperature and battery voltage	>	49.96 10.00	°C V		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshole	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions	;	Required	Illum.
			(with (a) minimum injection energizing time and with (b) offset of the minimum filtered energizing time (see	11 11	107.2 10 to 16	us	and combustion chamber is not cooled off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
			Look-Up-Table #22))) for rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	and intake manifold pressure and intake manifold pressure	> <	75.00 150.00	kPa kPa		
			,				and accelerator pedal position and Fuel system status	<	0.05 Fuel cut off	% -		
							for time and (>	0.00	sec		
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with (b) gear specific minimum engine speed	=	30.00 950	rpm		
							and with (c) gear specific maximum engine speed	=	1850	rpm		
) and current gear (see Look-Up- Table #93)	=	0 to 1	-		
							and vehicle speed and	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	₋ogic and Va	lue	Parameters		Conditions		Required	Illum.
							rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at least	< >	0.10	kPa sec		
							and no gear change has occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
						_						
Cylinder 8 Injection Timing Reached Feedback Limit	P02DB	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		Detects a fault when the corrected energizing time exceeds the feedback control limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	(fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters	C	Conditions	;	Required	Illum.
			(b) offset of the maximum filtered energizing time (see Look-Up-Table #21)) OR	II	10 to 16	us) and engine temperature	>	49.96	ô		
			(corrected energizing time for the rail	<	(a) + (b)	-	and battery voltage	>	10.00	V		
			pressure calibration points and cylinder 1 (with				and					
			(a) minimum injection energizing time and with	=	107.2	us	combustion chamber is not cooled off means					
			(b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	10 to 16	us	time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
)) for				and intake manifold pressure and	>	75.00	kPa		
			rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							time and (>	0.00	sec		
							engine speed and	>	(b) - (a)	-		
							engine speed with (a) value of engine speed	< =	(a) + (c) 30.00	- rpm		
							and with (b) gear specific minimum engine speed	=	950	rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and with (c) gear specific maximum engine speed	= 1850 rpm		
					and current gear (see Look-Up- Table #93) and	= 0 to 1 -		
					vehicle speed and	> 0 mph		
					rail pressure deviation from setpoint calculated out of difference between desired and actual value and	< 5000.00 kPa		
					rail pressure is stable for at least and	> 0.10 sec		
					no gear change has occurred and	= TRUE -		
					4 wheel mode and	= FALSE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Cylinder 4 Injection Timing Reached Feedback Limit	P02D3	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	> -7.04 °C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	;	Required	Illum.
		Detects a fault when the corrected energizing time	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	(fuel temperature and	>=	0.06	°C		
			and with (b) offset of the maximum filtered energizing time (see Look-Up-Table #21))	=	10 to 16	us	fuel temperature) and	<=	79.96	°C		
) OR (engine temperature and	>	49.96	°C		
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	battery voltage	^	10.00	V		
			with (a) minimum injection energizing time and with	=	107.2	us	and combustion chamber is not cooled off means					
			(b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	10 to 16	us	time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
)) for				and intake manifold pressure and	>	75.00	kPa		
			rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	intake manifold pressure	<	150.00	kPa		
							and accelerator pedal position and	<	0.05	%		
							Fuel system status for	=	Fuel cut off	-		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					time and '	> 0.00 sec		
					(engine speed and	> (b) - (a) -		
					engine speed with	< (a) + (c) -		
					(a) value of engine speed and with	= 30.00 rpm		
					(b) gear specific minimum engine speed and with	= 950 rpm		
					(c) gear specific maximum engine speed	= 1850 rpm		
					and current gear (see Look-Up- Table #93)	= 0 to 1 -		
					and vehicle speed and	> 0 mph		
					rail pressure deviation from setpoint calculated out of difference between desired and actual value	< 5000.00 kPa		
					and rail pressure is stable for at least and	> 0.10 sec		
					no gear change has occurred and	= TRUE -		
					4 wheel mode and	= FALSE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	l	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	ı	_ogic and Va		Parameters	(Conditions		Required	Illum.
Cylinder 5 Injection Timing Reached Feedback Limit	P02D5	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with				(fuel temperature	>=	0.06	°C		
			(a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	and	•	0.00	Ü		
			and with (b) offset of the maximum filtered energizing time (see Look-Up-Table #21)	=	10 to 16	us	fuel temperature)	<=	79.96	°C		
)				and					
			OR (engine temperature and	>	49.96	°C		
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	battery voltage	>	10.00	V		
			with (a) minimum injection energizing time and with	=	107.2	us	and combustion chamber is not cooled off means					
			(b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	10 to 16	us	time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
) ' '				and					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
) for		20000 4-	I-D-	intake manifold pressure and	>	75.00	kPa		
			rail pressure point (see Look-Up-Table #19)	=	30000 to 90000	kPa	intake manifold pressure and	<	150.00	kPa		
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							for time and (>	0.00	sec		
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed) and	=	1850	rpm		
							current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed and	>	0	mph		
							rail pressure deviation from setpoint calculated out of difference between desired and actual value and	<	5000.00	kPa		
							rail pressure is stable for at least and	>	0.10	sec		
							no gear change has occurred and	=	TRUE	-		
							4 wheel mode	=	FALSE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	I	∟ogic and Va	lue	Parameters		Conditions		Required	Illum.
							and basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables	-		
Cylinder 6 Injection Timing Reached Feedback Limit	P02D7	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point. Detects a fault when the corrected energizing time exceeds the feedback control limit.	corrected energizing time for the rail pressure calibration points and cylinder 1	^	(a) - (b)	-	environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			(with (a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	(fuel temperature and	>=	0.06	°C		
			and with (b) offset of the maximum filtered energizing time (see Look-Up-Table #21))) OR (corrected energizing time for the rail pressure calibration	= <	10 to 16 (a) + (b)	us	fuel temperature) and engine temperature and battery voltage	\=	79.96 49.96 10.00	°C °C V		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions	3	Required	Illum.
			(with (a) minimum injection energizing time and with (b) offset of the minimum filtered energizing time (see	=	107.2 10 to 16	us us	and combustion chamber is not cooled off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
			Look-Up-Table #22))) for rail pressure point	=	30000 to	kPa	and intake manifold pressure and intake manifold pressure	>	75.00 150.00	kPa kPa		
			(see Look-Up-Table #19)		90000	N G	and					
							accelerator pedal position and	<	0.05	%		
							Fuel system status	=	Fuel cut off	-		
							time and (>	0.00	sec		
							engine speed and	>	(b) - (a)	-		
							engine speed with	<	(a) + (c)	-		
							(a) value of engine speed and with	=	30.00	rpm		
							(b) gear specific minimum engine speed and with	=	950	rpm		
							(c) gear specific maximum engine speed)	=	1850	rpm		
							and current gear (see Look-Up- Table #93) and	=	0 to 1	-		
							vehicle speed and	>	0	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Valu	ıe	Parameters		Conditions		Required	Illum.
							rail pressure deviation from setpoint calculated out of difference between desired and actual value and rail pressure is stable for at least and	^	0.10	kPa sec		
							no gear change has occurred and	=	TRUE	-		
							4 wheel mode and	=	FALSE	-		
							basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cylinder 3 Injection Timing Reached Feedback Limit	P02D1	Monitors the correction values for the energizing time of each cylinder. A correction value for the energizing time is learned for each cylinder at three different rail pressure operating point.	(environmental temperature	>	-7.04	°C	fail conditions exists for more than 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В
		the corrected	corrected energizing time for the rail pressure calibration points and cylinder 1	>	(a) - (b)	-	and					
			(with (a) maximum injection energizing time (see Look-Up-Table #20)	=	353.2 to 670.8	us	(fuel temperature and	>=	0.06	°C		
			and with				fuel temperature	<=	79.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters	(Conditions		Required	Illum.
		·	(b) offset of the maximum filtered energizing time (see Look-Up-Table #21)) OR	=	10 to 16	us	and engine temperature and	>	49.96	°C		
			corrected energizing time for the rail pressure calibration points and cylinder 1	<	(a) + (b)	-	battery voltage	>	10.00	V		
			with (a) minimum injection energizing time and with (b) offset of the minimum filtered energizing time (see Look-Up-Table #22)	=	107.2 10 to 16	us	and combustion chamber is not cooled off means time since last combustion (see Look-Up- Table #94)	>=	5 to 30	sec		
)) for rail pressure point (see Look-Up-Table	=	30000 to 90000	kPa	and intake manifold pressure and intake manifold pressure	> <	75.00 150.00	kPa kPa		
			#19)				and accelerator pedal position and Fuel system status	< =	0.05 Fuel cut off	%		
							for time and (>	0.00	sec		
							engine speed and	>	(b) - (a)	-		
							engine speed with (a) value of engine speed	< =	(a) + (c) 30.00	- rpm		
							and with (b) gear specific minimum engine speed	=	950	rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and with (c) gear specific maximum engine speed	= 1850 rpm		
					and current gear (see Look-Up- Table #93) and	= 0 to 1 -		
					vehicle speed and	> 0 mph		
					rail pressure deviation from setpoint calculated out of difference between desired and actual value and	< 5000.00 kPa		
					rail pressure is stable for at least and	> 0.10 sec		
					no gear change has occurred and	= TRUE -		
					4 wheel mode and	= FALSE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Intake Air Flow Valve Control Circuit	P02E0	Diagnoses the Throttle Valve low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	battery voltage	> 11.00 V	fail conditions exists for 7s monitor runs with 0.005 s rate whenever enable conditions are met	В
					for time and	> 3.00 sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and	= FALSE - > 3.00 sec = ACTIVE -		
					basic enable conditions met	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		for time and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec = ACTIVE -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	
					and basic enable conditions met and	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					Open Load Diagnosis active	= FALSE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		battery voltage for time	>	11.00 3.00	V	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	
					and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and	= > =	FALSE 3.00 ACTIVE	sec		
					basic enable conditions met	=	see sheet enable tables	-		
					NO Pending or Confirmed DTCs: and	=	see sheet inhibit tables	-		
					Open Load Diagnosis active	=	FALSE			
Intake Air Flow Valve Control Circuit 1 Low Voltage	P02E2	Diagnoses the Throttle Valve low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	battery voltage	>	11.00	V	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					for time and starter is active cranking for	> =	3.00 FALSE	sec -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	time Throttle Valve Actuator Solenoid Control Circuit and basic enable conditions met and NO Pending or Confirmed DTCs: and Open Load Diagnosis active	> 3.00 sec = ACTIVE - = see sheet - enable tables = see sheet - inhibit tables = FALSE -	Required	Illum.
Intake Air Flow Valve Control Circuit 1 High Voltage	P02E3	circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and basic enable conditions met	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec = ACTIVE - = see sheet - enable tables	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	l	Threshold Logic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
							and Open Load Diagnosis active	=	FALSE	-		
Throttle Valve Actuator (TVA) Position Sensor Performance		Detects in range TVA position errors by comparing the difference between desired and actual TVA position.	throttle valve control deviation calculated out of difference between desired and actual value or throttle valve control deviation calculated out of difference between desired and actual value	< ^	-10.00	%	throttle valve controller bypass is active and throttle valve is driven to a mechanical stop and Throttle Governor Active and Throttle Valve Permanent Control Deviation and Engine Running (see parameter definition) and basic enable conditions met and NO Pending or Confirmed DTCs:	= = = =	FALSE TRUE FALSE TRUE See sheet enable tables see sheet inhibit tables		fail conditions exists for 10 s monitor runs with 0.005 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		ogic and Va		Parameters		Conditions	Required	Illum.
Diesel Intake Air Flow Position Sensor Circuit Low Voltage	P02E8	Detects low voltage readings on the throttle valve position sensor circuit, indicating an OOR low condition on the throttle valve position sensor circuit	measured throttle valve position voltage	V	0.40	V	and basic enable conditions met and NO Pending or Confirmed DTCs:	= =	see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 5 s test performed continuously 0.005 s rate	A
Diesel Intake Air Flow Position Sensor Circuit High Voltage	P02E9	Detects high voltage readings on the throttle valve position sensor circuit, indicating an OOR high condition on the throttle valve position sensor circuit	measured throttle valve position voltage	>	4.72	V	ignition on and basic enable conditions met and NO Pending or Confirmed DTCs:	=	TRUE - see sheet enable tables see sheet inhibit tables	fail conditions exists for 5 s test performed continuously 0.005 s rate	A
Intake Air Flow Valve Control Motor Current Performance		Electronic out-put driver circuitry determines circuit integrity on the intake air flow valve.	driver output current	>	7.7	A	battery voltage for	>	11.00 V	fail conditions exists for 2 s monitor runs with 0.005 s rate whenever enable	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and V	/alue	Parameters		Conditions		Required	Illum.
							time and starter is active cranking	> =	3.00 FALSE	sec -	conditions are met	
							for time Throttle Valve Actuator Solenoid Control Circuit and	> =	3.00 ACTIVE	sec -		
							basic enable conditions met	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
							Open Load Diagnosis active	=	FALSE	-		
Engine Misfire Detected	P0300	Indicates engine has experienced more than one cylinder misfiring	angular acceleration of the crankshaft and evaluated crankshaft revolutions with (a) number of crankshaft revolutions per block and with (b) number of test	< >= = =	-1.40 (a) * (b) 20.00	sec^(2) - counts	Engine Running (see parameter definition) and engine speed and engine speed	- >	TRUE 476.00 1560.00	- rpm	fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В
			blocks and misfires exist on more than one cylinder	=	TRUE	-	and (a) - (b) with (a) actual desired idle speed	< =	200.00 calculated parameter	rpm -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and with (b) engine speed	= measured - parameter		
					and (current injection quantity and current injection quantity	> 12.00 mm^ 3/rev < 400.00 mm^		
) and	3/rev		
					engine coolant temperature and vehicle speed	>= 39.96 °C <= 1.86 mph		
					and time since start and and	>= 10.00 sec		
					deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and	= TRUE -		
					adaptation value for tooth wheel has been learned and	= TRUE -		
					number of detected misfires and	> 140.00 coun ts		
					basic enable conditions met:	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
				_				

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	ı	_ogic and V		Parameters	Conditions	;	Required	Illum.
Cylinder 1 Misfire Detected	P0301	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	v	-1.40	sec^(2)	(fail conditions exists for 0.02 s monitor runs with 0.02 s rate whenever enable conditions are met	В
		event.	and evaluated crankshaft	>=	(a) * (b)	-	Engine Running (see parameter definition) and	= TRUE	-		
			revolutions with (a) number of crankshaft revolutions per	=	20.00	counts	engine speed and	> 476.00	rpm		
			block and with (b) number of test blocks	=	20.00	counts	engine speed) and	< 1560.00	rpm		
							(a) - (b) with	< 200.00	rpm		
							(a) actual desired idle speed	= calculated parameter			
							and with (b) engine speed	= measured parameter			
							and (
							current injection quantity	> 12.00	mm^ 3/rev		
							current injection quantity	< 400.00	mm^ 3/rev		
							and engine coolant temperature	>= 39.96	°C		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.		-	and vehicle speed and	<= 1.86 mph	,	
					time since start and and deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions	>= 10.00 sec = TRUE -		
					and adaptation value for tooth wheel has been learned and number of detected misfires and	= TRUE - > 140.00 coun ts		
					basic enable conditions met: and	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	_ogic and \		Parameters		Conditions		Required	Illum.
Cylinder 2 Misfire Detected	P0302	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	<	-1.40	sec^(2)	(fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В
		event.	and evaluated crankshaft	>=	(a) * (b)		Engine Running (see parameter definition) and	=	TRUE	-		
			revolutions with (a) number of crankshaft revolutions per block	=	20.00		engine speed and	>	476.00	rpm		
			and with (b) number of test blocks	=	20.00	counts	engine speed) and	<	1560.00	rpm		
							(a) - (b) with	<	200.00	rpm		
							(a) actual desired idle speed	=	calculated parameter	-		
							and with (b) engine speed	=	measured parameter	-		
							and (
							current injection quantity	>	12.00	mm^ 3/rev		
							current injection quantity	<	400.00	mm^ 3/rev		
) and engine coolant temperature	>=	39.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.			and vehicle speed and	<= 1.86 mph		
					time since start and and	>= 10.00 sec		
					deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and	= TRUE -		
					adaptation value for tooth wheel has been learned and	= TRUE -		
					number of detected misfires and	> 140.00 coun ts		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Cylinder 7 Misfire Detected	P0307	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	< -1.40 sec^(2			fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	1	Logic and V		Parameters		Conditions	;	Required	Illum.
			and evaluated crankshaft revolutions with	>=	(a) * (b)	-	Engine Running (see parameter definition) and engine speed	= >	TRUE 476.00	- rpm		
			(a) number of crankshaft revolutions per block and with (b) number of test blocks	=	20.00	counts	engine speed	<	1560.00	rpm		
							and (a) - (b) with	<	200.00	rpm		
							(a) actual desired idle speed	=	calculated parameter			
							and with (b) engine speed	=	measured parameter			
							and (current injection quantity	>	12.00	mm^		
							and current injection quantity	<	400.00	3/rev mm^		
) and			3/rev		
							engine coolant temperature and	>=	39.96	°C		
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.					vehicle speed and	<=	1.86	mph		
							time since start and and	>=	10.00	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and V	alue	Parameters		Conditions		Required	Illum.
							deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and adaptation value for tooth wheel has been learned and	=	TRUE	-		
							number of detected misfires and basic enable conditions	>	140.00 see sheet	coun ts		
							met:		enable tables			
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
										_		
Cylinder 8 Misfire Detected	P0308	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	<	-1.40	sec^(2)	(fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В
			and evaluated crankshaft	>=	(a) * (b)	_	Engine Running (see parameter definition) and	=	TRUE	-		
			revolutions with (a) number of crankshaft revolutions per	=	20.00	counts	engine speed and	>	476.00	rpm		
			block and with				engine speed	<	1560.00	rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			(b) number of test blocks	= 20.00 counts) and (a) - (b) with (a) actual desired idle speed and with	< 200.00 rpi = calculated - parameter	m	
					(b) engine speed and	= measured - parameter		
					current injection quantity	> 12.00 mn 3/r	ev	
					current injection quantity) and	< 400.00 mn 3/r		
					engine coolant temperature and	>= 39.96 °C		
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.			vehicle speed and	<= 1.86 mp	oh 	
					time since start and and deletion of error memory	>= 10.00 se = TRUE -		
					(Mode\$4) not executed since last check of the monitoring conditions and	- INOL -		
					adaptation value for tooth wheel has been learned and	= TRUE -		
					number of detected misfires and	> 140.00 cou ts		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	gic and V	/alue	Parameters		Conditions		Required	Illum.
							basic enable conditions met: and NO Pending or Confirmed DTCs:	-	see sheet enable tables see sheet inhibit tables			
Cylinder 4 Misfire Detected	P0304	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft evaluated crankshaft revolutions with (a) number of crankshaft revolutions per block and with (b) number of test blocks	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	-1.40 (a) * (b) 20.00	counts	Engine Running (see parameter definition) and engine speed and engine speed) and (a) - (b) with (a) actual desired idle speed and with (b) engine speed	= > < < = =	TRUE 476.00 1560.00 200.00 calculated parameter measured parameter	_	fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and (current injection quantity and	> 12.00 mm^ 3/rev		
					current injection quantity)	< 400.00 mm^ 3/rev		
					and engine coolant temperature and	>= 39.96 °C		
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.			vehicle speed and	<= 1.86 mph		
					time since start and and	>= 10.00 sec		
					deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and	= TRUE -		
					adaptation value for tooth wheel has been learned and	= TRUE -		
					number of detected misfires and	> 140.00 coun ts		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	ı	Logic and \		Parameters	Conditions		Required	Illum.
Cylinder 5 Misfire Detected	P0305	Detects cylinder	angular acceleration of the crankshaft	<	-1.40	sec^(2)	(fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В
			and evaluated crankshaft	>=	(a) * (b)	_	Engine Running (see parameter definition) and	= TRUE	-		
			revolutions with (a) number of crankshaft revolutions per	=	20.00	counts	engine speed and	> 476.00	rpm		
			block and with (b) number of test blocks	=	20.00	counts	engine speed)	< 1560.00	rpm		
							and (a) - (b) with (a) actual desired idle	< 200.00 = calculated	rpm -		
							speed and with (b) engine speed	parameter = measured parameter	-		
							and (current injection quantity and current injection quantity)	< 400.00	mm^ 3/rev mm^ 3/rev		
							and engine coolant temperature	>= 39.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Valu		Parameters		Conditions	;	Required	Illum.
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.				and vehicle speed and	<=	1.86	mph		
						time since start and and deletion of error memory (Mode\$4) not executed	>=	10.00	sec -		
						since last check of the monitoring conditions and adaptation value for tooth wheel has been learned and	=	TRUE	-		
						number of detected misfires and basic enable conditions met:	>	140.00 see sheet enable	coun ts		
						and NO Pending or Confirmed DTCs:	=	tables see sheet inhibit tables	-		
Cylinder 6 Misfire Detected	P0306	Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	< -1.40 se	ec^(2)	(fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	1	Logic and V		Parameters		Conditions	5	Required	Illum.
			and evaluated crankshaft revolutions with	>=	(a) * (b)	-	Engine Running (see parameter definition) and engine speed	= >	TRUE 476.00	- rpm		
			(a) number of crankshaft revolutions per block and with (b) number of test blocks	=	20.00	counts	and engine speed)	<	1560.00	rpm		
							and (a) - (b) with	<	200.00	rpm		
							(a) actual desired idle speed	=	calculated parameter			
							and with (b) engine speed	=	measured parameter			
							and (10.00	ΔΔ		
							current injection quantity and	>	12.00	mm^ 3/rev		
							current injection quantity	<	400.00	mm^ 3/rev		
) and engine coolant temperature and	>=	39.96	°C		
		Calculates angle acceleration after an injection event for the					vehicle speed and	<=	1.86	mph		
		cylinder under test and compares it to the minimum threshold.					time since start	>=	10.00	sec		
							and and		10.00	366		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and V	alue	Parameters		Conditions		Required	Illum.
							deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and adaptation value for tooth wheel has been learned		TRUE	-		
							and number of detected misfires and basic enable conditions met: and NO Pending or Confirmed DTCs:	> =	see sheet enable tables see sheet inhibit tables	coun ts -		
Cylinder 3 Misfire Detected		Detects cylinder misfire. The minimum average angle acceleration is calculated every 2 rotations and represents the average angle acceleration that all cylinders are rotating at after a combustion event.	angular acceleration of the crankshaft	<	-1.40	sec^(2)	(fail conditions exists for 0.02 ms monitor runs with 0.02 s rate whenever enable conditions are met	В
			and evaluated crankshaft	>=	(a) * (b)	_	Engine Running (see parameter definition) and	=	TRUE	-		
			revolutions with (a) number of crankshaft revolutions per block	=	20.00	counts	engine speed and	>	476.00	rpm		
			and with				engine speed	<	1560.00	rpm		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			(b) number of test blocks	= 20.00 counts) and (a) - (b) with (a) actual desired idle speed	< 200.00 rpm = calculated - parameter		
					and with (b) engine speed	= measured - parameter		
					and (
					current injection quantity and	> 12.00 mm [,] 3/re [,]		
					current injection quantity)	< 400.00 mm ² 3/re ³		
					and engine coolant temperature and	>= 39.96 °C		
		Calculates angle acceleration after an injection event for the cylinder under test and compares it to the minimum threshold.			vehicle speed and	<= 1.86 mph		
					time since start and and	>= 10.00 sec		
					deletion of error memory (Mode\$4) not executed since last check of the monitoring conditions and	= TRUE -		
					adaptation value for tooth wheel has been learned and	= TRUE -		
					number of detected misfires and	> 140.00 cour ts		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold ogic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
System	Odde	Description	Ontena		ogic and ve	and C	basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables	-	Required	mum.
Crankshaft Position System Variation Not Learned	P0315	Wheel Learn - Fuel Balance System - Tooth Wheel Variation and Crankshaft Dynamics not learned quickly enough	fuel balance wheel learn complete	=	FALSE	-	fuel system is in fuel cut off and engine speed engine speed No Pending or Confirmed DTCs	> <=		rpm rpm -	fail conditions exists for 5000 s cumulative time, monitor runs with 1 s rate whenever enable conditions are met	В
Crankshaft Position [CKP] Sensor Circuit	P0335	Detects crankshaft sensor circuit failure by monitoring for valid signals from CKP sensor while CMP sensor is also sending valid signals	ECM has detected reference mark on the crankshaft and number of detected camshaft rotations	>=	FALSE	counts	set condition ((engine speed and synchronization completed) starter is active cranking	>= = =	400.00 TRUE TRUE	rpm - -	fail conditions exists for more than 6 events monitor runs with 0.1 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable Conditions		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters) and (vehicle speed or vehicle speed and engine speed) and not reset condition (engine speed and starter is active cranking) and basic enable conditions met:	=	0 16 200.00 FALSE see sheet enable tables	mph rpm rpm	Required	Illum.
Crankshaft Position Sensor Performance	P0336	crankshaft sensor operation by detecting incorrect crank sensor signal patterns.	number of disturbances in crankshaft signal crankshaft signal disturbance detected under the following conditions: Current tooth time period or Crankshaft tooth counts between detected gaps or	>= >	10.00 ##################################	us	Engine Running (see parameter definition) and basic enable conditions met:	=	TRUE see sheet enable tables	-	fail conditions exists for 0.1 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria If gap not expected,	Logic and Value > 1.5 to 2 -	Parameters	Conditions	Required	Illum.
			ratio of current tooth time to previous tooth time (see Look-Up-Table #18) or If gap expected, ratio of current tooth time to previous tooth time to previous tooth time (see Look-Up-Table #17)	> 1.5 to 2 -				
Camshaft Position [CMP] Sensor Circuit	P0340	Detects camshaft sensor circuit failure by monitoring for valid signals from CMP sensor while CKP sensor is also sending valid signals	number of crankshaft revolutions during missed camshaft signal	>= 4.00 counts	ECM has detected reference mark on the crankshaft and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 0.01 s test performed continuously 0.01 s rate	A
Camshaft Position [CMP] Sensor Performance	P0341	Detects implausible camshaft sensor operation by detecting incorrect cam sensor patterns	number of camshaft edges	> 4 counts	ECM has detected reference mark on the crankshaft and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for more than 6 events test performed continuously 0.01 s rate	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Wait to Start (WTS) Lamp Control Circuit	P0381	Diagnoses the Glow Lamp Circuit high side driver circuit for circuit faults.	Voltage low during driver on state (indicates short-to-ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	and battery voltage for time and basic enable conditions met:	= TRUE - > 11.00 V > 3.00 sec = see sheet - enable tables	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			Voltage high during driver off state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	lamp is commanded off	= TRUE -	fail conditions exists for 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					for time and basic enable conditions met:	> 11.00 V > 3.00 sec = see sheet - enable tables		
			Voltage high during driver off state (open circuit)	= Open - Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground	circuit active at low current	= TRUE -	fail conditions exists for 0.1 s monitor runs with 0.01 s rate whenever enable conditions are met	
					and battery voltage for time and basic enable conditions met:	> 11.00 V > 3.00 sec = see sheet - enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	;	Required	Illum.
Exhaust Gas Recirculation(EGR) Flow Excessive	P0400	Detects excessive EGR flow. Actual MAF readings are compared to desired MAF values as an indication of how much EGR is flowing.	controller deviation of the air mass = actual minus desired value (see Look-Up-Table #11)	^	1.6 to 2	g/rev	EGR controller is active and VGT offset learning is active	1	TRUE	,	fail conditions exists for 15 s monitor runs 0.02 s rate whenever enable conditions are met	A
							and NO Pending or Confirmed DTCs: and	=	see sheet inhibit tables	-		
							basic enable conditions met:	H	see sheet enable tables	-		
Exhaust Gas Recirculation(EGR) Flow Insufficient	P0401	Detects insufficient EGR flow. Actual MAF readings are compared to desired MAF values as an indication of how much EGR is flowing.	recirculation (EGR) - calculated out of desired and actual value	>	(a)*(b)	-	(CD controller is setting	_	TDUE		fail conditions exists for 10 s monitor runs 0.02 s rate whenever enable conditions are met	В
			with (a) Minimum Controller Deviation (see Look-Up-Table #12)	=	-1.2 to - 0.56	g/rev	EGR controller is active and	H	TRUE		met	
			(b) Environmental Pressure correction factor (see Look-Up- Table #8)	=	0.71 to 1	factor	change of injection quantity between actual and last received value	<	40.00	(mm ^3/re v)/se c		
							for time and change of engine speed	= <	0.25 50.00	sec rpm/		
							between actual and last received value			sec		
							for time and	=	0.50	sec		

Component /	Fault Code	Monitor Strategy	Primary Malfunction Criteria	Threshold		Secondary Parameters		Enable Conditions		Time	MIL Illum.
System	Code	Description	Criteria	Logic and Va	liue	VGT offset learning is active	=	FALSE		Required	mum.
						maximum setpoint for air- mass flow (see Look-Up- Table #9) and	>	0.8 to 1.2	g/rev		
						Engine speed Engine speed and Torque generating engine fuel injection quantity Torque generating engine fuel injection quantity and setpoint valve position of	<= >= <= >= >	950.00 500.00 72.00 4.00	rpm rpm 3/rev mm^ 3/rev %		
						exhaust-gas recirculation and throttle position	<	5.00	%		
						and basic enable conditions met: and	=	see sheet enable tables	-		
						NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
						for time	>=	5.00	sec		
Exhaust Gas Recirculation(EGR) Flow Excessive		EGR flow. Actual MAF readings are compared to desired MAF values as an indication of how much EGR is flowing.	controller deviation of the exhaust gas recirculation (EGR) - calculated out of desired and actual value with (a) Maximum Controller Deviation (see Look-Up-Table	(a)*(b)	g/rev	(EGR controller is active and	=	TRUE	-	fail conditions exists for 7.5 s monitor runs 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			(b) Environmental Pressure correction factor	= 1 factor	change of injection quantity between actual and last received value	< 40.00 (mm ^3/re v)/se		
						С		
					for time and	= 0.25 sec		
					change of engine speed between actual and last received value	< 50.00 rpm/ sec		
					for time and	= 0.50 sec		
					VGT offset learning is active	= FALSE -		
					maximum setpoint for EGR mass flow and	< 1.00 g/rev		
					Engine speed	<= 1400.00 rpm		
					Engine speed and	>= 1000.00 rpm		
					Torque generating engine fuel injection quantity	<= 200.00 mm^ 3/rev		
					Torque generating engine fuel injection quantity	>= 50.00 mm^ 3/rev		
					and basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
) for time	>= 1.00 sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
Exhaust Gas Recirculation (EGR) Motor Control Circuit	P0403		Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	EGR Solenoid Control Circuit	=	ACTIVE	-	fail conditions exists for 7 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and offset learning for EGR valve is completed and battery voltage for time and starter is active cranking for time and basic enable conditions met: and NO Pending or Confirmed DTCs:	=	FALSE	V sec - sec -		
			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		EGR Solenoid Control Circuit and battery voltage for	=	ACTIVE	- V	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В

	Fault	Monitor Strategy	Primary Malfunction		Threshold	Secondary		Enable		Time	MIL
System C	Code	Description	Criteria	Lo	gic and Value	Parameters		Conditions		Required	Illum.
						time and starter is active cranking for time	=	3.00 FALSE 3.00	sec - sec		
						and basic enable conditions met: and NO Pending or Confirmed DTCs:		see sheet enable tables see sheet inhibit tables	-		
Exhaust Gas Recirculation(EGR) Position Sensor Circuit Low Voltage		readings on the EGR position circuit, indicating an OOR low condition on the EGR position circuit	raw voltage of EGR actuator position sensor same as EGR actuator position	<	0.25 V	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	=	TRUE see sheet enable tables see sheet inhibit tables		fail conditions exists for 5 s test performed continuously 0.005 s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ıld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and		Parameters		Conditions	;	Required	Illum.
Exhaust Gas Recirculation(EGR) Position Sensor Circuit High Voltage	P0406	Detects high voltage	raw voltage of EGR actuator position sensor	>	4.80	V	ignition on	II	TRUE	-	fail conditions exists for 5 s test performed continuously 0.005 s rate	А
			EGR actuator position	>	127	%	basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables			
Exhaust Gas Recirculation(EGR) Temperature Sensor A Circuit Low Voltage	P040C		EGR temperature sensor 2 voltage same as EGR sensor 2 temperature	>	220	°C	time since engine start and engine coolant temperature and ambient temperature and ambient pressure and (setpoint valve position of exhaust-gas recirculation and setpoint valve position of exhaust-gas recirculation) and Engine Running (see parameter definition)	>	0.00 199.96 -60.04 20.00 -100.00 200.00	sec °C °C kPa %	fail conditions exists for 5 s monitor runs 0.05 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions	;	Required	Illum.
							and (valve position of EGR cooler bypass and valve position of EGR cooler bypass	>	-100.00 200.00	%		
							and basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Exhaust Gas Recirculation(EGR) Temperature Sensor A Circuit High Voltage	P040D		EGR temperature sensor 2 voltage	>	4.84	V	(fail conditions exists for 5 s monitor runs 0.05 s rate whenever enable conditions are	В
			same as EGR sensor 2 temperature	<	-50	°C	time since engine start and	>	0.00	sec	met	
			tomporature				engine coolant temperature and	<	199.96	°C		
							ambient temperature and ambient pressure and	>	-60.04 20.00	°C kPa		
							(setpoint valve position of exhaust-gas recirculation	>	-100.00	%		
							and setpoint valve position of exhaust-gas recirculation	<	200.00	%		
							and Engine Running (see parameter definition)	=	TRUE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions		Required	Illum.
							and (valve position of EGR cooler bypass and valve position of EGR cooler bypass	>	-100.00 200.00	%		
							and basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	П	see sheet inhibit tables	-		
Exhaust Gas Recirculation(EGR) Temperature Sensor Correlation (EGR 1/ EGR 2)	P040F	Detects biased EGR temperature sensors by comparing the two EGR cooler temp sensor after an engine off soak time	Path 1: (a) - (b) (see Look- Up-Table #4) with	>	100 to 999	°C	minimum engine-off time and ambient temperature	>=	28800.00	sec	fail conditions exists for 0.1 s monitor runs with 0.1 s rate whenever enable conditions are met	В
			(a) captured EGR sensor 2 temperature at startand with(b) captured EGR sensor 1 temperature at start		measured parameter measured parameter	-	and Engine Running (see parameter definition) for	=	TRUE	-		
			or Path 2:				time and engine post drive/ afterun	> =	0.00 FALSE	sec -		
			((a) - (b) (see Look- Up-Table #4) with	<=	100 to 999	°C	and diagnostic performed in current dc and	=	FALSE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary	Ena	ble	Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters	Condi		Required	Illum.
			(a) captured EGR sensor 2 temperature at start	=	measured parameter	-	basic enable conditions met:	ena	sheet - able iles		
			and with (b) captured EGR sensor 1 temperature at start	=	measured parameter	-	and NO Pending or Confirmed DTCs:	inh	sheet - ibit les		
			and (a) - (b) (see Look- Up-Table #7) with	>	20 to 999	°C					
			(a) captured EGR sensor 2 temperature at start	=	measured parameter	-					
			and with (b) captured EGR sensor 1 temperature at start	=	measured parameter	-					
			and (status of block heater (see parameter definition)	=	FALSE	-					
			or status of sun-load detection (see parameter definition))	=	FALSE	-					
Exhaust Gas Recirculation(EGR) Temperature Sensor B Circuit Low Voltage		Detects low voltage readings on the EGR cooler temperature circuit, indicating an OOR low condition on the EGR cooler temperature 1 circuit	voltage of EGR temperature sensor 1	<	0.46	V	(time since engine start	> 0.	00 sec	fail conditions exists for 5 s monitor runs 0.05 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Valu	ıe	Parameters	Conditions	Required	Illum.
Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria EGR sensor 1 temperature		°C	and engine coolant temperature and ambient temperature and ambient pressure and (setpoint valve position of exhaust-gas recirculation and setpoint valve position of exhaust-gas recirculation) and	Conditions < 199.96 °C > -60.04 °C > 20.00 kPa > -100.00 % < 200.00 %		MIL Illum.
						Engine Running (see parameter definition) and (valve position of EGR cooler bypass and valve position of EGR cooler bypass and basic enable conditions met:	= TRUE - > -100.00 % < 200.00 % = see sheet - enable tables		
						NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Exhaust Gas Recirculation(EGR) Temperature Sensor B Circuit High Voltage			voltage of EGR temperature sensor 1	> 4.84	V	(fail conditions exists for 5 s monitor runs 0.05 s rate whenever enable conditions are	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			same as EGR sensor 1 temperature		time since engine start and	> 0.00 sec	met	
			·		engine coolant temperature and	< 199.96 °C		
					ambient temperature and	> -60.04 °C		
					ambient pressure and	> 20.00 kPa		
					setpoint valve position of exhaust-gas recirculation and	> -100.00 %		
					setpoint valve position of exhaust-gas recirculation	< 200.00 %		
					and Engine Running (see parameter definition) and	= TRUE -		
					(valve position of EGR cooler bypass	> -100.00 %		
					and valve position of EGR cooler bypass	< 200.00 %		
					and basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
NMHC Catalyst Efficiency Below Threshold Bank 1	P0420	Detects insufficient conversion rate in oxidation catalyst. Actual conversion rate is compared to a conversion rate threshold as an indication of how much HC is converted in the oxidation catalyst.	Calculated HC conversion rate	< 0.20 -			fail conditions exists for more than 0.1 seconds monitor runs once per driving cycle with 0.1 s rate whenever enable conditions are met	В
					(Modeled HC mass converted in the oxidation catalyst since monitor start and	> 115.00 g		
					average HC mass flow and	> 0.00 g/s		
					simulated heat quantity in oxidation catalyst and	> 0.00 kJ		
					particulate filter regeneration and no reset condition for evaluation is active therefore	= TRUE -		
					regeneration was not aborted to assure that HC conversion was not disturbed and	= TRUE -		
					evaluation took place one time step before (to ensure P0420 has not already completed)	= FALSE -		
					and there has been sufficient HC integrated in order to evaluate the monitor conversion efficiency.	= TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					means (set condition particulate filter regeneration	= TRUE -		
					and measured temperature upstream of the oxidation catalyst and	> 249.96 °C		
					engine speed and	> 700.00 rpm		
					engine speed)	< 3400.00 rpm		
					and diagnostic performed in current dc and	= FALSE -		
					reset condition which becomes False under following conditions	= FALSE -		
					converted HC mass in the oxidation catalyst during monitoring or	< 115.00 g		
					particulate filter regeneration	= FALSE -		
					or regeneration was not aborted to assure that HC conversion was disturbed and	= TRUE -		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					and basic enable conditions met:	= see sheet - enable tables		
1								

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	_	Logic and V	alue	Parameters		Conditions	<u> </u>	Required	Illum.
Primary Fuel Sensor Performance	P0461	Detects an error in the primary fuel tank sensor performance by comparing the decrease of the fuel level for a certain driven mileage to a threshold.	(a) - (b)	>=	100.00	miles	Engine Running (see parameter definition)	=	TRUE	-	fail conditions exists for 0.02 s monitor runs 0.02 s rate whenever enable conditions are met	В
			with (a) total vehicle distance	=	measured parameter	-	for time	>=	60.00	sec		
			and with (b) saved value of total vehicle distance at start of test	=	calculated parameter	-	and External fuel pump control request from GM specific diagnosis tester commanded and	=	FALSE	-		
			and (c) - (d) with	<	4.00	L	fuel transfer pump active means	=	FALSE	-		
			(c) maximum volume of fuel reached in primary tank during test	=	measured parameter	-	filtered fuel volume in primary tank	>=	1638.35	I		
			and with (c) minimum volume of fuel reached in primary tank during test	=	measured parameter	-	or filtered fuel volume in secondary tank	<=	0.00	I		
							or cumulative transfer pump on time in current ignition cycle	>=	0.00	sec		
							or time between activations of transfer pump or	<=	32767.00	sec		
							fuel transfer pump installed) and	=	FALSE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(fuel level zone 1 means	= TRUE -		
					filtered fuel volume in primary tank and	>= 110.70 I		
					filtered fuel volume in secondary tank) or	>= 0.00 l		
					fuel level zone 3 means	= TRUE -		
					filtered fuel volume in primary tank and	< 110.70 I		
					filtered fuel volume in secondary tank) or	> 0.00 I		
					fuel level zone 4 means	= TRUE -		
					filtered fuel volume in primary tank and	< 110.70 I		
					filtered fuel volume in secondary tank)	<= 0.00 I		
					fuel level zone 5 means	= TRUE -		
					(filtered fuel volume in primary tank and	< 110.70 I		
					filtered fuel volume in secondary tank)) and	> 0.00 I		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Logic and Value		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.	
-		·					basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet - enable tables see sheet - inhibit tables		
Fuel Level Sensor 1 Circuit Low	P0462	Detects low voltage readings in the fuel level sensor circuit, indicating an OOR low condition on the fuel level sensor circuit	voltage of fuel level sensor 1	<	0.20	V	ignition on	=	TRUE -	fail conditions exists for 24 s test performed continuously 0.1 s rate	В
			same as fuel level	^	123.2	I	and basic enable conditions met:	II	see sheet - enable tables		
Fuel Level Sensor 1 Circuit High	P0463	Detects high voltage readings in the fuel level sensor circuit, indicating an OOR high condition on the fuel level sensor circuit	voltage of fuel level sensor 1	>	4.80	V	ignition on	=	TRUE -	fail conditions exists for 24 s test performed continuously 0.1 s rate	В
			same as fuel level	<	0	I	and basic enable conditions met:	=	see sheet - enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction			hresh		Secondary		Enable		Time	MIL
System	Code	Description	Criteria				Value	Parameters		Conditions		Required	Illum.
Exhaust Gas Recirculation (EGR) Position Sensor Performance	P046C	valve position errors by comparing desired	controller deviation of EGR valve calculated out of difference between desired and actual value	>=	5	5.00	%	offset learning of EGR actuator active and	=	FALSE	-	fail conditions exists for 8 s monitor runs with 0.02 s rate whenever enable	В
			controller deviation of EGR valve calculated out of difference between desired and actual value	<=	-5	5.00	%	offset learning in the previous driving cycle was complete		TRUE	-	conditions are met	
								and Engine Running (see parameter definition) and	=	TRUE	-		
								duty cycle of the Intake Air Heater output and	<	5.00	%		
								battery voltage and	>=	11.00	V		
								EGR Valve	=	ACTIVE	-		
								EGR Valve Jammed and	=	FALSE	-		
								NO Pending or Confirmed DTCs: and		see sheet inhibit tables	-		
								basic enable conditions met:		see sheet enable tables	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan Speed Output Circuit	P0480	Diagnoses the Cooling Fan low side driver		= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	battery voltage	> 11.00 V	fail conditions exists for 3 s test performed continuously 0.02 s rate	В
			or Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	for time and starter is active cranking for time and ignition on and basic enable conditions met:	> 3.00 sec = FALSE - > 3.00 sec = TRUE - = see sheet - enable tables		
		Diagnoses the Cooling Fan low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	battery voltage	> 11.00 V	fail conditions exists for 1 s test performed continuously 0.02 s rate	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	ı	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	₋ogic and Va	lue	Parameters		Conditions	3	Required	Illum.
							for time and starter is active cranking for time and ignition on and basic enable conditions met:	> = > = =	3.00 FALSE 3.00 TRUE see sheet enable tables	sec sec -		
Cooling Fan System Performance	P0483	Detects inability to control fan speed to desired RPM	fan speed difference between actual and commanded value or fan speed difference between actual and commanded value or fan speed difference between actual and commanded value, unfiltered or fan speed difference between actual and commanded value, unfiltered	<= >= <=	-500.00 500.00 -500.00	rpm	PWM of fan driver output and Commanded fan speed and (fan speed and	>= >= <	36.01 0.00 5320.00	% rpm	fail conditions exists for 120 s monitor runs with 0.1 s rate whenever enable conditions are met	В
			ummtered				fan speed) and engine coolant temperature	>	400.00 69.96	rpm		
							and fan drive speed rate of change and	<	2000.00			
							fan speed weight factor calculated out of (>	0.59	facto r		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(a) * (b) * (c) * (d) with (a) factor based on input shaft stability (see Look- Up-Table #33) and with	= 0 to 1 facto		
					(b) factor based on intake air temperature (see Look- Up-Table #35) and with	= 0 to 1 facto		
					(c) factor based on engine coolant temperature (see Look-Up-Table #34)	= 0 to 1 facto		
					and with (d) factor based on fan drive speed (see Look-Up- Table #32))	= 0 to 1 facto		
					and basic enable conditions met:	= see sheet - enable tables		
Exhaust Gas Recirculation (EGR) Motor Control Circuit 1 Low Voltage	P0489	Diagnoses the EGR Valve low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	EGR Solenoid Control Circuit	= ACTIVE -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and battery voltage for	> 11.00 V		
					time and starter is active cranking for	> 3.00 sec = FALSE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and V		time and basic enable conditions met:	>	3.00 see sheet enable tables	sec -	Required	Illum.
Exhaust Gas Recirculation (EGR) Motor Control Circuit 1 High Voltage	P0490	Diagnoses the EGR Valve low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power		EGR Solenoid Control Circuit	=	ACTIVE	-	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
						and battery voltage for time and starter is active cranking for time and basic enable conditions met:	> = >	11.00 3.00 FALSE 3.00 see sheet enable tables	V sec - sec		
Cooling Fan Speed High	P0495	Detects a locked fan. When fan speed control solenoid is off, the fan speed should follow accessory drive input speed plus some slip.	fan speed (see Look- Up-Table #36) for Error counter	> 400 to 1500	counts	fluid volume in Clutch (see Look-Up-Table #37) or Maximum allowed clutch pump out time	>=	0.005 to 0.0115 600 to 65534	l	fail conditions exists for 0.02 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and V		Parameters		Conditions		Required	Illum.
			equivalent to 80 sec		when { fan sp and	peed	>	1500.00	rpm		
					and	of fan driver output	<=	36.00	%		
) and	nanded fan speed ent pressure	>	600.00 55.00	rpm kPa		
					intake and	air temperature	>	-40.04 0.00	°C sec		
					(engine	e speed (see Look- able #91)	>	600 to 850	rpm		
					time) } and		>	0.00	sec		
					basic en met:	nable conditions	=	see sheet enable tables	-		
Exhaust Gas Recirculation (EGR) Control Position Not Learned	P049D	Detects adaptation values of EGR bypass that are not plausible. Compares the difference between the maximum and minimum adaptation values to a threshold.	Path 1 : (a) - (b)	> 30.00		arning is active	=	TRUE	-	fail conditions exists for 0.005 s monitor runs with 0.005 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions		Required	Illum.
			(a) maximum learned offset value for EGR valve	=	measured parameter	-	engine coolant temperature	>=	5.06	°C		
			and with (b) minimum learned offset value for EGR valve	=	measured parameter	-	and engine coolant temperature	<=	123.06	°C		
			or Path 2: (learned offset value	>	23.33	%) and (battery voltage	>=	10.00	V		
			for EGR valve in the present driving cycle or				and					
			learned offset value for EGR valve in the present driving cycle	<	-23.33	%	battery voltage	<=	30.00	V		
			,				and EGR sweep has ended - no movement in EGR valve and	=	TRUE	-		
							engine post drive/ afterun and	=	TRUE	-		
							engine was running during last driving cycle means	=	TRUE	-		
							engine running during last driving cycle and	=	TRUE	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
							and basic enable conditions met:	=	see sheet enable tables	-		
					_	_			_			

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	l k	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions		Required	Illum.
		Detects a jammed EGR valve during opening or closing the valve.	Path 1:				Path 1:				fail conditions exists for 0.005 s monitor runs	
		valve.	EGR valve stuck during opening means (=	TRUE	-	EGR valve is opening or Path 2:	=	TRUE	-	with 0.005 s rate whenever enable conditions are	
			(a) + (b) with	>=	20.01	%	EGR valve is closing and	=	TRUE	-	met	
			(a) position of EGR valve	=	measured parameter	-	engine post drive/ afterun	=	TRUE	-		
			and with (b) learned offset value of EGR valve in the previous driving cycle	=	measured parameter	-	and offset learning active	=	TRUE	-		
			or (a) - (c)	<=	0.01	%	and basic enable conditions met:	=	see sheet enable tables	-		
			with (a) position of EGR valve	=	measured parameter	-						
			and with (c) position of EGR valve of previous process cycle	=	measured parameter	-						
) for time or	>	5.00	sec						
			Path 2: EGR valve stuck during closing means	=	TRUE	-						
			(position of EGR valve with	<=	(a) * (b)	-						

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters	(Conditions	3	Required	Illum.
			(a) reference position of the EGR valve in open position and with (b) factor for EGR valve close position	П	measured parameter 0.50	-						
			or (c) - (d) with	>	0.02	%						
			(c) position of EGR valve	=	measured parameter	-						
			and with (d) position of EGR valve of previous process cycle	=	measured parameter	-						
) for time	>	5.00	sec						
Idle Speed Too Low	P0506	Detects an idle speed governor that is unable to achieve the desired idle speed and the idle speed is too low	engine speed with (a) minimum engine	<	maximum value of (a) OR (b - (b * c))	rpm	engine speed (see Look-Up- Table #91) and	>=	600 to 850	rpm	fail conditions exists for 20 s monitor runs with 0.1 s rate whenever enable conditions are met	В
			speed and with (b) minimum idle speed setpoint	=	calculated parameter	-	engine coolant temperature and	<	122.96	°C		
			and with (c) factor for calculation of engine speed interval	=	24.00	%	engine coolant temperature)	>	-7.04	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	I	Logic and Va	lue	Parameters		Conditions		Required	Illum.
							and idle speed controller active and vehicle speed and	V	TRUE	- mph		
							no other torque demanding function active and	=	TRUE	-		
							setpoint torque of the speed controller and	>	0	NM		
							engine speed and	>	300.00	rpm		
							basic enable conditions met: and	=	see sheet enable tables	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Idle Speed Too High	P0507	Detects an idle speed governor that is unable to achieve the desired idle speed and the idle speed is too high.	engine speed		minimum value of (a) OR (b + (b * c))		engine speed (see Look-Up- Table #91)	>=	600 to 850	rpm	fail conditions exists for 20 s monitor runs with 0.1 s rate whenever enable	В
			with (a) maximum engine speed	=	2500.00	rpm	and (conditions are met	
			and with (b) minimum idle speed setpoint	=	calculated parameter	-	engine coolant temperature and	<	122.96	°C		
			and with (c) factor for calculation of engine speed interval	=	24.00	%	engine coolant temperature)	>	-7.04	°C		
							and idle speed controller active	=	TRUE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and Va	lue	Parameters		Conditions		Required	Illum.
							and vehicle speed and no other torque demanding function active	< =	1.86 TRUE	mph -		
							and setpoint torque of the speed controller	>	0	NM		
							and engine speed and	>	300.00	rpm		
							basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Cooling Fan Speed Sensor Circuit	P0526	This diagnostic checks the circuit for electrical integrity during operation.	Path 1:				engine speed	>	550.00	rpm	fail conditions exists for 3 s monitor runs with 0.020 s rate	В
			period is too long to measure and	>	0.21	sec	and {				whenever enable conditions are met	
			current state of the signal received from fan is low	=	TRUE	-	PWM of fan driver output	>=	36.00	%		
) or				and Commanded fan speed)	>=	0.00	rpm		
			Path 2: period is too long to	>	0.21	sec	for time or	>	30.00	sec		
			measure and (vehicle speed for	<	203.65	mph		
			current state of the signal received from fan is high	=	TRUE	-	time	>	327.67	sec		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshol ogic and V		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
)				} and basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet - enable tables see sheet - inhibit tables		
Exhaust Gas Temperature (EGT) Sensor 1 Circuit Low Voltage	P0545	Detects low voltage readings on the EGT 1 circuit, indicating an OOR low condition on the EGT circuit	voltage of the temperature sensor upstream of oxidation catalyst same as temperature upstream of oxidation catalyst	<	-50	°C	NO Pending or Confirmed DTCs: for time and ignition on and basic enable conditions met:	= > = =	see sheet inhibit tables 0.00 sec TRUE - see sheet enable tables	fail conditions exists for 3 s monitor runs 0.050 s rate whenever enable conditions are met	В
Exhaust Gas Temperature (EGT) Sensor 1 Circuit High Voltage	P0546	Detects high voltage readings on the EGT 1 circuit, indicating an OOR high condition on the EGT 1 circuit	voltage of the temperature sensor upstream of oxidation catalyst same as temperature upstream of oxidation catalyst	>	2.21	V °C	NO Pending or Confirmed DTCs: for time and ignition on and	>	see sheet - inhibit tables 0.00 sec	fail conditions exists for 3 s monitor runs 0.050 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \	/alue	Parameters		Conditions		Required	Illum.
							basic enable conditions met:	П	see sheet enable tables			
Idle Control System Fuel Quantity Lower Than Expected	P054E	Quantity Threshold - Fuel Quantity Lower Than Expected	Current injection quantity with Current gear and minimum expected injection quantity (see Look-Up-Table #96) and factor for calculating the minimum threshold out of the	✓	expected injection quantity (map) * factor for calculatin g the minimum threshold out of the reference map	- mm^3/rev	and Vehicle speed and Particulate filter regeneration and Engine speed	= <= =	unchange d 1.86 not active 1040.00	mph - rpm	fail conditions exists for 15 s monitor runs 0.10 s rate whenever enable conditions are met	В
			reference map)				and Engine speed and Engine coolant temperature and Idle speed controller all for time	>= >	476.00 -20.04 active 5.00	rpm °C - sec		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
) and accelerator pedal position and Fluctuation range of engine speed and Basic enable conditions met	= 0.00 % < 16383.50 rpm = see sheet - enable tables		
Idle Control System - Fuel Quantity Higher Than Expected	P054F	Quantity Threshold - Fuel Quantity Higher Than Expected	(Current injection quantity	maximum mm^3 expected injection quantity (map) * factor for calculatin g the maximum threshold out of the reference map	rev Current gear	= unchange - d	fail conditions exists for 15 s monitor runs 0.10 s rate whenever enable conditions are met	В
			with Current gear and maximum expected injection quantity (see Look-Up-Table #50) and	<> Neutral - = 126.8 to mm^3 230.8	and Vehicle speed and rev Particulate filter regeneration and	<= 1.86 mph = not active -		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
- Oystein	Odde	Безсприон	factor for calculating the maximum threshold out of the reference map	= 1.50 factor	and Engine speed and Engine speed and Engine coolant temperature and Idle speed controller all for time) and accelerator pedal position and Fluctuation range of engine speed and	<= 1040.00 rpm >= 476.00 rpm > -20.04 °C = active - > 5.00 sec = 0.00 % < 16383.50 rpm	Required	
Cruise Control Resume Switch Circuit	P0567	Resume switch state indicates problem with the circuit	Resume Switch CAN message in high / active state	= TRUE -	ignition on and input circuit active and basic enable conditions met and DTCs:	= see sheet - enable tables = TRUE - = TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exists for 90 s monitor runs with 0.005 s rate whenever enable conditions are met	Special C

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Thresho		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
Cruise Control Set Switch Circuit	P0568	Set switch state indicates problem with the circuit	Set Switch CAN message in high / active state	=	TRUE	-	ignition on and input circuit active and basic enable conditions met and NO Pending or Confirmed DTCs:	= =	TRUE - TRUE - see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 90 s monitor runs with 0.005 s rate whenever enable conditions are met	Special C
Cruise Control Input Circuit	P0575	Cruise control CAN communication monitoring	amount of errors in consecutive frames with number of consecutive frames	>=	3.00	counts	ignition on and input circuit active and basic enable conditions met and NO Pending or Confirmed DTCs:	= = =	TRUE - TRUE - see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 0.005 ms monitor runs with 0.005 s rate whenever enable conditions are met	Special C
Brake Pedal Position Sensor "A" Circuit Range/Performance	P057B	Compare maximum delta of analog brake pedal sensor with a threshold	EWMA filtered test result based on the difference of (a) - (b) where	<=	0.40	factor	following conditions for time:	>	4 se	monitor runs 0.02 s rate whenever enable conditions are met	А

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions		Required	Illum.
			(a) maximum analog brake sensor raw voltage during test (b) minimum analog	=	measured parameter measured	V	ignition on	=	TRUE	-		
			brake sensor raw voltage during test		parameter	·						
			where difference of the brake sensor voltage corresponds to a corrected value of (see Look-Up- Table #14)	=	0 to 1	factor	starter is active cranking for	=	FALSE	-		
							time and	>	3.00	sec		
							battery voltage for	>	11.00	V		
							time)	>	3.00	sec		
							and gear has been in Park during this driving cycle	=	TRUE	-		
							full test has not been completed this driving cycle	=	TRUE	-		
							gear selector currently not in Park	=	TRUE	-		
							vehicle speed accelerator pedal position 1 and	>=	4.35 5.00	mph %		
							No Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
							and basic enable conditions met:	=	see sheet enable tables	-		
					_	_			_			

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor - Circuit Low Voltage	P057C		Brake pedal position sensor voltage	< 0.25 V	and No Pending or Confirmed DTCs: and basic enable conditions met:	= TRUE - = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for 0.5 s monitor runs 0.01 s rate whenever enable conditions are met	A
Brake Pedal Position Sensor - Circuit High Voltage	P057D	Brake pedal voltage above threshold of a calibrated period of time	Brake pedal position sensor voltage	> 4.75 V	ignition on and No Pending or Confirmed DTCs: and basic enable conditions met:	= TRUE - = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for 0.5 s monitor runs 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Value	Parameters		Conditions		Required	Illum.
ROM Memory Fault	P0601	Detects a fault in the ROM memory	ECM detects multiple errors in the ROM-memory by comparing a calculated checksum with a check word	П	TRUE -	engine post drive/ afterun	П	TRUE	-	fail conditions exists for 0.01 s test performed once per drive cycle during afterrun	A
Control Module Not Programmed	P0602	Detects if the ECM is programmed.	ECM not programmed	=	TRUE -	ignition on and engine pre drive	=	TRUE	-	fail conditions exists for 0.01 s test performed test performed once per driving cycle during ECU initialization	A
Control Module Internal Performance	P0606	Monitors and detects the improper operation of the ECM. This is accomplished by monitoring the output of various hardware modules within the ECM and by creating parallel redundant calculations of critical engine management system parameters.	SPI communication, data transfer lost	Е	TRUE -	ignition on	11	TRUE	-	fail conditions exists for 0.5 s test performed continuously with 0.01 s rate	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Thresh Logic and		Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Gystein	Odde	Description	Ontena	Logio and	Value	basic enable conditions met:	= see sheet - enable conditions	required	mam.
			faults detected in the SPI communication IC internal	> 523.00	counts	ignition on and NO Pending or Confirmed DTCs:	= TRUE - see sheet - inhibit tables	fail conditions exists for at least 0.64 s monitor runs once per trip during pre drive at least twice every 0.08s rate whenever enable conditions are met	
			internal supply voltage or internal supply voltage	< 4.2 > 5.25	V	ignition on and counter of reactivation attempt of power output stage and NO Pending or Confirmed DTCs:	= TRUE - >= 2.00 coun ts see sheet - inhibit tables	fail conditions exists for 0.08s monitor runs once per trip during pre drive at least twice every 0.08s rate whenever enable conditions are met	
			(a) - (b)	> 50.00	us	programmed energizing time for fuel injection has been read back	= TRUE -	fail conditions exists for at least 0.05 s monitor runs with 0.01 s rate	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
			with (a) parallel redundant calculation of energizing time for fuel injection and with		measured	-	means programmed energizing time for fuel injection and	>=	0 TRUE	-	whenever enable conditions are met	
			(b) parallel redundant calculation of programmed energizing time for fuel injection	=	measured parameter	-	measured energizing time for fuel injection has been read back means	=	TRUE	-		
							measured energizing time for fuel injection and	>=	0	-		
							engine speed and	>	1200.00	rpm		
							rail pressure and	>	20000.00	kPa		
							engine test active via diagnosis tester	=	FALSE	-		
			Path 1:				engine speed	>	1200.00	rpm	fail conditions exists for at least 0.05 s	
			(parallel redundant calculation of angle for pilot injection 1 quantity or	<	-32.98		and engine test active via diagnosis tester	=	FALSE	-	monitor runs with 0.01 s rate whenever enable conditions are	
			parallel redundant calculation of angle for pilot injection 1 quantity) or Path 2:	>	102.99	degrees					met	
			(parallel redundant calculation of angle for main injection quantity	<	-32.98	degrees						

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary	Enable	Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters	Conditions	Required	Illum.
		·	or parallel redundant calculation of angle for main injection quantity) or Path 3:	>	30.06	degrees				
			(parallel redundant calculation of angle for post injection quantity 1 or	<	-360.00	degrees				
			parallel redundant calculation of angle for post injection quantity 1) or Path 4:	>	-67.00	degrees				
			parallel redundant calculation of angle for post injection quantity 2	<	-83.00	degrees				
			parallel redundant calculation of angle for post injection quantity 2) or Path 5:	>	30.06	degrees				
			(parallel redundant calculation of angle for post injection quantity 3 or	<	-83.00	degrees				
			parallel redundant calculation of angle for post injection quantity 3	>	0.00	degrees				

Component / Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
		parallel redundant calculation of energizing times of the correction value for pilot injection quantity (see Look-Up-Table #56) or parallel redundant calculation of energizing times of the correction value for pilot injection	< -500 to - us 500	redundant engine speed calculation and engine test active via diagnosis tester	>= 1200.00 rpm = FALSE -	fail conditions exists for at least 0.2 s monitor runs with 0.04 s rate whenever enable conditions are met	
		for pilot injection quantity (see Look-Up-Table #55)) parallel redundant calculation of post injection 2 quantity	> 130.00 mm^3	engine test active via diagnosis tester and change in injection operation mode requested	= TRUE -	fail conditions exists for at least 0.4 s monitor runs with 0.04 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters		Conditions		Required	Illum.
			parallel redundant calculation of averaged torque creating energizing time per cylinder (see Look-Up-Table #58)	>	200 to 6000	us	fuel system is in fuel cut off	=	TRUE	-	fail conditions exists for at least 0.8 s monitor runs	
			and activation counter (intervention) of the surge damper	>=	72.00	counts	for time and	>	0.65	sec	with 0.04 s rate whenever enable conditions are met	
							redundant engine speed calculation and	>	2040.00	rpm		
							general engine speed demand (see parameter definition line #213) and	=	FALSE	-		
							external torque demand from stability ECU via CAN and	=	FALSE	-		
							external torque demand from transmission ECU via CAN and	=	FALSE	-		
							cruise control active or	=	FALSE	-		
							brake pedal status or	=	TRUE	-		
							redundant brake pedal status)	=	TRUE	-		
							for time) and	>	0.28	sec		
							(pedal position or	=	0	%		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions		Required	Illum.
							redundant calculation of pedal position for time	>	0.02	% sec		
							and (redundant engine speed calculation after start detected	>	120.00	rpm		
							and redundant engine speed calculation at start (see Look-Up-Table #57))	>	840 to 1080	rpm		
							and engine test active via diagnosis tester	=	FALSE	-		
			parallel redundant calculation of averaged wave correction quantity for pilot injection	>=	5.00	mm^3	redundant engine speed calculation	>=	1200.00	rpm	fail conditions exists for at least 0.2 s monitor runs with 0.04 s rate whenever	
			or parallel redundant calculation of averaged wave correction quantity for main injection or	>=	5.00	mm^3	and engine test is active via diagnosis tester	=	FALSE	-	enable conditions are met	
			parallel redundant calculation of averaged wave correction quantity for post injection 2 or	>=	5.00	mm^3						
			parallel redundant calculation of averaged wave correction quantity for post injection 3	>=	5.00	mm^3						

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	l l	₋ogic and V	alue	Parameters		Conditions		Required	Illum.
			substitute value of rail pressure or substitute value of rail pressure	<= >=	16000 204000	kPa kPa	parallel redundant calculation of voltage of rail pressure sensor or parallel redundant calculation of voltage of rail pressure sensor) and delay time and parallel redundant calculation of injections active and redundant engine speed calculation and engine test active via diagnosis tester and level one signal range check detects fault		0.19 4.81 0.21 TRUE 1000.00 FALSE TRUE	V V sec - rpm -	fail conditions exists for 0.120 s monitor runs with 0.01 s rate whenever enable conditions are met	
			internal supply voltage or internal supply voltage		4.2 5.25	V	ignition on	=	TRUE		fail conditions exists for 0.05 s test performed continuously with 0.01 s rate	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \	/alue	Parameters		Conditions		Required	Illum.
			WDA (watch dog) shut off due to undervoltage means internal supply voltage	= <	TRUE	- V	shut off path test active and battery voltage for time and WDA (watch dog) line active	> > =	8.00	- V	fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	
			WDA (watch dog) shut off due to overvoltage means internal supply voltage	= >	TRUE 5.25	- V	shut off path test active and WDA (watch dog) line active	=			fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	
			WDA (watch dog) shut off due to internal security error	=	TRUE	-	shut off path test active and WDA (watch dog) line active	=	FALSE TRUE	-	fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			WDA (watch dog) shut off because of corrupt question-and- answer communication	= TRUE -	ignition on and WDA (watch dog) line active and shut off path test active	= TRUE - = TRUE - = FALSE -	fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	
			the actual response time from processor is not equal to the requested response- time	= TRUE -	ignition on and NO Pending or Confirmed DTCs:	= TRUE - see sheet inhibit tables	fail conditions exists for more than 0.08 s monitor runs at least twice every 0.08 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	Required	Illum.
			redundant, independent algorithm for plausibility fault of accelerator pedal signal for safety reasons:							fail conditions	
			Path 1:				ignition on	=	TRUE -	exists for 0.28 s monitor runs with 0.04 s rate	
			(maximum (a) (b)) - 2 * (maximum (c) (b)) with	>	0.29	V	and engine test active via	=	FALSE -	whenever enable conditions are	
			(a) voltage accelerator pedal 1	=	measured parameter	-	diagnosis tester and			met	
			and with (b) lower limit for accelerator pedal voltage	=	0.80	V	Input signal fault present and	=	FALSE -		
			and with (c) voltage accelerator pedal 2	=	measured parameter	-	ADC fault present	=	FALSE -		
			and (
			voltage accelerator pedal 1 or	>	1.47	V					
			voltage accelerator pedal 2) or Path 2:	>	1.47	V					
			(maximum (a) (b)) - 2 * (maximum (c) (b)) with		0.41	V					
			(a) voltage accelerator pedal 1	=	measured parameter	-					
			and with								

Component /	Fault	Monitor Strategy	Primary Malfunction		reshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria		and Value	Parameters	Conditions	Required	Illum.
			(b) lower limit for accelerator pedal voltage and with (c) voltage accelerator pedal 2	= mea	.80 V asured - ameter				
			and (voltage accelerator pedal 1 or		.47 V				
			voltage accelerator pedal 2)		.47 V				
			no response to an injection request processor internal	= TF	RUE -	ignition on and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - inhibit tables	fail conditions exists for more than 0.08 s monitor runs at least twice every 0.08 s rate whenever enable conditions are met	
			no response to shut- off path test processor internal	= TF	RUE -	ignition on and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - inhibit tables	fail conditions exists for more than 0.523 monitor runs at the 0.01 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			no response to hardware activation request processor internal		ignition on and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - inhibit tables	fail conditions exists for more than 0.437 monitor runs at least twice every 0.08 s rate whenever	
			no response from processor operative system processor internal		ignition on and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - inhibit tables	fail conditions exists for more than 0.08 s monitor runs at least twice every 0.08 s rate whenever	
							enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and		Parameters		Conditions		Required	Illum.
			Path 1: repetitions of injection	>=	523.00		ignition on and	=	TRUE	-	fail conditions exists for more	
			shut-off path test or Path 2: (number of a powerstage test too few	<	2.00	counts	injection shut-off path test	=	ACTIVE	-	than 0.64 s monitor runs at least twice every 0.08 s rate whenever enable conditions are met	
			and number of cylinders)	>=	8.00	counts					met	
			prevention of the	=	TRUE	-	ignition on	=	TRUE	-		
			execution of the shut- off path test				and injection shut-off path test	=	ACTIVE	-	fail conditions exists for 0.08 s monitor runs at least twice every 0.08 s rate whenever enable conditions are met	
			too few bytes received by monitoring module from CPU	=	TRUE	-	ignition on	=	TRUE	-		
			means bytes received by monitoring module from CPU as response	<	4	Bytes					fail conditions exists for more than 0.4 s monitor runs at least twice every 0.08 s rate whenever enable conditions are	

Component / Faul		Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cyolom Code	Boompton	ECM detects interruption in the SPI communication processor internal	= TRUE	ignition on	= TRUE -	fail conditions exists for more than 0.08 s monitor runs at least twice every	
		ECM detects plausibility error of the	= TRUE -	ignition on	= TRUE -	0.08 s rate whenever enable conditions are met	
		communication between controller and the monitoring module (2 processors in ECU) processor internal				fail conditions exists for more than 0.2 s monitor runs at least twice every 0.08 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary	Enab		Time	MIL
System	Code	Description	Criteria	L	₋ogic and \	/alue	Parameters	Condit	ions	Required	Illum.
			redundant filtered supply voltage to injector chip 1 or	<	3.10	V	ignition on and	= TRU	JE -	fail conditions exists for 0.5 s monitor runs with 0.01 s rate	
			redundant filtered supply voltage to injector chip 1	>	3.51	V	battery voltage	> 8.00	0 V	whenever enable conditions are	
							and basic enable conditions met:	= see sh enab table	ole	met	
			redundant filtered supply voltage to injector chip 2	<	3.10	V	ignition on	= TRU	JE -	fail conditions exists for 0.5 s monitor runs with 0.01 s rate whenever	
			or redundant filtered supply voltage to injector chip 2	>	3.51	V	and battery voltage	> 8.00	0 V	enable conditions are met	
							and basic enable conditions met:	= see sh enab table	ole		
			internal injector driver chip 1 error	=	TRUE	-	Engine Running	= TRU	JE -	fail conditions exists for more	
			IC internal				and			than 0.1 s monitor runs	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters basic enable conditions met:	conditions = see sheet - enable tables	Required with 0.01 s rate whenever enable conditions are met	Illum.
			internal injector driver chip 2 error IC internal	= TRUE -	Engine Running and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for more than 0.1 s monitor runs with 0.01 s rate whenever enable conditions are met	
			piezo injector actuator internal feedback voltage or piezo injector actuator internal feedback voltage	< 0.00 V > 3.30 V	main injection	= ACTIVE	fail conditions exists for more than 0.1 s monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	L	ogic and Va	alue	Parameters	Conditions	Required	Illum.
			Path 1: engine speed or Path 2:	>	1500.00	rpm	injection cut off demand from ECM internal monitoring	= TRUE	fail conditions exists for 0.02 s test performed continuously with 0.02 s	
			engine speed		1600.00	rpm				
			security torque limitation request due to implausible air system control requests		TRUE		ignition on	= TRUE -	fail conditions exists for more than 533 events test performed continuously with 0.01 s	
			security torque limitation request due to implausible rail pressure request	=	TRUE	-	ignition on	= TRUE -	fail conditions exists for more than 533 events test performed continuously with 0.01 s	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions	Required	Illum.
			security torque limitation request due to implausible quantity	=	TRUE		ignition on	=	TRUE -	fail conditions exists for more than 533 events	
			setpoint control requests							test performed continuously with 0.01 s	
			indicated torque	>	(a) + (b) + (c) + (d)	-	Engine Running	=	TRUE -		
			with				and				
			(a) modeled inner engine torque	=	calculated parameter	-	basic enable conditions met:	=	see sheet - enable tables	fail conditions	
			and with (b) torque tolerance offset (see Look-Up- Table #54)		11.71875 to 99.60937 5	%				exists for more than 0.28 s monitor runs with 0.04 s rate whenever	
			and with (c) torque of engine speed controller	=	calculated parameter	-				enable conditions are met	
			and with (d) torque of surge damper control	=	calculated parameter	-					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary	Enable	Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters Parameters Parameters	Conditions	Required	Illum.
			voltage of charging switch or voltage of charging switch if buffer of a bank is not charged completely, or not at all	>	210.00	V	ECM is in startup before injections are released	= TRUE -	fail conditions exists for more than 4 events monitor runs with 0.01 s rate whenever enable conditions are met	
			error at startup of DC/DC converter of one bank	=	TRUE		ignition on and DC/DC converter is in startup	= TRUE - = TRUE -	fail conditions exists for 0.01 ms monitor runs with 0.01 s rate whenever enable conditions are met	
			DC/DC converter cannot be switched off.	=	TRUE	_	ignition on	= TRUE -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Cyclessis	0000	2000	- Thoria	Logio una value	T diamotoro	Contantions	rtoquirou	
Control Module Analog to Digital Performance	P060B	Electronic ECM circuitry determines if ADC is correctly converting signals within the correct time periods.	time for calibration of ADC	>= 0.30 sec	ignition on	= TRUE -	fail conditions exists for 0.01 s test performed continuously 0.01 s	A
			voltage at ADC test voltage input or voltage at ADC test voltage input	< 4.73 V > 4.83 V	ignition on	= TRUE -	fail conditions exists for at least 0.15 s test performed continuously 0.01 s	
			(a) - (b) with (a) voltage accelerator pedal signal 2 at internal ADC	> 0.15 V = measured - parameter	ignition on and (= TRUE -	fail conditions exists for at least 0.12 s monitor runs with 0.01 s rate whenever enable	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required
			and with (b) voltage accelerator pedal signal 2 at external ADC	= measured - parameter	counter for steady state detection of the internal AD converter means (a) - (b) with (a) voltage accelerator pedal signal 2 at internal ADC and with (b) voltage of the accelerator pedal signal 2 at the external ADC or counter for steady state detection of the external AD converter means (c) - (d) with (c) voltage accelerator pedal signal 2 at external ADC and with (d) voltage of the accelerator pedal signal 2 at the internal ADC)	>= 4.00 coun ts <= 0.06 V = measured - parameter = measured - parameter >= 4.00 coun ts <= 0.06 V = measured - parameter = measured - parameter = measured - parameter	conditions are met
			(ratio metric correction factor or ratio metric correction factor)	< 0.62 - > 0.74 -	ignition on	= TRUE -	fail conditions exists for at least 0.15 s test performed continuously 0.01 s

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshole Logic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
- Cystein	55.00	Jeen pien	5.1.5.1.0				7 41411101010				roquirou	
Internal Control Module Engine Speed (RPM) Performance	P061C	Monitors main and redundant engine speed calculations for agreement. Detects failure in engine speed calculation through redundant calculation algorithm.	(a) - (b)	>=	400.00	rpm	redundant calculated engine speed	>=	600.00	rpm	fail conditions exists for more than 0.32 s monitor runs with 0.04 s rate whenever enable conditions are met	В
			with (a) redundant calculated engine speed	H	calculated parameter	-	and engine synchronization	=	TRUE	-	illet	
			and with (b) engine speed	Ξ	measured parameter	-						
Fuel Pre-supply Pump Control Circuit Open	P0627	Diagnoses the Fuel Pre-Supply Pump low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	=	Open Circuit:≥ 200 K Ω impedanc e between ECU pin		engine post drive/ afterun	=	FALSE	-	fail conditions exists for 1.99s monitor runs with 0.2 s rate whenever enable conditions are	В
					and load		for time and battery voltage for time	> >	1.00 11.00 3.00	sec V sec	met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
-		·			and (ignition on and basic enable conditions met:)	= TRUE - = see sheet - enable tables		
Fuel Pre-supply Pump Control Circuit Low Voltage		Diagnoses the Fuel Pre-Supply Pump low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to-ground)	ground: ≤ 0.5 Ω impedanc e between signal and controller ground	for time and battery voltage for time and (ignition on and basic enable conditions met:	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec = TRUE - = see sheet - enable tables	fail conditions exists for 1s monitor runs with 0.2 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Val	ue Parameters	Conditions	Required	Illum.
Fuel Pre-supply Pump Control Circuit High Voltage	P0629		Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	- engine post drive/ afterun	= FALSE -	fail conditions exists for 2 s monitor runs with 0.2 s rate whenever enable conditions are met	В
					for time and battery voltage for time and (ignition on and basic enable conditions met:	> 1.00 sec > 11.00 V > 3.00 sec = TRUE - = see sheet - enable tables		
Control Module Long Term Memory Performance	P062F	Each data block of memory is read for a check sum error and flags if a fault is found.	EEPROM sector reports faults regarding: unable to erase or change whole EEPROM sector or read order is not successfully accomplished for more than amount of blocks or	= TRUE = 3 c	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 0.01 s test performed continuously at the 0.01 s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and \		Parameters		Conditions	5	Required	Illum.
			amount of write errors in current block	=	3	counts						
5 Volt Reference 1 Circuit	P0641	Sensor supply voltage circuitry determines if faults related to maintaining the voltage level exist.	sensor supply voltage 1	<=	4.6	V	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables	-	fail conditions exists for 0.1 s test performed continuously 0.01s rate	A
Malfunction Indicator Lamp (MIL) Control Circuit	P0650	Diagnoses the Malfunction Indicator Lamp (MIL) low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	; ; ;	Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground		and ignition on and (battery voltage for time	= >	TRUE TRUE 11.00 3.00	- V	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	A (no MIL)

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Gystein	9949	Soonpilon	511611d	20glo ana valuo	and basic enable conditions met:	= see sheet - enable tables	. roquirou	
			Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	lamp is commanded off	= TRUE -	fail conditions exists for 2 s monitor runs with 0.01 s rate whenever enable conditions are met	
					and ignition on and (battery voltage for time and basic enable conditions met:	= TRUE - > 11.00 V > 3.00 sec = see sheet - enable		
			Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	circuit active at low current and ignition on and	tables = TRUE -	fail conditions exists for 0.2 s monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters battery voltage for time and basic enable conditions met:	> 11.00 V > 3.00 sec = see sheet - enable tables	Required	Illum.
5 Volt Reference 2 Circuit	P0651	Sensor supply voltage circuitry determines if faults related to maintaining the voltage level exist.	sensor supply voltage 2	<= 4.6 V	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 0.1 s test performed continuously 0.01s rate	A
5 Volt Reference 3 Circuit			sensor supply voltage 3	<= 4.6 V	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 0.1 s test performed continuously 0.01s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System 5 Volt Reference 4 Circuit	P06A3	Description Sensor supply voltage circuitry determines if faults related to the voltage level present at the sensor supply voltage exist.		<=	4.6	V	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 1.0 s test performed continuously 0.01s rate	B B
5 Volt Reference 5 Circuit	P06D2	Sensor supply voltage circuitry determines if faults related to the voltage level present at the sensor supply voltage exist.	sensor supply voltage 5	<=	4.6	V	ignition on and basic enable conditions met:	=	TRUE - see sheet - enable tables	fail conditions exists for 0.1 s test performed continuously 0.01s rate	В
Transmission Control Module (TCM) Requested MIL Illumination	P0700	Monitors Serial Data Communication for request from TCM to illuminate the MIL	Serial data communication from the TCM indicates the TCM has requested the MIL	=	TRUE		for time and new message is received via CAN and	> =	TRUE - 0.25 sec TRUE -	fail conditions exists for 1 s test performed continuously 0.5 s rate	А

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					basic enable conditions met and NO Pending or Confirmed DTCs:	see sheet - enable tablessee sheet - inhibit tables		
Park/Neutral Position (PNP) Switch Circuit High Voltage	P0851	Detects high voltage condition on the PNP circuit by comparing the ECM sensed input to the broadcasted state from the TCM over GMLAN serial data	ECM (on-board control unit) sensed position based on PNP switch inputs to ECM indicates park or neutral and the GMLAN message from the TCM disagrees	= TRUE -	battery voltage and battery voltage) and engine speed and vehicle speed and engine torque and accelerator pedal position and (selected gear position is park or selected gear position is neutral) and basic enable conditions:	>= 11.00 V <= 655.34 V >= 650.00 rpm >= 14.92 mph >= 120.00 Nm >= 0.00 % = FALSE - = FALSE -	fail conditions exist for more than 3000 events monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Park/Neutral Position (PNP) Switch Circuit Low Voltage	P0852	condition on the PNP circuit by comparing the ECM sensed input to the broadcasted state from the TCM over GMLAN serial data	GMLAN Message for PNP position indicates park neutral and disagrees with ECM (on-board control unit) sensed position based on PNP switch inputs to ECM		battery voltage and battery voltage) and engine speed and (selected gear position is park or selected gear position is neutral) and basic enable conditions met: and NO Pending or Confirmed DTCs:	>= 11.00 V <= 655.34 V <= 7000.00 rpm = TRUE - = TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exist for more than 3000 events monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions	3	Required	Illum.
Traction Control Input Signal	P0856	Detects a failure when a certain number of Traction Control System torque request messages within a defined message group checksum or rolling count values are incorrect	Traction Control torque request	>=	3.00	counts	Traction Control Torque Request CAN Message Received	Ξ	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	Special C
							and no rolling count or protection errors on CAN Frame \$1C7 and ignition on and basic enable conditions met:	= =	TRUE TRUE see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Reductant Pump High Control Circuit Low Voltage	P1043		Voltage low during driver on state (indicates short to ground)	Ξ	Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	-	engine pre drive	=	FALSE	-	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
							for time and battery voltage	> >	1.00 11.00	sec V		
							for time and	>	3.00	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions < 655.34 V	Required	Illum.
					battery voltage for time and	> 3.00 sec		
					(battery voltage correction factor and	> 0.00 facto r		
					battery voltage correction factor)	< 4.00 facto r		
					for time battery voltage correction factor)	> 3.00 sec < 4.00 facto r		
					for time and basic enable conditions	> 3.00 sec = see sheet -		
					met:	enable tables		
Reductant Pump High Control Circuit High Voltage			Voltage high during driver off state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	В
					for time and battery voltage	> 1.00 sec > 11.00 V		
					for time	> 3.00 sec		
					and battery voltage for	< 655.34 V		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					time and (battery voltage correction factor and battery voltage correction factor) for time battery voltage correction factor) for time battery voltage correction factor) and basic enable conditions met:	> 3.00 sec > 0.00 facto r < 4.00 facto r > 3.00 sec < 4.00 facto r > 3.00 sec < 4.00 facto r > and facto r > and facto r > and facto r		
Reductant Purge Valve High Control Circuit High Voltage	P1046		Voltage high during driver off state (indicates short to power)		for time and battery voltage for time and battery time and battery time and battery voltage for time and battery voltage for time and	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					(battery voltage correction factor and battery voltage correction factor) for time battery voltage correction factor) for time and basic enable conditions met:	> 0.00 facto r < 4.00 facto r > 3.00 sec < 4.00 facto r > 3.00 sec = see sheet enable tables		
Reductant Injector High Control Circuit Low Voltage	P1048	Diagnoses the Reductant Injector high side driver circuit for circuit faults.	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	for time and battery voltage for time and battery time and battery voltage for time and battery voltage for time and	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					battery voltage correction factor and battery voltage correction factor	> 0.00 facto r < 4.00 facto r		
					for time battery voltage correction factor	> 3.00 sec < 4.00 facto r		
					for time and basic enable conditions met:	> 3.00 sec = see sheet - enable tables		
Reductant Injector High Control Circuit High Voltage	P1049	Diagnoses the Reductant Injector high side driver circuit for circuit faults.	Voltage high during driver off state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
					for	1.00		
					time and	> 1.00 sec		
					battery voltage for	> 11.00 V		
					time and	> 3.00 sec		
					battery voltage for	< 655.34 V		
					time and	> 3.00 sec		
					(battery voltage correction factor	> 0.00 facto		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and battery voltage correction factor) for time battery voltage correction factor) for time and basic enable conditions met:	< 4.00 facto r > 3.00 sec < 4.00 facto r > 3.00 sec < 4.00 facto r > 3.00 sec = see sheet enable tables		
Fuel Rail Pressure Performance	P1089	Measured rail pressure is checked against desired rail pressure to detect high rail pressure conditions in fuel cut- off	rail pressure deviation from setpoint calculated as the absolute value of difference between desired and actual value	> 5000.00 kPa	rail pressure control commanded during injection timing correction learning phase and NO Pending or Confirmed DTCs limiting rail pressure set point for time and basic enable conditions met:	= TRUE - = see sheet - inhibit tables > 2.00 sec = see sheet - enable tables	fail conditions exists for 720 crank revolutions monitor runs with 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Exhaust Aftertreatment Fuel Injector Control Circuit Shorted	P10CC	Diagnoses the Exhaust Aftertreatment Fuel Injector low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for more than 5 events monitor runs with 0.1 s rate whenever enable conditions are met	В
					for time and battery voltage for time and starter is active cranking for time and Diesel dosing valve: fuel injection and basic enable conditions met:	> 1.00 sec > 11.00 V > 3.00 sec = FALSE - > 3.00 sec = ACTIVE - = see sheet - enable tables		
Exhaust Aftertreatment Fuel Injector High Control Circuit Low Voltage	P10CD	Electronic out-put driver circuitry determines circuit integrity on the diesel dosing valve control circuit.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		engine pre drive for time and battery voltage for time and	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec	fail conditions exists for more than 30 events monitor runs with 0.1 s rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Gystem	Gode	Description	Official	Logic and Value	starter is active cranking for time and Diesel dosing valve: fuel injection and basic enable conditions met:	= FALSE - > 3.00 sec = ACTIVE - = see sheet - enable tables	required	mum.
Exhaust Aftertreatment Fuel Injector High Control Circuit High Voltage	P10CE	Diagnoses the Exhaust Aftertreatment Fuel Injector high side driver circuit for circuit faults.	Voltage high during driver off state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and battery voltage for time and starter is active cranking for time and Diesel dosing valve: fuel injection and basic enable conditions met:	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec = FALSE - > 3.00 sec = ACTIVE - = see sheet - enable tables	fail conditions exists for more than 30 events monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	;	Required	Illum.
Charge Air Cooler Temperature Sensor Performance	P10CF	Detects a biased charge air cooler temperature sensor downstream or charge air cooler temperature sensor upstream by comparing the respective values at startup.	Path 1:				minimum engine-off time	>=	28800.00	sec	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate whenever enable conditions are met	В
			(a) - (b) (see Look- Up-Table #3) with (a) captured charge air cooler	>	100 to 999 measured parameter	°C	and ambient temperature and	>	-60.04	°C		
			downstream temperature at start and with (b) captured charge air cooler upstream temperature at start	=	measured parameter	-	engine speed (see Look-Up- Table #91) for	>	600 to 850	rpm		
			or Path 2: (100 45	°C	time and engine post drive/ afterun and diagnostic performed in current dc	> = =	0.00 FALSE FALSE	sec - -		
			(a) - (b) (see Look- Up-Table #3) with	<=	100 to 999	°C	and basic enable conditions met:	=	see sheet enable tables	-		
			(a) captured charge air cooler downstream temperature at start and with	=	measured parameter	-	and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary	Enable	Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters	Conditions	Required	Illum.
			(b) captured charge air cooler upstream temperature at start	=	measured parameter	-				
			and (a) - (b) (see Look- Up-Table #6) with	>	35 to 999	°C				
			(a) captured charge air cooler downstream temperature at start	=	measured parameter	-				
			and with (b) captured charge air cooler upstream temperature at start	=	measured parameter	-				
			and (status of block heater	=	FALSE	_				
			(see parameter definition) status of sun-load detection (see parameter definition))	=	FALSE	-				
				_						
Reductant Injector Temperature - Exhaust Gas Temperature 2 Correlation	P10D0	Detects an implausible SCR dosing valve coil temperature by comparing the temperature with a reference temperature	Up-Table #90)	>	30 to 3276.7 calculated parameter	°C °C	ignition on and state of selective catalytic reduction system	= TRUE - = STANDB - Y or NO PRESSU	fail conditions exists for 0.1 s monitor with 0.1 s rate whenever enable conditions are met	В
			and with				and	RE CONTRO L		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			(b) oxidation catalyst downstream temperature	= measured °C parameter	active heating phase for dosing valve	= FALSE -		
					valve already activated within this driving cycle	= FALSE -		
					and battery voltage and	> 11.00 V		
					ambient temperature and	>= -60.04 °C		
					engine run time and	< 10.00 sec		
					engine off time and urea pump motor output	> 28800.00 sec = 0.00 %		
					duty cycle and	- 0.00 /6		
					Max [(a), (b)] - Min [(a), (b)] where	<= 7.00 °C		
					(a) ambient temperature	= measured - parameter		
					(b) oxidation catalyst downstream temperature	= measured - parameter		
					and urea dosing valve output duty cycle and	> 3.00 %		
					coil current measurement is valid	= TRUE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	liue	Parameters		Conditions		Required	Illum.
Fuel Temperature Sensor 1 Circuit High	P111F	Detects an error in the fuel pump temperature sensor performance by comparing start-up temperatures between fuel pump temperature and fuel rail temperature					minimum engine-off time	>=	28800.00	sec	fail conditions exists for 0.2 s monitor runs once per trip with 0.2 s rate whenever enable conditions are met	В
			(a) - (b) (see Look- Up-Table #41) where	>	100 to 999	°C	and					
			((a) captured fuel temperature 1 at start	=	measured parameter	-	ambient temperature and	>	-60.04	°C		
			and with	=	measured		engine speed (see Look-Up- Table #91) for	>	600 to 850	rpm		
			(b) captured fuel temperature 2 at start	_	parameter	-	101					
)				time and	>	0.00	sec		
			or Path 2:				engine post drive/ afterun and	=	FALSE	-		
			(a) - (b) (see Look- Up-Table #41) with	<=	100 to 999	°C	diagnostic performed in current dc and	=	FALSE	-		
			(a) captured fuel temperature 1 at start	=	measured parameter	-	basic enable conditions met:	=	see sheet enable tables	-		
			and with (b) captured fuel temperature 2 at start	=	measured parameter	-	and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
			and (a) - (b) (see Look- Up-Table #42)	>	20 to 999	°C						

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
			where (a) captured fuel temperature 1 at start	=	measured parameter	-						
			and with (b) captured fuel temperature 2 at start	=	measured parameter	-						
			and (status of block heater (see parameter definition)	=	FALSE	-						
HO2S Performance - Signal High During Moderate Load Bank 1 Sensor 1	P11A6		Pressure compensated O2 concentration	>	(a) + (b)	factor	engine speed	<	2600.00	rpm	fail conditions exists for more than 2 event monitor runs with 0.1 s rate	В
			where				engine speed	>	1200	rpm	whenever enable	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	6	Required	Illum.
		•	(a) Filtered calculated O2 concentration based on injection quantity, air mass and fuel density	II	Please see the general descriptio n for details of this calculated O2 concentra	factor	Inner combusted quantity	<	180.00	mm^ 3/rev	conditions are met	
			(b) Positive O2 concentration margin	=	tion 0.05	factor	Inner combusted quantity	>	108.00	mm^ 3/rev		
							Air mass per cylinder Air mass per cylinder Status of binary lambda	>	4.20 2.20	g/rev g/rev		
							signal valid	=	TRUE	_		
							for time	>	0.50	sec		
							oxidation catalyst upstream temperature	<	999.96	°C		
							oxidation catalyst upstream temperature	>	99.96	°C		
							integrated air mass since all other release conditions are fulfilled for O2 plausibility	>	2.5	g		
							battery voltage	>	11.00	V		
							Fuel volume in fuel tank	>	-1638.40	I		
							Deceleration fuel cut-off Injection active	=	FALSE TRUE	-		
							calculated oxygen	<=	(a) + (b)	facto		
							concentration			r		
							calculated oxygen concentration	>=	(a) - (b)	facto r		
							where			'		
							(a) random start	=	measure	facto		
							calculated Oxygen concentration		variable	r		
							(b) tolerance range of calculated Oxygen	=	0.02	facto r		
							concentration for time	>	0.10	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Thr	eshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic	and Value	Parameters		Conditions	S	Required	Illum.
						Engine operation mode (Please see the definition) engine speed	= <	normal operation 4500.00	- rpm		
						engine speed ambient temperature ambient temperature ambient pressure ambient pressure NO Pending or Confirmed DTCs: basic enable conditions met:	>	600.00 122.96 -45.04 110.00 74.80 see sheet inhibit table see sheet enable tables			
HO2S Performance - Signal Low During Moderate Load Bank 1 Sensor 1	P11A9	•	Pressure compensated O2 concentration	< (a) -	(b) factor	engine speed	<	2600.00	rpm	fail conditions exists for more than 2 event monitor runs with 0.1 s rate	В
			where			engine speed	>	1200	rpm	whenever enable	
			(a) Filtered calculated O2 concentration based on injection quantity, air mass and fuel density	= Plea see gene descr n fo detail thi calcul O2 conce	the eral iptio or is of s ated 2 entra	Inner combusted quantity	<	180.00	mm^ 3/rev	conditions are met	
			(b) Positive O2 concentration margin	= 0.0		Inner combusted quantity	>	108.00	mm^ 3/rev		
						Air mass per cylinder Air mass per cylinder Status of binary lambda signal valid for time	< > = >	4.20 2.20 TRUE 0.50	g/rev g/rev - sec		

		Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System Co	ode	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
		·			oxidation catalyst upstream temperature oxidation catalyst upstream temperature integrated air mass since all	< >	999.96 99.96 2.5	°C °C g		
					other release conditions are fulfilled for O2 plausibility battery voltage Fuel volume in fuel tank Deceleration fuel cut-off Injection active calculated oxygen concentration calculated oxygen concentration where (a) random start calculated Oxygen concentration (b) tolerance range of calculated Oxygen concentration for time Engine operation mode (Please see the definition) engine speed ambient temperature ambient pressure ambient pressure NO Pending or Confirmed DTCs: basic enable conditions met:	^ ^	11.00 -1638.40 FALSE TRUE (a) + (b) (a) - (b) measure variable	V I - facto r facto r		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	•	Required	Illum.
HO2S Performance - Signal High During Moderate Load Bank 1 Sensor 2	P11AF	Compare the pressure compensated O2	compensated O2 concentration	>	(a) + (b)	factor	engine speed	<	2600.00	rpm	fail conditions exists for more than 2 event monitor runs with 0.1 s rate	В
			where				engine speed	>	1200	rpm	whenever enable	
			(a) Filtered calculated O2 concentration based on injection quantity, air mass and fuel density	=	Please see the general descriptio n for details of this calculated O2 concentra tion	factor	Inner combusted quantity	<	180.00	mm^ 3/rev	conditions are met	
			(b) Positive O2 concentration margin	=	0.05	factor	Inner combusted quantity	>	108.00	mm^ 3/rev		
			a.g				Air mass per cylinder Air mass per cylinder Status of binary lambda	>	4.20 2.20	g/rev g/rev		
							signal valid	=	TRUE	-		
							for time SCR downstream temperature	> <	0.50 999.96	°C		
							SCR downstream temperature	>	99.96	°C		
							integrated air mass since all other release conditions are fulfilled for O2 plausibility	>	2.5	g		
							battery voltage	>	11.00	٧		
							Fuel volume in fuel tank	>	-1638.40	I		
							Deceleration fuel cut-off Injection active	=	FALSE TRUE	-		
							calculated oxygen	<=	(a) + (b)	facto		
							concentration			r		
							calculated oxygen	>=	(a) - (b)	facto		
							concentration where			r		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshol		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and V	alue	Parameters	Conditions	Required	Illum.
						(a) random start calculated Oxygen concentration (b) tolerance range of calculated Oxygen concentration for time Engine operation mode (Please see the definition) engine speed engine speed ambient temperature ambient pressure ambient pressure NO Pending or Confirmed DTCs: basic enable conditions met:	= measured parameter = 0.02 factor r > 0.10 sector normal parameter > 0.10 sector normal parameter > 600.00 rpm > 600.00 rpm > 600.00 rpm > 122.96 °C > -45.04 °C < 110.00 kPator > 74.80 kPator = see sheet parameter inhibit table = see sheet parameter enable tables		
HO2S Performance - Signal Low During Moderate Load Bank 1 Sensor 2	P11B2	Compare the pressure compensated O2 concentration sensor signal with a threshold	Pressure compensated O2 concentration where (a) Filtered calculated O2 concentration based on injection quantity, air mass and fuel density	 (a) - (b) Please see the general descriptio n for details of this calculated O2 concentra tion 	factor	engine speed engine speed Inner combusted quantity	< 2600.00 rpm > 1200 rpm < 180.00 mm/ 3/rev	exists for more than 2 event monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Parameters Inner combusted quantity Air mass per cylinder Air mass per cylinder Status of binary lambda signal valid for time SCR downstream temperature SCR downstream temperature integrated air mass since all			
					other release conditions are fulfilled for O2 plausibility battery voltage Fuel volume in fuel tank Deceleration fuel cut-off Injection active calculated oxygen concentration calculated oxygen concentration where (a) random start calculated Oxygen	> 11.00 V > -1638.40 I = FALSE - = TRUE - <= (a) + (b) facto r >= (a) - (b) facto r = measured - parameter		
					concentration (b) tolerance range of calculated Oxygen concentration for time Engine operation mode (Please see the definition) engine speed engine speed ambient temperature ambient temperature ambient pressure ambient pressure NO Pending or Confirmed DTCs:	= 0.02 facto r > 0.10 sec = normal - operation < 4500.00 rpm > 600.00 rpm < 122.96 °C > -45.04 °C < 110.00 kPa > 74.80 kPa = see sheet - inhibit table		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				-	basic enable conditions met:	= see sheet - enable tables		
HO2S Current Performance Bank 1 Sensor 1	P11B4	valid lambda signal	ratio of valid lambda signal time to total time: (a) / (b) where (a) time for which valid lambda signal received over CAN (b) total time for which diagnosis is enabled	< 0.1 ratio = measured parameter = calculated parameter	NOx sensor's heater temperature has reached the set point for time Enabling Upstream NOx sensor heater diagnosis (please see the definition) Reciprocal lambda change: (a) - (b) (see Look-Up-Table #49) where (a) Reciprocal lambda (b) Filtered reciprocal lambda for time NO Pending or Confirmed DTCs: not disabled during following conditions	= TRUE - > 2.00 sec = TRUE - <= 0.1 to 10 facto r = measured - parameter = calculated - parameter > 5.00 sec = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for more than 60 sec monitor runs with 0.02 s rate whenever enable conditions are met	В
HO2S Current Performance Bank 1 Sensor 2	P11B5	Compares the ratio of valid lambda signal time to total time with a threshold	ratio of valid lambda signal time to total time: (a) / (b) where	< 0.1 ratio	NOx sensor's heater temperature has reached the set point for time	= TRUE - > 120.00 sec	fail conditions exists for more than 60 sec monitor runs with 0.02 s rate whenever enable	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		gic and Value	Parameters		Conditions		Required	Illum.
			(a) time for which valid lambda signal received over CAN		neasured - arameter	Enabling Downstream NOx sensor heater diagnosis (please see the definition)	=	TRUE	-	conditions are met	
			(b) total time for which diagnosis is enabled		alculated - arameter	Reciprocal lambda change : (a) - (b) (see Look-Up- Table #49)	<=	0.1 to 10	facto r		
						where (a) Reciprocal lambda	=	measured parameter	-		
						(b) Filtered reciprocal lambda	=	calculated parameter	-		
						for time NO Pending or Confirmed DTCs: not disabled during	> =	5.00 see sheet inhibit tables see sheet	sec -		
						following conditions	_	enable tables	-		
NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CB	Ŭ	Filtered NOx concentration deviation from model	>	0.70 -	Status of NOx signal of upstream NOx sensor (please see the definition)	=	TRUE	-	fault exists for more than 1 event; monitor runs at 0.1 s once per trip	В
						Normal Mode (Particulate Filter Regeneration not active)	=	TRUE	-		
						for time	>=	15.00	sec		
						ambient pressure ambient pressure	>= <=	75.00 106.00	kPa kPa		
						ambient pressure ambient temperature ambient temperature	>= <=	-7.04 37.96	°C		
						((filtered modeled Nox concentration percent	<=	0.050048 828125	%		
						positive deviation		0_0.20			

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
					filtered modeled Nox	>=	0.050048	%		
					concentration percent		828125			
					negative deviation					
)					
))					
					for time	>	2.00	sec		
					time since start	>	30.00	sec		
					Engine Coolant	>=	68.96	°C		
					Temperature					
					Engine Coolant	<=	104.96	°C		
					Temperature					
					Exhaust gas temperature	>0	0 to 1	facto		
					range at Upstream Nox			r		
					sensor (see Look-Up-Table					
					#81)					
					Fuel Injection pattern (see	=	0 to 58	patte		
					Look-Up-Table #82)			rn		
							24 = pilot			
							1 main			
							56 = pilot			
							2, pilot 1,			
							main			
							58 = pilot			
							2, pilot 1,			
							main,			
							post 2			
							26 = pilot			
							1 main,			
							post 2			
							0 = all off			
							(overrun)			
					Ratio of transient factor	>	0.95	facto		
								r		
					for time	>	0.50	sec		
					Vehicle speed	>=	37.29	mph		
					for time	>	1.00	sec		
					relative humidity	<=	100.00	%		
					relative humidity	>=	0.00	%		
					relative numicity	^=	0.00	70		
					Enable range for the	≠0	0 to 1	facto		
					plausibility check of	<i>+</i> ∪	0 10 1	iacio		
					Upstream Nox sensor (see			1		
1		l			Look-Up-Table #74)					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	- 1	Logic and V	alue	Parameters		Conditions	;	Required	Illum.
							for time Air mass per cylinder Air mass per cylinder for time actual valve position of	>	0.00 0.00 6.00 5.00 0.00	sec g/rev g/rev sec %		
							exhaust-gas recirculation actual valve position of exhaust-gas recirculation	<=	100.00	%		
							for time filtered modeled NOx- concentration upstream of the SCR	> >=	0.50 0.00	sec ppm		
							filtered modeled NOx- concentration upstream of the SCR	<=	1650.00	ppm		
							for time Diagnostic has not completed this driving cycle	> =	0.50 FALSE	sec -		
							NO Pending or Confirmed DTCs	=	see sheet inhibit tables			
							basic enable conditions met:	=	see sheet enable tables	-		
NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P11CC	<u> </u>	Filtered NOx concentration deviation from model	٧	(a) * (b)		Status of NOx signal of upstream NOx sensor (please see the definition)	=	TRUE	-	fault exists for more than 1 event; monitor runs at 0.1 s once per trip	В
			(a) Table for the base value of the lower plausibility limit (see Look-Up-Table #80)	=	-1 to -0.46	-	Normal Mode (Particulate Filter Regeneration not active)	=	TRUE	-		
			(b) Factor correction based on Environmental Pressure	=	1	factor	for time		15.00	sec		
							ambient pressure ambient pressure ambient temperature	>= <= >=	75.00 106.00 -7.04	kPa kPa °C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions	;	Required	Illum.
					ambient temperature	<=	37.96	°C		
					filtered modeled Nox	<=	0.05	facto		
					concentration percent			r		
					positive deviation					
					filtered modeled Nox	>=	0.05	facto		
					concentration percent			r		
					negative deviation					
))					
					for time	>	2.00	sec		
					time since start	>	30.00	sec		
					Engine Coolant	>=	68.96	°C		
					Temperature		40			
					Engine Coolant	<=	104.96	°C		
					Temperature Exhaust gas temperature	>0	0 to 1	facto		
					range at Upstream Nox		0 10 1	r		
					sensor (see Look-Up-Table					
					#81)					
					Fuel Injection pattern (see	=	0 to 58	patte		
					Look-Up-Table #82)			rn		
							24 = pilot			
							1 main 56 = pilot			
							2, pilot 1,			
							main			
							58 = pilot			
							2, pilot 1,			
							main,			
							post 2			
							26 = pilot 1 main,			
							post 2			
							0 = all off			
							(overrun)			
					Ratio of transient factor	>	0.95	facto		
							0.50	r		
					for time	>	0.50	sec		
					Vehicle speed for time	>=	37.29 1.00	mph sec		
					relative humidity	<=	100.00	%		
					relative humidity	>=	0.00	%		
					l					

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
- System	Code	Description	Ontena	Logic and value	Enable range for the plausibility check of Upstream Nox sensor (see Look-Up-Table #75) for time Air mass per cylinder Air mass per cylinder for time actual valve position of exhaust-gas recirculation actual valve position of	≠0 > >= <= > >=	0.00 0.00 0.00 6.00 5.00 0.00	facto r sec g/rev g/rev sec %	Required	mum.
					exhaust-gas recirculation for time filtered modeled NOx- concentration upstream of the SCR filtered modeled NOx- concentration upstream of the SCR for time	> >= <= >	0.50 0.00 1650.00 0.50	sec ppm ppm		
					Diagnostic has not completed this driving cycle NO Pending or Confirmed DTCs basic enable conditions:	=	see sheet inhibit tables see sheet enable tables			
Nox Sensor Current Performance Bank 1 Sensor 1	P11DB	Detects a failure of the feedback performance of upstream NoX sensor			Sufficient number of valid and invalid NOx status time (sum of valid and invalid Nox status for diagnostic determination) and Engine Running (see parameter definition) for time (required for the NOx sensor to give valid response) and	>= = >	20.00 TRUE 20.00	sec - sec	fault exists for more than 3 events; monitor runs at 0.1 s when enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	С	onditions		Required	Illum.
					Upstream NoX sensor detects a lean A/F mixture and Valid NOx signal from CAN is received (no Nox sensor communication failures)	=	TRUE	-		
					or following conditions for time:	>	45.00	sec		
					battery voltage	>=	11.00	V		
					battery voltage	<=	655.34	V		
					SCR upstream temperature	>=	94.96	°C		
					SCR upstream temperature	<=	3003.56	°C		
					Engine Running (see parameter definition)	=	TRUE	-		
					for time (required for the NOx sensor to give valid response)	>	20.00	sec		
					and Lambda signal is in steady state condition (see Look- Up-Table #28)	<=	0.1 to 10	-		
					for time Inhibit Status (no inhibiting faults) (No pending or stored DTC	>= =	5.00 see sheet inhibit tables	sec -		
					basic enable conditions met:	=	see sheet enable tables	-		
Nox Sensor Current Performance Bank1 Sensor 2	P11DC	feedback performance	Ratio of valid to invalid downstream Nox sensor status time count	> 0.90 ratio	Sufficient number of valid and invalid downstream NOx sensor status time (sum of valid and invalid Nox status for diagnostic determination) and Engine Running (see parameter definition)	>=	20.00 TRUE	sec	fault exists for more than 3 events; monitor runs at 0.1 s when enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Condition		Required	Illum.
					for time (required for the NOx sensor to give valid response) and	> 20.00	sec		
					Downstream NoX sensor detects a lean A/F mixture and	= TRUE	-		
					Valid NOx signal from CAN is received (no Nox sensor communication failures) or	= TRUE	-		
					following conditions for time:	> 120.00	sec		
					battery voltage battery voltage	>= 11.00 <= 655.34	V V		
					SCR downstream temperature	>= 94.96	°C		
					SCR downstream temperature	<= 3003.56	°C		
					Engine Running (see parameter definition)	= TRUE	-		
					for time (required for the NOx sensor to give valid response) and	> 20.00	sec		
					Downstream Lambda signal is in steady state condition (measured lambda signal - filtered lambda signal) (see Look-Up-Table #27)	<= 0.2 to 3.2	-		
					for time	>= 5.00	sec		
					Inhibit Status (no inhibiting faults) (No pending or stored DTC	= see shee inhibit tables	t -		
					basic enable conditions met:	= see shee enable tables	t -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Control Circuit Shorted	P1224		Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 2 Control Circuit Shorted	P1227		Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Control Circuit Shorted	P122A		Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE	- fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Intake Air Flow Valve Control Circuit Shorted	P122C	Electronic out-put driver circuitry determines circuit integrity on the intake air flow valve.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		for time and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and basic enable conditions met	= FALSE	V fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met sec - sec -	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters and NO Pending or Confirmed DTCs: and Open Load Diagnosis active	= see sheet - inhibit tables = FALSE -	Required	Illum.
Diesel Intake Air Flow Position Sensor Exceeded Learning Limit		Detects adaptation values of throttle valve that are not plausible. Compares the difference between the maximum and minimum adaptation values to a threshold.	out of difference between desired and	< -10.00 % > 10.00 %	and throttle valve is driven to a mechanical stop and offset learning for the throttle valve was successful in the previous driving cycle and engine post drive/ afterun and basic enable conditions met and NO Pending or Confirmed DTCs:	= FALSE - = FALSE - = TRUE - = see sheet - enable tables = see sheet - inhibit	fail conditions exists for 10.05 s monitor runs once per driving cycle with 0.005 s rate whenever enable conditions are met	В
		Detects implausible learned offset values.	Path 1:		(tables	fail conditions exists for 0.005	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and Va		Parameters		Conditions		Required	Illum.
			learned throttle valve offset position at open or closed position or	<	-20.00	%	engine temperature and	>=	4.96	°C	s monitor runs once per driving cycle with 0.005	
			learned throttle valve offset position at open or closed position or	>	20.00	%	engine temperature	<=	123.06	°C	s rate whenever enable conditions are met	
			Path 2: difference between the maximum and minimum positions learned at closed position	>	30.00	%	and (
			or Path 3 :				battery voltage	>=	8.00	V		
			difference between the maximum and minimum positions learned at open position	>	30.00	%	and					
			p = 0.0.0				battery voltage	<=	30.00	V		
							and Throttle Valve is not frozen consisting of: (
							charge air cooler downstream temperature or if	>=	5.06	°C		
							charge air cooler downstream temperature then	<	5.06	°C		
							charge air cooler downstream temperature for	>	6.06	°C		
							time) and		10.00	sec		
							engine speed and	=	0	rpm		
							engine post drive/ afterun and	=	TRUE	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Gystein	Oout	Bescription	Ontena	Eogie and Value	basic enable conditions met	= see sheet - enable tables	Required	mum.
Intake Air Flow Valve Control Circuit 2 Low Voltage	P122E		Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	for time and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and basic enable conditions met and NO Pending or Confirmed DTCs: and Open Load Diagnosis active	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec = ACTIVE - = see sheet - enable tables = see sheet - inhibit tables = FALSE -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Intake Air Flow Valve Control Circuit 2 High Voltage	P122F		Voltage high during driver off state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	battery voltage	> 11.00 V	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					for time and starter is active cranking for time Throttle Valve Actuator Solenoid Control Circuit and basic enable conditions met	> 3.00 sec = FALSE - > 3.00 sec = ACTIVE - = see sheet -		
					and NO Pending or Confirmed DTCs: and Open Load Diagnosis active	enable tables = see sheet - inhibit tables = FALSE -		
Injector 4 Control Circuit Shorted	P1233	,	Voltage low during driver on state (indicates short to ground)	= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 5 Control Circuit Shorted	P1236	driver circuit for circuit	driver on state	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 6 Control Circuit Shorted	P1239	Diagnoses the Injector Cylinder #6 high side driver circuit for circuit faults.	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Injector 7 Control Circuit Shorted	P1242	Cylinder #7 high side	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Injector 8 Control Circuit Shorted		driver circuit for circuit	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	Engine Running (see parameter definition)	= TRUE -	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Fuel Pressure Regulator 2 High Control Circuit Low Voltage	P125A	Diagnoses the Fuel Rail Pressure Regulator #2 high side driver circuit for circuit faults.		= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	battery voltage	> 11.00 V	fail conditions exists for 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	A
					for time and (ignition on and basic enable conditions met:)	> 3.00 sec = TRUE - = see sheet - enable tables		
Fuel Pressure Regulator 2 High Control Circuit High Voltage	P125B			= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and (ignition on and basic enable conditions met:	> 11.00 V > 3.00 sec = TRUE - = see sheet - enable tables	fail conditions exists for 0.1 s monitor runs with 0.1s rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Criteria	Logic and value	Farameters	Conditions	Required	mum.
Fuel Rail Pressure Performance	P128E	Actual rail pressure is compared to fixed absolute value to detect low or high rail pressure conditions.	rail pressure (see Look-Up-Table #67)	< 0 to kPa 15000	(fail conditions exists for 2 s monitor runs with 0.02 s rate whenever	А
					state machine rail pressure control transitioning pressure control valve mode	= TRUE -	enable conditions are met	
					or state machine rail pressure control transitioning to coupled pressure control mode (rail pressure is controlled by metering unit and pressure control valve) or	= TRUE -		
					state machine rail pressure control equal transitioning to metering unit pressure control mode) and	= TRUE -		
					basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
			rail pressure (see	< 0 to kPa	(
			Look-Up-Table #72)	15000	state machine rail pressure control equal to pressure control valve or	= TRUE -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			rail pressure (see Look-Up-Table #70)	< 0 to kP 15000	state machine rail pressure control equal coupled pressure control (rail pressure is controlled by metering unit and pressure control valve)) and basic enable conditions met: and NO Pending or Confirmed DTCs:	see sheet - enable tables see sheet - inhibit tables = TRUE - = see sheet - enable tables = see sheet - inhibit tables		
			rail pressure	> ####### kP	state machine rail pressure control transitioning pressure control valve mode or	= TRUE -	fail conditions exists for 1.01 s. monitor runs with 0.02 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters state machine rail pressure control transitioning to coupled pressure control mode (rail pressure is controlled by metering unit and pressure control valve)	Conditions = TRUE -	Required	Illum.
					or state machine rail pressure control equal transitioning to metering unit pressure control mode) and	= TRUE -		
					basic enable conditions met:	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
			rail pressure	> ######## kPa	(state machine rail pressure control equal to pressure control valve or	= TRUE -		
					state machine rail pressure control equal coupled pressure control (rail pressure is controlled by metering unit and pressure control valve)	= TRUE -		
					and basic enable conditions met:	= see sheet - enable tables		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
			rail pressure	>	215000	kPa	state machine rail pressure control equal to metering unit control mode and basic enable conditions met:	=	TRUE see sheet enable	-		
							and NO Pending or Confirmed DTCs:	=	tables see sheet inhibit tables	-		
Exhaust Gas Temperature Sensors 3-4 Not Plausible	P113A	Detects biased SCR catalyst temperature sensor by comparing SCR catalyst temperature sensor to the particulate filter temperature sensor after an engine off soak time	(a) - (b) (see Look- Up-Table #95)	>	30 to 999	°C	Power on reset by ignition on	=	TRUE	-	fail conditions exists for 0.01 s monitor runs with 0.01 s rate whenever enable conditions are met	В
			and with (a) captured downstream SCR catalyst temperature at start	=	measured parameter	-	Engine Running (see parameter definition) for time	= >	TRUE 0	sec		
			(b) captured downstream Particulate Filter catalyst temperature at start	=	measured parameter	-	Engine off soak time	>=	28800	sec		
							ambient temperature and NO Pending or Confirmed DTCs:	> =	-60.04 see sheet inhibit	°C -		
							basic enable conditions met:	=	tables see sheet enable tables	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshold ogic and Value		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
- Cystom		2000			gio ana valuo		, aramotore				rtoquiiou	
Exhaust Gas Recirculation (EGR) Motor Control Circuit Shorted	P1407	Electronic out-put driver circuitry determines circuit integrity on the EGR solenoid.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.				EGR Solenoid Control Circuit and battery voltage for time and starter is active cranking for time and basic enable conditions met:	- > - >	11.00 3.00 FALSE 3.00 see sheet enable tables	V sec - sec -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
Exhaust Gas Recirculation Slow Response- Increasing Flow	P140B	Detects a negative slow response by comparing expected system dynamics with actual value	average negative gradient of the air mass - calculated by accumulating control deviation (deviation between desired and actual value) over a sampling time and dividing result by sampling time	>	0.32 g/s	rev	ambient pressure and engine coolant temperature and EGR control is in closed loop for time and EGR control is active	> = > =	74.80 69.96 TRUE 1.50 TRUE	kPa °C - sec	fail conditions exists for 15 s monitor runs with 0.1s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					for time and exhaust gas system	> 0.00 sec = FALSE -		
					regeneration mode for time and	> 5.00 sec		
					Engine speed Engine speed	>= 1000.00 rpm <= 2200.00 rpm		
					and injection quantity	>= 80.00 mm^ 3/rev	,	
					injection quantity and	<= 300.00 mm^ 3/rev		
					desired delta air mass flow desired delta air mass flow and	> 0.13 g/s < -0.02 g/s		
					difference of the air mass and NO Pending or Confirmed	< 0 g/rev = see sheet -		
					DTCs:	= see sheet - inhibit tables		
					for time and	> 0.10 sec		
					basic enable conditions met:	= see sheet - enable tables		
Exhaust Gas Recirculation Slow Response- Decreasing Flow	P140C	slow response by comparing expected system dynamics with actual value	average positive gradient of the air mass - calculated by accumulating control deviation (deviation between desired and actual value) over a sampling time and dividing result by sampling time	>= -0.32 g/rev	(fail conditions exists for 15 s monitor runs with 0.1s rate whenever enable conditions are met	В
					ambient pressure and engine coolant temperature	> 74.80 kPa > 69.96 °C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and			
					EGR control is in closed	= TRUE -		
					loop			
					for time	> 1.50 se	ec	
					and			
					EGR control is active	= TRUE -		
					for time	> 0.00 se	ec	
					and			
					exhaust gas system	= FALSE -		
					regeneration mode			
					for time	> 5.00 se	ec	
					and			
					Engine speed	>= 1000.00 rp		
					Engine speed	<= 2200.00 rp	m	
					and			
					injection quantity	>= 80.00 mr		
						3/r		
					injection quantity	<= 300.00 mr		
						3/r	ev	
					and	0.40	/-	
					desired delta air mass flow	> 0.13 g/		
					desired delta air mass flow and	< -0.02 g/	S	
					difference of the air mass	< 0 g/r	.014	
					and	< 0 g/r	ev	
					NO Pending or Confirmed	= see sheet -		
					DTCs:	= see sheet - inhibit	·	
					DTCs.	tables		
						tabics		
					for time	> 0.10 se	^{2C}	
					and	0.10	,~	
					basic enable conditions	= see sheet -	. [
					met:	enable		
						tables		
						130,00		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Exhaust Gas Recirculation (EGR) Motor Control Circuit 2 Low Voltage	P140D		Voltage low during driver on state (indicates short to ground)	= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	EGR Solenoid Control Circuit	= ACTIVE -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and battery voltage for time and starter is active cranking for time and basic enable conditions met:	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec see sheet - enable tables		
Exhaust Gas Recirculation (EGR) Motor Control Circuit 2 High Voltage	P140E		Voltage high during driver off state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	EGR Solenoid Control Circuit	= ACTIVE -	fail conditions exists for 3 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and battery voltage for time and starter is active cranking for time and	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Gyotom		Возоприон	Ontona	Eogio una valac	basic enable conditions met:	see sheet - enable tables	rtoquilou	mam.
Exhaust Gas Recirculation (EGR) Motor Current Performance	P140F	Diagnoses the EGR Valve low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	EGR Solenoid Control Circuit	= ACTIVE -	fail conditions exists for 2 s monitor runs with 0.005 s rate whenever enable conditions are met	В
					and battery voltage for time and starter is active cranking for time and basic enable conditions met:	> 11.00 V > 3.00 sec = FALSE - > 3.00 sec see sheet - enable tables		
Closed Loop Diesel Particulate Filter (DPF) Regeneration Control At Limit - Stage 1 Temperature Too Low	P144B	Detects insufficient exhaust temperature. Actual inner controller ratio and temperature readings are compared to desired controller ratio and temperature values as an indication of an insufficient exhaust gas temperature.	commanded control value of the inner control loop of the temperature controller	>= 0.99 -	current engine operating point is suitable for monitoring deviation of exhaust gas temperature control - depending on engine speed and injection quantity (see Look-Up-Table #23)	= 0 to 1 -	fail conditions exists for 200 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Condition	S	Required	Illum.
			deviation from the temperature setpoint for inner control loop (with	>	maximum of (a) and (b)	-	time and release of the exhaust gas temperature outer loop control monitoring	=	0.00	sec -		
			(a) limitation of the temperature threshold and with (b) temperature threshold value for maximum deviation	=	100.00	°C	means (active operation mode of the inner control loop means	=	TRUE	-		
							(particulate filter regeneration and	=	TRUE	-		
							temperature before oxidation catalyst and temperature after particulate filter and (>	99.96	°C		
							temperature before oxidation catalyst and temperature after particulate filter or	<	649.96	°C		
							temperature before oxidation catalyst and temperature after particulate filter for activated post injection)	<	649.96	°C		
							and status maximum governor deviation means	=	TRUE	-		
							vehicle speed and	<=	124.30	mph		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	lue	Parameters		Conditions		Required	Illum.
							Relative accelerator pedal position for time and basic enable conditions met: and NO Pending or Confirmed DTCs:	> = =	3.00 1.00 see sheet enable tables see sheet inhibit tables	% sec		
Closed Loop Diesel Particulate Filter (DPF) Regeneration Control At Limit - Stage 1 Temperature Too High	P144C	Detects excessive exhaust temperature. Actual inner controller ratio and temperature readings are compared to desired controller ratio and temperature values as an indication of an excessive exhaust gas temperature.	commanded control value of the inner control loop of the temperature controller	<=	0.00	-	current engine operating point is suitable for monitoring deviation of exhaust gas temperature control - depending on engine speed and injection quantity (see Look-Up-Table #24)	=	0 to 1	-	fail conditions exists for 200 s monitor runs with 0.1 s rate whenever enable conditions are met	В
			and deviation from the temperature setpoint for inner control loop (with (a) limitation of the	<	minimum of (a) and (b)	- °C	for time and release of the exhaust gas temperature outer loop control monitoring means	>	0.00	sec		
			temperature threshold and with (b) temperature threshold value for minimum deviation	=	100	°C	(active operation mode of the inner control loop means (particulate filter regeneration	=	TRUE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and temperature before oxidation catalyst and temperature after particulate filter and	> 99.96 °C		
					temperature before oxidation catalyst and temperature after particulate filter or	< 649.96 °C		
					temperature before oxidation catalyst and temperature after particulate filter for activated post injection)) and	< 649.96 °C		
					status maximum governor deviation means	= TRUE -		
					vehicle speed and	<= 124.30 mph		
					Relative accelerator pedal position for	> 3.00 %		
					time and	> 1.00 sec		
					basic enable conditions met: and	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
TCM Engine Speed Request Signal Message Counter Incorrect	P150C	Detects implausible engine speed request information received from the TCM	Path 1:		ignition on	= TRUE -	fail conditions exists for 0.01 s test performed continuously	А

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and \	/alue	Parameters	C	onditions		Required 0.01 S	Illum.
			(number of rolling count / protection values detected with number of consecutive frames	>=	7.00	counts	and basic enable conditions met: and NO Pending or Confirmed DTCs:		see sheet enable tables see sheet inhibit tables	-	0.013	
			or Path 2: (internal calculated checksum value for transmission is not equal the received	=	TRUE	-			lables			
			value and number of fault results	>	15.00	counts						
) or Path 3: time since last frame of validation protection was received from	>	0.08	sec						
Validation Error in messages received from Power Take Off Control Module	P1591	Rolling counter and protection value evaluation of message received from Power Take Off Control Module	number of messages with validation errors	>=	4.00	counts	ignition on	=	TRUE	-	fail conditions exists for 0.12 s test performed continuously 0.01 s rate	Special C
			in the last number of messages (sliding window) received from power take off control module	=	10.00	counts	for time and	>=	3.00	sec		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Citteria	Logic and value	basic enable conditions met: and NO Pending or Confirmed DTCs:	= see sheet - enable tables = see sheet - inhibit tables	Requireu	mum.
Particulate filter efficiency monitoring	P2002	Statistical evaluation of the present exhaust gas volume flow signal and particulate filter delta pressure signal to determine particulate filter efficiency		> 0.35 -	Calculated exhaust-gas volume flow in the particulate filter	< 3000.00 m^3/ h	fail conditions exists for 0.1 s monitor runs with 0.1s rate whenever enable conditions are met	В
					and Calculated exhaust-gas volume flow in the particulate filter	> 600.00 m^3/ h		
					and Temperature upstream of the particulate filter and	< 799.96 °C		
					Temperature upstream of the particulate filter and	> 499.96 °C		
					Temperature downstream particulate filter and	< 799.96 °C		
					Temperature downstream particulate filter and	> 499.96 °C		
					Upstream and downstream particulate filter temperature difference	< 300.00 °C		
					and Upstream and downstream particulate filter temperature difference and	> -300.00 °C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions		Required	Illum.
					Simulated surface temperature, particulate filter and Simulated surface temperature, particulate filter and	< 799.96 > 499.96	°C		
					Basic enable conditions met	= see sheet enable tables	-		
					Number of segments filled with flow rate distributions for DPF efficiency regression analysis and	>= 3.00	coun ts		
					Sum of flow rate distribution for DPF efficiency regression analysis	>= 1.00	-		
Reductant Injector Performance	P202E	operation.		> 10.00 counts	Flag for successful measurement of current in opening phase of Reductant Injector	= TRUE	-	fault exists for more than 80 injection events; monitor runs with 100 ms rate whenever enable conditions are	А
					Reductant Dosing System Metering control substate of Pressure control state (see definition)	= TRUE	-	met	
					Calculated Reductant Injector coil temperature Calculated Reductant	>= -6.64 <= 99.96	°C		
					Injector coil temperature)	55.50	O		
					battery voltage	>= 11.00	V		
					battery voltage	<= 655.34	V		ı

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshold ogic and Val	ue	Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Gyotom		Dodonpuon	Ontonia) (Reductant Dosing System pump relative pressure Reductant Dosing System pump relative pressure) (ambient pressure ambient pressure) (NO Pending or Confirmed DTCs) (ambient pressure ambient pressure) the provided pressure ambient pressure ambient pressure ambient pressure ambient temperature) basic enable conditions met:	\	350.00 650.00 0.00 130.00 see sheet inhibit tables	kPa kPa kPa - kPa °C	roquilou	
Exhaust Gas Temperature (EGT) Sensor 2 Circuit Low Voltage	P2032	readings on the EGT 2 circuit, indicating an OOR low condition on the EGT 2 circuit	temperature sensor voltage downstream of oxidation catalyst same as temperature downstream of oxidation catalyst	<	- 50	v °c	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables		fail conditions exists for 3 s monitor runs 0.050 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	Required	Illum.
Exhaust Gas Temperature (EGT) Sensor 2 Circuit High Voltage	P2033	Detects high voltage readings on the EGT 2 circuit, indicating an OOR high condition on the EGT 2 circuit	temperature sensor voltage downstream of oxidation catalyst same as	>	2.21	V	ignition on	II	TRUE -	fail conditions exists for 3 s monitor runs 0.050 s rate whenever enable	A
			temperature downstream of oxidation catalyst	>	1000	°C	and basic enable conditions met:	=	see sheet - enable tables	conditions are met	
Reductant Level Sensor "A" Circuit Range/Performance	P203B	Reductant level plausibility check error from CAN	CAN message "Reductant Level Plausibility Check Error" from reductant tank level evaluation module	=	TRUE	-	ignition on	=	TRUE -	fail conditions exists for 5 s test performed continuously 1 s rate	В
			which means (and basic enable conditions met:	=	see sheet - enable tables		
			(measured tank level sensor 2 voltage after 1.5 ms since a test impulse was applied)	=	(0.0 to 1.7)	V	and		tables		
			(measured tank level sensor 1 voltage after 1.5 ms since a test impulse was applied)) or (=	(1.71 to 3.56)	V	NO Pending or Confirmed DTCs:	=	see sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction	Thresho		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and \		Parameters	Conditions	Required	Illum.
			(measured tank level sensor 3 voltage after 1.5 ms since a test impulse was applied) (measured tank level sensor 1 voltage after 1.5 ms since a test impulse was applied)) or	= (0.0 to 1.7) = (1.71 to 3.56)	V				
			(measured tank level sensor 3 voltage after 1.5 ms since a test impulse was applied)	= (0.0 to 1.7)	V				
			(measured tank level sensor 2 voltage after 1.5 ms since a test impulse was applied)	= (1.71 to 3.56)	V				
Reductant Level Sensor 1 Circuit Low	P203C	CAN message: Discrete level sensor level 1 short to ground error	Reductant Tank Level 1 Error Status	= 1	-	ignition on	= TRUE -	fail conditions exists for more than 3 sec. monitor runs	А
			(tank level sensor 1 voltage directly measured after a test impulse was applied)	< (0.17)	V	battery voltage	> 8 V	with 1 s rate whenever enable conditions are	
						basic enable conditions met:	= see sheet - enable tables	met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	l	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
Reductant Level Sensor 1 Circuit High	P203D	Path 1: CAN message: Discrete level sensor 1 open load error	Reductant Tank Level 1 Error Status	=	3	-	ignition on	=	TRUE	-	fail conditions exists for more than 3 sec. monitor runs with 1 s rate whenever	А
		open load error	(measured tank level sensor 1 voltage after 1.5 ms since a test impulse was applied)	>	(3.56)	V	battery voltage	>	8	V	enable conditions are met	
			(measured tank level sensor 1 voltage after 1.5 ms since a test impulse was applied)	<	(4.74)	V	basic enable conditions met:	=	see sheet enable tables	-		
		Path 2: CAN message: Discrete level sensor 1 short to battery error	Reductant Tank Level 1 Error Status	=	2	-	ignition on	=	TRUE	-		
			(measured tank level sensor 1 voltage after 1.5 ms since a test impulse was applied)	>	(4.74)	V	battery voltage	>	8	V		
							basic enable conditions met:	=	see sheet enable tables	-		
Reductant Injector Control Circuit	P2047	Diagnoses the Reductant Injector low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	=	Open Circuit:≥ 200 K Ω impedanc e between ECU pin and load		engine pre drive	=	FALSE	-	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
							for time and battery voltage for	>	1.00 11.00	sec V		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters		Conditions		Required	Illum.
					time and battery voltage for time and	> < >	3.00 655.34 3.00	sec V sec		
					(battery voltage correction factor and battery voltage correction	>	0.00 4.00	facto r facto		
					factor) for time and basic enable conditions met:	> =	3.00 see sheet enable tables	sec		
Reductant Injector Control Circuit Low Voltage	P2048	Diagnoses the Reductant Injector low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	engine pre drive	=	FALSE	-	fail conditions exists for 2 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
					for time and battery voltage for time and battery voltage for time and battery voltage for time and	>	1.00 11.00 3.00 655.34 3.00	sec V sec v		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Criteria	Logic and Value	(battery voltage correction factor and battery voltage correction factor) for time and basic enable conditions met:	> 0.00 facto r < 4.00 facto r > 3.00 sec = see sheet - enable tables		mum.
Reductant Injector Control Circuit High Voltage	P2049	Diagnoses the Reductant Injector low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to - power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
					for time and battery voltage for time and battery voltage for time and battery voltage for time and (battery voltage correction factor and battery voltage correction factor	> 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec > 0.00 factore < 4.00 factore		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	ı	Thresholo		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
		·) for time and basic enable conditions met:	> =	3.00 se see sheet - enable tables		
Reductant Pump Pressure Sensor Performance	P204B		Unfiltered Reductant Pump Module Pressure	^	50.00	kPa	Reductant filling state in the pressure line status of SCR control state (please see the definition) State of the defrosting check of pressure line (please see the definition) ambient pressure ambient temperature NO Pending or Confirmed DTCs: basic enable conditions met:	<= !! !! ^ ^ !! !!	No - Pressure Control TRUE - 0.00 kP -30.04 °C see sheet inhibit tables see sheet enable tables	exists for more than 0.6 sec monitor runs with 0.01 s rate whenever enable conditions are met	A
Reductant Pump Pressure Sensor Circuit Low	P204C	pump pressure sensor	Reductant pump pressure sensor signal same as: reductant pump pressure	<	0.41	V kPa	ignition on NO Pending or Confirmed DTCs: basic enable conditions met:	=	TRUE - see sheet - inhibit tables see sheet enable tables	fail conditions exists for more than 0.4 sec. monitor runs with 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
					_	_			_			
Reductant Pump Pressure Sensor Circuit High	P204D	Measured reductant pump pressure sensor signal high voltage	Reductant pump pressure sensor signal same as:	>	4.80	V	ignition on NO Pending or Confirmed	=	TRUE	-	fail conditions exists for more than 0.4 sec. monitor runs with 0.01 s rate	A
							DTCs:		inhibit tables		whenever enable	
			reductant pump pressure	>	800.00	kPa	basic enable conditions met:	=	see sheet enable tables	-	conditions are met	
										_		
Reductant System Performance Bank 1	P204F	Unsuccessful reductant pressure build up	Reductant Pump Module Pressure	<=	350.00	kPa	status of SCR control sub state (please see the definition) and	=	PRESSU RE BUILDUP	-	fail conditions exists for 1 event monitor runs with 0.1 s rate	А
							Reductant Defrost check (please see the definition) and	=	1.00	-	whenever enable conditions are met	
							ambient pressure and	>	0.00	kPa		
							ambient temperature and	>	-30.04	°C		
							number of pressure build-up attempts in pressure buildup and ventilation states with	>=	30.00	coun ts		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				-	(Dwell time in Pressure Build up substate Dwell time in ventilation substate) and	>= 10.00 sec >= 10.00 sec		
					Urea heater release reason	!= COMPON - ENT PROTEC TION		
					NO Pending or Confirmed DTCs: basic enable conditions met:	 see sheet - inhibit tables see sheet - enable tables 		
Reductant Tank Temperature Sensor Performance	P205B	difference between reductant tank temperature and diesel fuel temperature are compared to an upper threshold after sufficient engine-off	(a) - (b)	> 34.96 °C	ignition on	= TRUE -	fail conditions exists for more than 0.5 sec monitor runs with 0.01 s rate whenever enable conditions are met	В
		duration	where		status of SCR control state (please see the definition)	= No - Pressure control		

Component /	Fault	Monitor Strategy	Primary Malfunction	Thresh	old	Secondary		Enable	Time	MIL
System	Code	Description	Criteria	Logic and	Value	Parameters	С	onditions	Required	Illum.
			(a) Reductant tank temperature (b) fuel temperature	measured parametemeasured paramete	r d -	Engine off Time time since start	>	28800.00 sec 6.00 sec		
						Max [(a), (b), (c)] - Min [(a), (b), (c)] where (a) Oxidation Catalyst upstream temperature (b) fuel temperature (c) Particulate filter downstream temperature NO Pending or Confirmed DTCs: basic enable conditions met:	= ! = ! = !	6.96 °C measured parameter measured parameter measured parameter see sheet inhibit tables see sheet enable tables		
		Path 2: The temperature difference between reductant tank temperature and diesel fuel temperature are compared to a lower threshold after sufficient engine-off duration	(a) - (b) where	< -35.04	°C	ignition on status of SCR control state (please see the definition)		TRUE - No - Pressure control	fail conditions exists for more than 0.5 sec monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
			(a) Reductant tank temperature (b) fuel temperature		measured parameter measured parameter	-	time since start Max [(a), (b), (c)] - Min [(a), (b), (c)]	> <=	6.00 6.96	°C		
							where (a) Oxidation Catalyst upstream temperature (b) fuel temperature	=	measured parameter measured parameter	-		
							(c) Particulate filter downstream temperature	=	measured parameter	-		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables see sheet	-		
							basic enable conditions met:	_	enable tables	-		
Reductant Tank Temperature Sensor Circuit Low	P205C	Detects an out of range low reading of the Reductant Tank Temperature Sensor via CAN Message	Raw value of the CAN message for the Reductant Tank Temperature	<	1.00	hex	basic enable conditions met:	П	see sheet enable tables	-	fault exists for more than 3 seconds; monitor runs at 1 s whenever enable conditions are met	A
			Corresponds to a temperature of	<=	-55.0	°C	and					
			Corresponds to a resistance of	>=	1200	kOhm	No rolling count or protection value errors. (sliding window errors) in the CAN frame	=	TRUE	-		
			Corresponds to a voltage of	>=	5.0	V						

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		Logic and V	value	Parameters		Conditions	Required	Illum.
Reductant Tank Temperature Sensor Circuit High	P205D	Detects an out of range high reading of the Reductant Tank Temperature Sensor via CAN Message or an invalid (initialization) value of the Reductant Tank Temperature CAN message	Raw value of the CAN message for the Reductant Tank Temperature	>	1022.00	hex	basic enable conditions met:	=	see sheet - enable tables	fault exists for more than 6 seconds; monitor runs at 1 s whenever enable conditions are met	В
			Corresponds to a temperature of	>=	160.0	°C	and				
			Corresponds to a resistance of	<=	0.153	kOhm	No rolling count or protection value errors. (sliding window errors) in the CAN frame	=	TRUE -		
			Corresponds to a voltage of	<=	0.270	V	une o/ uv marine				
			OR Path2: Raw value of the CAN message for the Reductant Tank Temperature	=	0x3FF	hex					
Exhaust	P2080	Detects a fault in the	integrated heat	<	(a) / (b) *	-	exhaust gas system	=	FALSE -	fail conditions	В
Temperature Sensor 1 Performance		exhaust temperature sensor 1 performance by comparing the heat quantity on the sensor position to a threshold.	quantity of exhaust gas temperature sensor 1		(c) / (d) * (e) * (f)		regeneration mode			exists for xxs monitor runs with 0.1 s rate whenever enable	
			or integrated heat quantity of exhaust gas temperature sensor 1 with	>	(a) / (b) * (c) / (d) * (e) * (g)	-	for time	>	1500.00 sec	conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions		Required	Illum.
		·	(a) exhaust gas mass flow		calculated parameter	-	time since start	>	327.00	sec		
			and with (b) factor and with	=	3.600	g/s	and (exhaust-gas temperature sensor 1	>	-60.04	°C		
			(c) heat capacity and with	=	1050.00	J/Kg/°C	and exhaust-gas temperature sensor 1	<	1999.96	°C		
			(d) factor and with	=	1000	kW/°C) and					
			(e) correction factor for heat flow quantity depending on exhaust gas mass flow for temperature sensor 1	=	1.00	factor	change in exhaust-gas temperature sensor 1	<	7.00	°C		
			and with (f) minimum permissible temperature deviation for exhaust gas temperature sensor	=	-100.00	°C	for time and	=	5.00	sec		
			1 and with				engine operation point suitable for diagnostic (see Look-Up-Table #29)	=255	0 to 255	-		
			(g) maximum permissible temperature deviation for exhaust gas temperature sensor	=	100.00	°C	for					
							time and	>=	0.05	sec		
							change in modeled exhaust- gas temperature sensor 1 and	>	4.00	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	ue	Parameters /		Conditions		Required	Illum.
							heat quantity for exhaust gas temperature sensor 1 and heat quantity for exhaust gas temperature sensor 1	>	10.00	kJ kJ		
) and engine has been in normal mode for time or	>=	1.00	sec		
							engine has been in exhaust warm-up mode for time	>=	1.00	sec		
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
						_						
Exhaust Temperature Sensor 2 Performance	P2084		integrated heat quantity of exhaust gas temperature sensor 2	<	(a) / (b) * (c) / (d) * (e) * (f)	-	exhaust gas system regeneration mode	=	FALSE	-	fail conditions exists for xxs monitor runs with 0.1 s rate whenever enable	В
			or integrated heat quantity of exhaust gas temperature sensor 2	>	(a) / (b) * (c) / (d) * (e) * (g)	-	for time	>	1500.00	sec	conditions are met	
			with (a) exhaust gas mass flow	=	calculated parameter	-	and time since start	>	327.00	sec		
			and with (b) factor and with	=	3.600	g/s	and (exhaust-gas temperature sensor 2	>	-60.04	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters		Conditions	,	Required	Illum.
- System	0.000		(c) heat capacity	=	1050.00	J/Kg/°C						
			and with				exhaust-gas temperature sensor 2	<	1999.96	°C		
			(d) factor and with	=	1000	kW/°C) and					
			(e) correction factor for heat flow quantity depending on exhaust gas mass flow for temperature sensor 2	II	1.00	factor	change in exhaust-gas temperature sensor 2	V	7.00	°C		
			and with				for time	_	F 00	200		
			and with (f) minimum permissible temperature deviation for exhaust gas temperature sensor	П	-100.00	°C	time and	=	5.00	sec		
			2 and with				engine operation point suitable for diagnostic (see Look-Up-Table #29)	=	0 to 255	-		
			(g) maximum permissible temperature deviation for exhaust gas temperature sensor 2	II	100.00	°C	for					
							time and	>=	0.05	sec		
							change in modeled exhaust- gas temperature sensor 2 and	>	4.00	°C		
							heat quantity for exhaust gas temperature sensor 2 and	>	10.00	kJ		
							heat quantity for exhaust gas temperature sensor 2)	<	12.00	kJ		
							and					

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	>= 1.00 sec	Required	Illum.
					engine has been in normal mode for time or engine has been in exhaust warm-up mode for time and	>= 1.00 sec		
					basic enable conditions met: and	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Reductant Pump Control Circuit	P208A	Detects an open circuit or an overtemperature condition in the Reductant Pump Control Circuit	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedanc e between ECU pin and load	((fail conditions exists for 6.2 s monitor runs with 0.010 s rate whenever enable conditions are met	В
			Voltage high during driver off state (open circuit)	= Open - Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground	Battery voltage for time OR	< 10.5 V < 3 sec		
					Battery voltage)) ((> 11 V		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshologic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
							SCR system waiting for shut down in afterrun OR SCR system in standby in afterun) ignition) NO Pending or Confirmed DTCs basic enable conditions met:	= = =	TRUE TRUE FALSE see sheet inhibit tables see sheet enable tables			
Reductant Pump Performance		the commanded state of the Reductant Pump driver and the actual state of the control circuit do not match.	timer for functional acknowledgement of the reductant pump motor timer for functional acknowledgement of the reductant pump motor	> <=	4.00 6.00	sec	ambient pressure ambient temperature) basic enable conditions met:	> =	0.00 -30.04 see sheet enable tables	kPa °C -	fault exists for more than 30 s; monitor runs at 0.1 s whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value = Short to -	Parameters	Conditions = FALSE -	Required	Illum.
Reductant Pump Control Circuit High Voltage	P208D	Reductant Pump	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
					for time and battery voltage for time and battery voltage for time and battery voltage for time and (battery voltage correction factor and battery voltage correction factor) for time and basic enable conditions met:	> 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec > 0.00 facto r < 4.00 facto r > 3.00 sec = see sheet enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Reductant Purge Valve Control Circuit	P20A0	Diagnoses the Reductant Purge Valve low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open Circuit:≥ 200 K Ω impedanc e between ECU pin and load	for time and battery voltage for time and battery voltage for time and battery voltage for time and (battery voltage correction factor and battery voltage correction factor) for time and basic enable conditions met:	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec > 0.00 facto r < 4.00 facto r > 3.00 sec = see sheet enable tables	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
Reductant Purge Valve Performance	P20A1	This diagnostic checks the Reductant Purge valve performance during operation by detecting a lack of reduction of the reductant pressure		< 50.00 kPa	(fault exists for more than 1 event monitor runs with 100 ms rate whenever enable conditions are	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Cinteria		Reductant Dosing System state pressure reduction Reductant Dosing System pump relative pressure to initiate test) AND	= TRUE - >= 350.00 kPa	met	mum.
					Time attempting to reduce dosing pressure AND	>= 5.00 sec		
					Reductant Dosing System pump relative pressure after attempting to reduce pressure) OR	> 50.00 kPa		
					Reductant Dosing System pump relative pressure after attempting to reduce pressure	<= 50.00 kPa		
					ambient pressure ambient temperature	> 0.00 kPa > -100.04 °C		
					NO Pending or Confirmed DTCs basic enable conditions met:	= see sheet - inhibit tables = see sheet - enable tables		

Component / Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Reductant Purge P20A2 Valve Control Circuit Low Voltage	Diagnoses the Reductant Purge Valve low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to - ground: ≤ 0.5 Ω impedanc e between signal and controller ground	engine pre drive	= FALSE -	fail conditions exists for 2 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
				for time and battery voltage for time and battery voltage for time and battery voltage for time and (battery voltage correction factor and battery voltage correction factor) for time and basic enable conditions met:	> 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec > 0.00 facto r < 4.00 facto r > 3.00 sec = see sheet enable tables		

Component / Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Reductant Purge P20A3 Valve Control Circuit High Voltage	Diagnoses the Reductant Purge Valve low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	engine pre drive	= FALSE -	fail conditions exists for 3 s monitor runs with 0.01 sec rate whenever enable conditions are met	A
				for time and battery voltage for time and battery voltage for time and battery voltage for time and (battery voltage correction factor and battery voltage correction factor) for time and basic enable conditions met:	> 1.00 sec > 11.00 V > 3.00 sec < 655.34 V > 3.00 sec > 0.00 facto r < 4.00 facto r > 3.00 sec = see sheet enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	gic and Value	Parameters		Conditions		Required	Illum.
Exhaust Aftertreatment Fuel Injector Control Circuit	P20CB	Electronic output driver circuitry determines circuit integrity on the exhaust aftertreatment fuel injector control circuit.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.			for time and battery voltage for time and starter is active cranking for time and starter is active cranking for time and basic enable conditions met:	- > > = > =	1.00 11.00 3.00 FALSE 3.00 see sheet enable tables	sec V sec - sec	fail conditions exists for more than 30 events monitor runs with 0.1 s rate whenever enable conditions are met	В
Exhaust Aftertreatment Fuel Injector Performance	P20CC	Detects high exhaust temperatures in order to protect the engine	oxidation catalyst downstream temperature - oxidation catalyst upstream temperature OR particulate filter downstream temperature - SCR downstream temperature	>	300 °0	oxidation catalyst upstream temperature change for time) and (time since last successful regeneration) and	< > >	50.00 10.00 900.00	°C sec	fail conditions exists for 180 s test performed continuously 0.1 s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters ((Normal Mode (Particulate	Conditions = TRUE -	Required	Illum.
					Filter Regeneration not active) or Exhaust Gas Temperature	= TRUE -		
					(Active) Management Mode)			
					for time) and	> 300.00 sec		
					time since the end of the last tip cleaning request of the Exhaust Aftertreatment Fuel Injector	> 300.00 sec		
					AND basic enable conditions met: AND	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
5 h	Page		The FOM to to the the			EALOE	6.21 120	
Exhaust Aftertreatment Fuel Injector Control Circuit Low Voltage	P20CD	determines circuit integrity on the exhaust aftertreatment	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		engine pre drive	= FALSE -	fail conditions exists for more than 30 events monitor runs with 0.1 s rate whenever enable conditions are	В
					time	> 1.00 sec	met	
					and battery voltage for	> 11.00 V		
					time	> 3.00 sec		
					and starter is active cranking for	= FALSE -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		·		J	time and basic enable conditions met: and Diesel dosing valve: fuel injection	> 3.00 sec = see sheet - enable tables = INACTIVE -		
Exhaust Aftertreatment Fuel Injector Control Circuit High Voltage	P20CE	Diagnoses the Exhaust Aftertreatment Fuel Injector low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and battery voltage for time and starter is active cranking for time and basic enable conditions met:	= FALSE - > 1.00 sec > 11.00 V > 3.00 sec = FALSE - > 3.00 sec = see sheet - enable tables	fail conditions exists for more than 30 events monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions		Required	Illum.
Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P20E2	Detects biased exhaust temperature sensors by comparing the upstream and downstream oxidation catalyst temperature sensors after a calibrated engine off soak time	Path 1:				minimum engine-off time	>=	28800.00	sec	fail conditions exists for 0.050 s monitor runs with 0.050 s rate whenever enable conditions are met	В
			(a) - (b) (see Look- Up-Table #30) with (a) captured oxidation catalyst downstream temperature at start and with	> =	100 to 999 measured parameter	°C -	and ambient temperature and Engine Running (see	> =	-60.04 TRUE	°C		
			(b) captured oxidation catalyst upstream temperature at start as reference temperature	=	measured parameter	-	parameter definition) for					
			or Path 2: (time and engine post drive/ afterun	> =	0.00 FALSE	sec -		
			(a) - (b) (see Look- Up-Table #30) with	<=	100 to 999	°C	and diagnostic performed in	_	FALSE			
			(a) captured oxidation catalyst downstream temperature at start and with	=	measured parameter	-	current dc and basic enable conditions met:	=	see sheet enable tables	-		
			(b) captured oxidation catalyst upstream temperature at start as reference temperature	=	measured parameter	-	and		<i>asios</i>			

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions	;	Required	Illum.
			and (a) - (b) (see Look-Up-Table #31) with (a) captured oxidation catalyst downstream temperature at start and with (b) captured oxidation catalyst upstream temperature at start as reference temperature and status of block heater	= =	30 to 999 measured parameter measured parameter	°C -	NO Pending or Confirmed DTCs:	П	see sheet inhibit tables			
Delivery performance bank 1	P20E8	Compare Reductant tank pressure with lower thresholds under metering control	Reductant Pump Module Pressure	<	400.00	kPa	status of SCR control sub state (please see the definition) status byte in substate METERING CONTROL Dwell time in Metering control substate ambient pressure ambient temperature NO Pending or Confirmed DTCs: basic enable conditions met:	=	Metering control Running 1.00 0.00 -30.04 see sheet inhibit tables see sheet enable tables	sec kPa °C -	fail conditions exists for more than 60.0 s monitor runs with 0.1 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable Conditions	,	Time Required	MIL Illum.
Reductant System Performance Bank 1	P20E9		Reductant Pump Module Pressure	>	650.00	kPa	status of SCR control sub state (please see the definition) status byte in substate METERING CONTROL Dwell time in Metering control substate ambient pressure ambient temperature NO Pending or Confirmed DTCs: basic enable conditions met:	= > >= = =	Metering control Running 1.00 0.00 -30.04 see sheet inhibit tables see sheet enable tables		fail conditions exists for more than 10 s monitor runs with 0.1 s rate whenever enable conditions are met	A
			Unfiltered Reductant Pump Module Pressure	>=	795.00	kPa	ambient pressure ambient temperature basic enable conditions met:	> =	0.00 -30.04 see sheet enable tables	kPa °C -	fail conditions exists for more than 1 s monitor runs with 0.1 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions		Required	Illum.
SCR Nox Catalyst Efficiency Below Threshold Bank 1	P20EE	Compare EWMA filtered NOx conversion efficiency of SCR catalyst with a threshold value	EWMA filtered delta SCR catalyst efficiency of (a) - (b) where (a) measured SCR catalyst efficiency	=	0.00 calculated parameter	factor -	NO Pending or Confirmed DTCs: for time	>	see sheet inhibit tables 300.00	sec	fail conditions exists for more than 1 event monitor runs with 0.01 s rate whenever enable conditions are met	A
			(b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	=	calculated parameter	-	Status of NOx signal of upstream NOx sensor (please see the definition)	=	Active	-		
			io. Gotano,				for time Status of NOx signal of downstream NOx sensor (please see the definition) for time	> =	60.00 Active	sec - sec		
							(Release of dosing strategy (please see the definition) for time (a) Turn on delay time 1 of status metering strategy (b) Turn on delay time 2 of status metering strategy)	= >=	TRUE (a) + (b) 380.00	sec sec		
							(Status for disabling SCR Efficiency monitoring following an SCR Adaptation completion (please see the definition) for time (a) Debounce time after pre controlled dosing over	= > >	(a) + (b) 0.50	sec sec		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(b) delay time the status of disabling SCR Efficiency monitoring or integrated upstream NOx	> 80.00 sec >= 3276.70 g		
					(Status of pre controlled dosing (please see the definition) for time	= FALSE - > (a) + (b)		
					(a) Debounce time after pre controlled dosing off	= 0.50 sec		
					(b) Delay time after pre controlled dosing off or	= 180.00 sec		
					integrated upstream NOx)	>= 3276.70 g		
					(Decrease of Reductant load level (please see the definition)	= FALSE -		
					for time	> 300.00 sec		
					(Average slow filtered NOx mass flow upstream SCR	<= 0.12 g/sec		
					for time Monitor disable time based on average NOx mass flow and the time (see Look-Up- Table #88))	> 0.50 sec > 0 to 85 sec		
					for time with	> 15.00 sec		
					Delta SCR temperature (see Look-Up-Table #85) or	<= 23.96 to °C 74.96		
					Delta SCR temperature Delta SCR temperature	> 524.96 °C < 199.96 °C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					or Initialization time of temperature gradient calculation)	< 2.50 sec		
					or Delta SCR temperature or Delta SCR temperature for time	< 229.96 °C > 499.96 °C > 10.00 sec		
					(normalized HC load in SCR catalyst)	> 21.00 -		
					(ambient pressure ambient temperature)	>= 74.80 kPa >= -7.04 °C		
					Stuck reductant dosing valve fault was healed	= FALSE -		
					last particulate filter regeneration successful)	= TRUE -		
					(State of the NH3 slip detection	= FALSE -		
					integrated upstream NOx during SCR adaptation	>= 20.00 g		
					plausibility check active Status of the SCR adaptation plausibility check active (please see the definition)	= FALSE -		
					for time	> 600.00 sec		
					SCR NOx Catalyst Efficiency Below Threshold Bank 1 was performed this drive cycle	= FALSE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					engine speed	>= 1000.00 rpr		
					engine speed	<= 3000.00 rpr		
					for time	> 0.00 se	C	
					SCR estimated current	>= 0.06 to g		
					Reductant load (see Look-	1.3		
					Up-Table #77)			
					SCR estimated current	<= 0.2 to 2.7 g		
					Reductant load (see Look-			
					Up-Table #76) Difference between nominal	>= -0.35 to - g		
					and estimated Reductant	>= -0.35 to - g 0.05		
					(see Look-Up-Table #79)	0.00		
					Difference between nominal	<= 0.05 to g		
					and estimated Reductant	0.2		
					(see Look-Up-Table #78)			
					SCR in Pre-Control State	= FALSE -		
					(please see the definition)			
					(
					Disable after adaptation	= FALSE		
					with			
					for time	> 600.00 se	С	
)			
					(((a) - (b) (see Look-Up-Table	<= 44.96 to °C	,	
					#86)	74.96	í	
					for time	> 0.00 se	С	
)			
					or			
					(. 40.044		
					(a) - (b) (see Look-Up-Table #87)	>= -40.04 to - °C 0.04	1	
					for time	> 0.04 > 0.00 se	c	
					(a) upstream SCR	= measured -	Ĭ	
					catalyst temperature	parameter		
					· ·			
					(b) downstream SCR	= measured -		
					catalyst temperature	parameter		
))			
					Integrated NOx mass	> 1.50 g		
					upstream SCR]		
					for time	> 0.00 se	С	

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Average SCR Temperature Average SCR Temperature Downstream SCR catalyst temperature	<= 399.96 °C >= -3549.94 °C >= 3003.56 °C		
					Downstream SCR catalyst temperature Filtered and delayed upstream NOx raw emission	<= -3549.94 °C >= 750.00 ppm		
					Filtered and delayed upstream NOx raw emission	<= 100.00 ppm		
					Filtered and delayed NOx raw emission mass flow upstream of SCR	<= 0.25 g/sec		
					Filtered and delayed NOx raw emission mass flow upstream of SCR	>= 0.01 g/sec		
					Filtered exhaust gas mass flow	<= 236.11 g/sec		
					Filtered exhaust gas mass flow	>= -910.20 g/sec		
					MAP for valid engine operation points for SCR efficiency monitoring (see Look-Up-Table #83)	= 0 to 1 facto		
					for time Inverse calculated accelerator pedal value	> 0.00 sec > 5.00 %		
					for time	> 0.00 sec		
					EWMA fast initialization mode: filter coefficient for fast initialization number of SCR efficiency measurements for fast initialization mode	= 0.45 facto r >= 2.00 coun t		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					EWMA Rapid Response mode: EWMA filtered delta SCR catalyst efficiency (a) - (b)	> 0.15 facto r < -0.20 facto r		
					(a) measured SCR catalyst efficiency	= measured - parameter		
					(b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	= measured - parameter		
					offset-corrected modeled SCR catalyst efficiency (please see the general description for details) filter coefficient for Rapid	> 0.00 facto r = 0.15 facto		
					Response mode number of SCR efficiency measurements for Rapid Response mode	>= 6.00 coun t		
					EWMA filtered value too small in Fast Init. And Rapid Response modes:			
					EWMA filtered delta SCR catalyst efficiency of (a) - (b)	< 0.00 facto r		
					(a) measured SCR catalyst efficiency	= measured - parameter		
					(b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	= measured - parameter		
					EWMA stabilized mode: filter coefficient for stabilized mode	= 0.05 facto		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria	L	ogic and Va	lue	Parameters		Conditions	Required	Illum.
							number of SCR efficiency measurements for stabilized mode basic enable conditions met:	11	1 coun t see sheet - enable tables		
Accelerator Pedal Position (APP) Sensor 1 Circuit Low Voltage	P2122		voltage of acceleration pedal sensor 1 same as acceleration pedal position	<=	0.79	V %	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= =	TRUE - see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 0.19 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Accelerator Pedal Position (APP) Sensor 1 Circuit High Voltage	P2123		voltage of acceleration pedal sensor 1 same as acceleration pedal position	>=	4.75 125.6	V %	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= =	TRUE - see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 0.19 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	L	Threshold ogic and Va		Secondary Parameters		Enable enditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 2 Circuit Low Voltage	P2127	Detects low voltage readings on the APP circuit, indicating an OOR low condition on the APP 2 circuit	voltage of acceleration pedal sensor 2 same as acceleration pedal position	<= <=	-13.9	V %	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= 56	ee sheet - enable tables ee sheet - inhibit tables	fail conditions exists for 0.19 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Accelerator Pedal Position (APP) Sensor 2 Circuit High Voltage	P2128	Detects high voltage readings on the APP circuit, indicating an OOR high condition on the APP 2 circuit	voltage of acceleration pedal sensor 2 same as acceleration pedal position	>= >=	2.32	V %	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= S6	ee sheet - enable tables ee sheet - inhibit tables	fail conditions exists for 0.19 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Accelerator Pedal Position (APP) Sensor 1-2 Correlation	P2138	positions errors by comparing voltages on each sensor.	maximum value ((a/b) or (c)) - maximum value ((c) or (d)) (see Look-Up-Table #13) with	>	0.120 to 0.180	V	ignition on	=	TRUE -	fail conditions exists for 0.2 s monitor runs with 0.01 rate whenever enable	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable onditions	Time Required	MIL Illum.
			(a) voltage of acceleration pedal position sensor 1	=	measured parameter	V	basic enable conditions met:	=	see sheet - enable tables	conditions are met	
			and with (b) factor between sensor raw values	=	2.00	factor	and NO Pending or Confirmed DTCs:	=	see sheet - inhibit tables		
			and with (c) minimum voltage	=	0.45	V					
			and with (d) redundant voltage of acceleration pedal (from pedal position sensor 2)	=	calculated parameter	-					

tage Control cuit Group 1 put driver circuitry determines if faults (open/short/no load) exist on injector charging bank #1. circuit) properties of the controller power circuit power: ≤ (indicates short to power, short to power, short to enable controller power circuit parameter definition parameter definition exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable controller power controller power circuit ≥ 200 K Ω impedanc e between ECU pin and load signal and controller controller	Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
tage Control cuit Group 1 Dut driver circuitry determines if faults (open/short/no load) exist on injector charging bank #1. Determines if faults (open/short/no load) exist on injector charging bank #1. Determines if faults (indicates short to power, short to ground, or open circuit) Determines if faults (indicates short to power, short to ground, or open circuit) Determines injection controller power Determines injection controller power Determines injection controller									
Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground			ECM Electronic out- put driver circuitry determines if faults (open/short/no load) exist on injector	Voltage high during driver off state (indicates short to power, short to ground, or open	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power Open Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground Short to ground: ≤ 0.5 Ω impedanc e between signal and controller	Engine Running (see		fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are	
and fuel system status = no fuel - cut off									

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Injector Positive Voltage Control Circuit Group 2	P2149	ECM Electronic output driver circuitry determines if faults (open/short/no load) exist on injector charging bank #2.	Voltage high during driver off state (indicates short to power, short to ground, or open circuit)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power Open Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	and fuel system status	= TRUE - = no fuel - cut off	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
Reductant Heater "A" Current Too High	P214F	Detects a tank heater short circuit by detecting high conductance in the heater	(a) >= (b)	=	TRUE	-	ignition switch on	=	TRUE	-	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate	В
		i leatei	with (a) maximum conductance of the urea tank heater	=	calculated parameter	1/Ohm	and urea tank heater powerstage on	=	TRUE	-	whenever enable conditions are met	
			and with (b) maximum tolerance threshold of the conductance for the urea tank heater	=	0.56	1/Ohm	and battery voltage	>=	11.00	٧		
			da.e.				and battery voltage	<=	100.00	٧		
							and engine off time and	>=	5400.00	sec		
							urea tank temperature and (<=	41.96	°C		
							conductance of the urea tank heater is steady or falling					
							for time or	>	1000.00	sec		
							heater activation time)	>=	600.00	sec		
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		

Component /	Fault Code	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	illum.
Injector Positive Voltage Control Circuit Group 3	P2152	ECM Electronic output driver circuitry determines if faults (open/short/no load) exist on injector charging bank #3.	Voltage high during driver off state (indicates short to power, short to ground, or open circuit)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power Open Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground: qround: qround	and fuel system status	= TRUE - e no fuel - cut off	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Oyotom	OGGG	Восоприон	Omona	Logio ana valao	T dramotoro	Conditions	rtoquirou	mam.
Injector Positive Voltage Control Circuit Group 4	P2155	ECM Electronic output driver circuitry determines if faults (open/short/no load) exist on injector charging bank #4.	Voltage high during driver off state (indicates short to power, short to ground, or open circuit)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power Open Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground:	Engine Running (see parameter definition) and fuel system status	= TRUE - = no fuel - cut off	fail conditions exists for more than 0.04 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
System	Code	Description	Cinteria		Logic and va	nue	Farameters		Conditions		Requireu	mum.
Intake Air Temp Sensor 1 / 2 Correlation	P2199	Detects biased Humidity Temperature Sensor or MAF Intake Air Temperature Sensor by comparing the measured temperatures at start.	Path 1: (a) - (b) (see Look-Up-Table #2) where (a) captured intake air temperature at	> =	100 to 999 measured parameter	°C	minimum engine-off time and ambient air temperature and	>=	28800.00 -60.04	sec °C	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate whenever enable conditions are met	В
			start and (b) captured humidity temperature at start	=	measured parameter	-	Engine Running (see parameter definition) for	=	TRUE	-		
			or Path 2: ((a) - (b) (see Look- Up-Table #2) where (a) captured intake air temperature at start and (b) captured humidity temperature at start	<= =	100 to 999 measured parameter measured parameter	°C -	time and engine post drive/ afterun and diagnostic performed in current dc and basic enable conditions met: and NO Pending or Confirmed DTCs:	> = = =	0.00 FALSE FALSE see sheet enable tables see sheet inhibit tables	sec		
					parameter		DTCs:					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary	Enable	Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters	Conditions	Required	Illum.
			(a) - (b) (see Look- Up-Table #5) where (a) captured intake air temperature at start		20 to 999 measured parameter	°C -				
			and (b) captured humidity temperature at start	=	measured parameter	-				
			and (status of block heater (see parameter definition) or	=	FALSE	-				
			status of sun-load detection (see parameter definition))	=	FALSE	-				
Reductant Level Sensor 2 Circuit Low	P21AA		Reductant Tank Level 2 Error Status	=	1	-	ignition on	= TRUE -	fail conditions exists for more than 3 sec monitor runs	А
			(tank level sensor 2 voltage directly measured after a test impulse was applied)	<	(0.17)	V	battery voltage	> 8 V	with 1 s rate whenever enable conditions are	
							basic enable conditions met:	= see sheet - enable tables	met	
Reductant Level Sensor 2 Circuit High	P21AB	Path 1:							1	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va	alue	Parameters		Conditions		Required	Illum.
		CAN message: Discrete level sensor 2 open load error	Reductant Tank Level 2 Error Status (measured tank level sensor 2 voltage after 1.5 ms since a test	>	3 (3.56)	V	ignition on battery voltage	>	TRUE 8	V		
			impulse was applied) (measured tank level sensor 2 voltage after 1.5 ms since a test impulse was applied)	<	(4.74)	V	basic enable conditions met:	=	see sheet enable tables	-		
		Path 2: CAN message: Discrete level sensor 2 short to battery error	Reductant Tank Level 2 Error Status	=	2	-	ignition on	=	TRUE	-		
		oner to suitely error	(measured tank level sensor 2 voltage after 1.5 ms since a test impulse was applied)	>	(4.74)	V	battery voltage	>	8	V		
			ралоо тао оррпоо)				basic enable conditions met:	=	see sheet enable tables	-		
Reductant Level Sensor 3 Circuit Low	P21AF	CAN message: Discrete level sensor level 3 short to ground error	Reductant Tank Level 3 Error Status	=	1		ignition on	=	TRUE	-		
			(tank level sensor 3 voltage directly measured after a test impulse was applied)	<	(0.17)	V	battery voltage	>	8	V		
			,				basic enable conditions met:	=	see sheet enable tables	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Reductant Level Sensor 3 Circuit High	P21B0	Path 1: CAN message: Discrete level sensor 3 open load error	Reductant Tank Level	= >	3 (3.56) (4.74)	- V V	ignition on battery voltage basic enable conditions met:	= >	TRUE 8 see sheet enable tables	- V	fail conditions exists for more than 3 sec monitor runs with 1 s rate whenever enable conditions are met	A
		Path 2: CAN message: Discrete level sensor 3 short to battery error	Reductant Tank Level 3 Error Status (measured tank level sensor 3 voltage after 1.5 ms since a test impulse was applied)	= ^	2 (4.74)	- V	ignition on battery voltage basic enable conditions met:	= >	TRUE 8 see sheet enable tables	- V		
Reductant Heater "A" Current Too Low	P21DD	Detects a tank heater open circuit by detecting low conductance in the heater	(a) <= (b) with (a) maximum conductance of the urea tank heater and with	=	TRUE calculated parameter	- 1/Ohm	ignition switch on and urea tank heater powerstage on and	=	TRUE	-	fail conditions exists for 0.05 s monitor runs once per trip with 0.05 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
			(b) minimum tolerance threshold of the conductance for the urea tank heater	П	0.35	1/Ohm	battery voltage and	>=	11.00	V		
							battery voltage and	<=	100.00	V		
							engine off time and	>=	300.00	sec		
							urea tank temperature and (<=	41.96	°C		
							conductance of the urea tank heater is steady or falling					
							for time or	>	1000.00	sec		
							heater activation time)	>=	600.00	sec		
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
NOx Sensor Circuit Bank 1 Sensor 1	P2200	Detects a failure when open circuit status message from NOx sensor is received continuously for a time period	Open circuit NOx signal error	=	TRUE		following conditions for time	>	0.50	sec	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever	A
							battery voltage	>=	11.00	V	enable conditions are	
							battery voltage	<=	655.34	V	met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					SCR upstream temperature	>= 94.96 °C		
					SCR upstream temperature	<= 3003.56 °C		
					Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of:	= TRUE - >= 20.00 sec = TRUE -		
					ignition on for time	= TRUE - >= 3 sec		
					battery voltage	> 9.8 V		
					battery voltage	< 655.34 V		
					Upstream NOx sensor dewpoint achieved (please see the definition)	= TRUE -		
					no pending or confirmed faults	= see sheet - inhibit tables		
					basic enable conditions met:	= see sheet - enable tables		
		Detects a failure when open circuit status message from binary lambda signal from the NOx sensor is received continuously for a time period	lambda signal error	= TRUE -	following conditions for time	> 0.50 sec	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable	
		a. a p aa			battery voltage	>= 11.00 V	conditions are	
					battery voltage	<= 655.34 V	met	
					SCR upstream temperature	>= 94.96 °C		
					SCR upstream temperature	<= 3003.56 °C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Engine Running for time	= TRUE - >= 20.00 sec		
					Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage Upstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	= TRUE - = TRUE - >= 3 sec > 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables		
		Detects a failure when open circuit status message from linear lambda signal from the NOx sensor is received continuously for a time period	lambda signal error	= TRUE -	following conditions for time battery voltage battery voltage SCR upstream temperature SCR upstream temperature Engine Running for time	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage Upstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	= TRUE - = TRUE - >= 3 sec > 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables		
		Detects a failure when short circuit status message from NOx sensor is received continuously for a time period	Short Circuit Nox signal error	= TRUE -	following conditions for time battery voltage battery voltage SCR upstream temperature SCR upstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec = TRUE - = TRUE - = TRUE - >= 3 sec > 9.8 V	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters battery voltage	<	Conditions 655.34	V	Required	Illum.
					Upstream NOx sensor dewpoint achieved (please see the definition)	=	TRUE	-		
					no pending or confirmed faults	=	see sheet inhibit tables	-		
					basic enable conditions met:	=	see sheet enable tables	-		
		Detects a failure when	Short Circuit binary	= TRUE -	following conditions for time	>	0.50	sec	fail conditions	
		short circuit status message from binary lambda signal form the NOx sensor is received continuously for a time period	lambda signal error	- INGE	Tollowing conditions for time		0.00	300	exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable	
		ioi a umo pomea			battery voltage	>=	11.00	V	conditions are met	
					battery voltage	<=	655.34	V		
					SCR upstream temperature	>=	94.96	°C		
					SCR upstream temperature	<=	3003.56	°C		
					Engine Running	=	TRUE	-		
					for time	>=	20.00	sec		
					Can Bus Initialized (CAN Bus is Active)	=	TRUE	-		
					consisting of: ignition on for time battery voltage battery voltage	= >= > <	TRUE 3 9.8 655.34	sec V V		

	ault ode	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions		Time Required	MIL Illum.
System	oue	Description	Onteria	Logic and value	Upstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	= TRUE = see sheet inhibit tables = see sheet enable tables	-	Required	mum.
		Detects a failure when short circuit status message from linear lambda signal from the NOx sensor is received continuously for a time period	Short Circuit linear lambda signal error	= TRUE -	following conditions for time battery voltage battery voltage SCR upstream temperature SCR upstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage battery voltage	> 0.50 >= 11.00 <= 655.34 >= 94.96 <= 3003.56 = TRUE >= 20.00 = TRUE = TRUE = 3 > 9.8 < 655.34	sec V V °C - sec - sec V V	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshol Logic and V		Secondary Parameters		Enable Conditions	5	Time Required	MIL Illum.
		·		J		Upstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	=	TRUE see sheet inhibit tables see sheet enable tables	-		
N0x Sensor Circuit High Bank 1 Sensor 1	P2203	Detects an out of range high fault of the upstream NoX Sensor	Nox sensor signal (raw information received via CAN from Nox sensor)	> 2500.00	ppm	Nox sensor 1 ready status (see parameter definition) Valid NOx signal from CAN is received (no Nox sensor communication failures) Engine Running (see parameter definition) for time	= = =	TRUE TRUE TRUE 20.00	- - sec	fault exists for more than 10 sec; monitor runs at 0.1 s when enable conditions are met	В
N0x Sensor Circuit Low Bank 1 Sensor 1	P2202	Detects an out of range low fault of the upstream NoX Sensor	Nox sensor signal (raw information received via CAN from Nox sensor)	< -90.00	ppm	Injection Quantity or Upstream NOx sensor dewpoint achieved (please see the definition) for time	> =	8.00 TRUE 600.00	mm^ 3/rev - sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Nox Sensor Heater Control Circuit Bank 1 Sensor 1	P2205	Detects a failure when open circuit status message from NOx sensor heater is received continuously for a time period	Open Circuit Nox Heater signal error	= TRUE -	following conditions for time	> 0.50 sec	fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever enable	А
					battery voltage battery voltage	>= 11.00 V <= 655.34 V	conditions are met	
					SCR upstream temperature	>= 94.96 °C		
					SCR upstream temperature	<= 3003.56 °C		
					Engine Running	= TRUE -		
					for time	>= 20.00 sec		
					Can Bus Initialized (CAN Bus is Active)	= TRUE -		
					consisting of: ignition on for time	= TRUE - >= 3 sec		
					battery voltage battery voltage	> 9.8 V < 655.34 V		
					Upstream NOx sensor dewpoint achieved (please see the definition)	= TRUE -		
					no pending or confirmed faults	= see sheet - inhibit tables		
					basic enable conditions met:	= see sheet - enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
		Detects a failure when short circuit status message from NOx sensor heater is received continuously for a time period	Short Circuit Nox heater signal error	= TRUE -	following conditions for time	> 0.50 s	ec fail conditions exists for more than 13 sec. monitor runs with 0.01 s rate whenever	
					battery voltage battery voltage		enable conditions are met	
					SCR upstream temperature SCR upstream temperature		c c	
					Engine Running for time		- ec	
					Can Bus Initialized (CAN Bus is Active)	= TRUE	-	
					consisting of: ignition on for time battery voltage battery voltage Upstream NOx sensor dewpoint achieved (please see the definition)	>= 3 s > 9.8 < 655.34	ec / /	
					no pending or confirmed faults basic enable conditions met:	inhibit tables	-	
NOx Heater Performance Bank 1 Sensor 1	P2209		Upstream NOx sensor heater temperature has reached setpoint	= FALSE -	(battery voltage	>= 11.00	fault exists for more than 1 event when dewpoint end is reached;	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
System	Code	Description	Criteria		Logic and V	aiue	and battery voltage and Oxidation Catalyst upstream temperature and Oxidation Catalyst upstream temperature and Engine running for time and Upstream NOx sensor dewpoint end is reached (please see parameter definition)) for time and basic enable conditions met: No Pending or Confirmed DTC	<=	655.34 94.96 3003.56 TRUE 20.00 TRUE 150.5 see sheet enable tables see sheet inhibit tables	V °C - sec -	monitor runs at 0.02 s when enable conditions are met	illum.
Reductant Heater "B" Current Too Low	P221C	Detects a pressure line heater open circuit by detecting low conductance in the heater	(a) <= (b) with (a) conductance of the urea pressure line heater and with	=	TRUE calculated parameter	- 1/Ohm	ignition switch on and urea pressure line heater powerstage on	=	TRUE	-	fail conditions exists for 0.05 s monitor runs with 0.05 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
			(b) minimum tolerance threshold of the conductance for the urea pressure line heater	=	0.28	1/Ohm	battery voltage and	>=	11.00	V		
							battery voltage	<=	100.00	V		
							and engine off time and heater activation time	>=	0.00 81.00	sec sec		
							and basic enable conditions	=	see sheet	-		
							met: and		enable tables			
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Reductant Heater "B" Current Too High	P221D	Detects a pressure line heater short circuit by detecting high conductance in the	(a) >= (b) with	=	TRUE	-	ignition switch on	=	TRUE	-	fail conditions exists for 0.05 s monitor runs with 0.05 s rate	В
		heater									whenever enable	
			(a) conductance of the urea pressure line heater	=	calculated parameter	1/Ohm	urea pressure line heater powerstage on	=	TRUE	-	conditions are met	
			and with (b) maximum tolerance threshold of the conductance for the urea pressure line heater	=	0.92	1/Ohm	and battery voltage	>=	11.00	V		
							and battery voltage	<=	100.00	٧		
							and					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	;	Required	Illum.
		·					engine off time and heater activation time and basic enable conditions met:	>= >= =	0.00 81.00 see sheet enable tables	sec sec		
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables			
Reductant Heater "C" Current Too Low	P221E	Detects a supply module heater open circuit by detecting low conductance in the heater	(a) <= (b) with	=	TRUE	-	ignition switch on	=	TRUE	-	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate	В
			(a) maximum conductance of the supply module heater and with	=	calculated parameter	1/Ohm	supply module heater powerstage on and	=	TRUE	-	whenever enable conditions are met	
			(b) minimum tolerance threshold of the conductance for the supply module heater	=	0.14	1/Ohm	battery voltage	>=	11.00	V		
							and battery voltage	<=	100.00	٧		
							and engine off time and (conductance of the urea tank heater is steady or falling for	>=	7600.00	sec		
							time or heater activation time	> >=	100.00	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters) and basic enable conditions met:	=	see sheet enable tables	<u>-</u>	Required	Illum.
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables			
Reductant Heater "C" Current Too High	P221F	Detects a supply module heater short circuit by detecting high conductance in the heater	(a) >= (b) with	=	TRUE	-	ignition switch on	=	TRUE	-	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate whenever	В
			(a) maximum conductance of the supply module heater and with	=	calculated parameter		supply module heater powerstage on and	=	TRUE	-	enable conditions are met	
			(b) maximum tolerance threshold of the conductance for the supply module heater	=	0.35	1/Ohm	battery voltage	>=	11.00	V		
							and battery voltage	<=	100.00	٧		
							and engine off time and (>=	7600.00	sec		
							conductance of the urea tank heater is steady or falling for					
							time or	>	100.00	sec		
							heater activation time)	>=	10.00	sec		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshologic and V		Secondary Parameters	(Enable Conditions	Time Required	MIL Illum.
							and basic enable conditions met: and NO Pending or Confirmed DTCs:		see sheet - enable tables see sheet - inhibit tables		
Barometric Pressure (BARO) Circuit Low	P2228	Detects low voltage readings on the ECM internal BARO circuit, indicating an OOR low condition on the BARO circuit.	voltage of barometric pressure sensor same as ambient pressure	<= <=	1.97	V kPa	ignition on and basic enable conditions met:	= =	TRUE - see sheet - enable tables	fail conditions exists for 0.8 s monitor runs 0.1 s rate whenever enable conditions are met	A
Barometric Pressure (BARO) Circuit High	P2229	internal BARO circuit, indicating an OOR high condition on the BARO circuit.	voltage of barometric pressure sensor same as ambient pressure	>=	4.54		ignition on and basic enable conditions met:	11	TRUE - see sheet - enable tables	fail conditions exists for 0.8 s monitor runs 0.1 s rate whenever enable conditions are met	A

Component /	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
System					Logic and v	alue	Parameters		Conditions		
Turbo Boost System Performance	P2263	Detects if the Turbocharger is severely over or under boosting based on control deviation	Path 1:							fail conditions exists for 15 s test performed continuously 0.01 s rate	A
			control deviation of the boost pressure calculated out of difference between desired and actual value with (a) control deviation threshold (see Look-	>	(a)*(b) 80 to 100	- kPa	offset learning for turbo charger (VNT) actuator position sensor is active during idling - in order to compensate sensor drift and valve aging, the valve is closed and opened fully once in a driving cycle during engine idling, the read positions for opening and closing are averaged and used for the calculation of offset drift of the valve and	=	FALSE -		
			Up-Table #64) (b) environmental pressure correction factor(see Look-Up-Table #59)		0.67 to 1	factor	turbo charger (VNT) wiping is active - in order to prevent soot accumulation e.g. in a long idle operation under cold engine condition on the turbine the desired value of the boost pressure actuator position governor is assigned from the set-point value and	=	FALSE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	3	Required	Illum.
					injection quantity is stable means increase of injection quantity	= TRUE < 24.00	- (mm ^3/re		
					and engine speed is stable means	= TRUE	v)/se c -		
					increase of engine speed and	< 100.00	rpm/ sec		
					injection Quantity	>= 80.00	mm^ 3/rev		
					injection Quantity and	<= 480.00	mm^ 3/rev		
					engine Speed engine Speed	>= 1200.00 <= 3400.00	rpm rpm		
					and working range of boost pressure is in closed-loop means (= TRUE	-		
					engine speed and	> 550.00	rpm		
					injection quantity	> 80.00	mm^ 3/rev		
					NO Pending or Confirmed DTCs:	= see sheet inhibit tables	-		
					for time and basic enable conditions met:	> 2.00 = see sheet enable	sec -		
						tables			
			Path 2					fail conditions	

Component /	Fault	Monitor Strategy	Primary Malfunction	Thresho	ld	Secondary	F	nable	Time	MIL
System	Code	Description	Criteria	Logic and \		Parameters		nditions	Required	Illum.
		·	control deviation of the boost pressure calculated out of difference between desired and actual value	< (a)*(b)	-	offset learning for turbo charger (VNT) actuator position sensor is active during idling		ALSE -	exists for 15 s test performed continuously 0.01 s rate	
			with			- in order to compensate sensor drift and valve aging, the valve is closed and opened fully once in a driving cycle during engine idling, the read positions for opening and closing are averaged and used for the calculation of offset drift of the valve				
			(a) control deviation threshold (see Look- Up-Table #63)		kPa	and	_			
			(b) environmental pressure correction factor	= 1.00	factor	turbo charger (VNT) wiping is active - in order to prevent soot accumulation e.g. in a long idle operation under cold engine condition on the turbine the desired value of the boost pressure actuator position governor is assigned from the set-point value	= F	ALSE -		
						and injection quantity is stable means increase of injection quantity and engine speed is stable means	< 2 = T	FRUE - 24.00 (mm	e e	
						increase of engine speed	< 1	00.00 rpm sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					and injection Quantity injection Quantity	>= 80.00 mm^ 3/rev <= 480.00 mm^ 3/rev		
					and engine Speed engine Speed and working range of boost pressure is in closed-loop means	>= 1200.00 rpm <= 3400.00 rpm = TRUE -		
					(engine speed and injection quantity)	> 550.00 rpm > 80.00 mm^ 3/rev		
					NO Pending or Confirmed DTCs: for time	= see sheet - inhibit tables > 2.00 sec		
					and basic enable conditions met:	= see sheet - enable tables		
Fuel Pressure Regulator 2 Control Circuit	P2294	Diagnoses the Fuel Pressure Regulator 2 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Open - Circuit: ≥ 200 K Ω impedanc e between ECU pin and load signal and controller ground	battery voltage	> 11.00 V	fail conditions exists for 0.75 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Oyotom	-	Josephon	011011a		time and ignition on and basic enable conditions met:	> 3.00 sec = TRUE - = see sheet - enable tables	roquirou	
			Electronic power stage circuitry determines over temperature on the fuel pressure regulator 2 control circuit.		for time and ignition on and basic enable conditions met:	> 11.00 V > 3.00 sec = TRUE - = see sheet - enable tables	fail conditions exists for 1 s monitor runs with 0.01 s rate whenever enable conditions are met	A
Fuel Pressure Regulator 2 Control Circuit Low Voltage	P2295	Diagnoses the Fuel Pressure Regulator 2 low side driver circuit for circuit faults.	Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedanc e between signal and controller ground	for time and ignition on and	> 11.00 V > 3.00 sec = TRUE -	fail conditions exists for 0.75 s monitor runs with 0.01 s rate whenever enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
- Oystem	Odde	Description	Ontena	Logic and Value	basic enable conditions met:	= see sheet - enable tables	required	mum.
Fuel Pressure Regulator 2 Control Circuit High Voltage	P2296	Diagnoses the Fuel Pressure Regulator 2 low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedanc e between signal and controller power	for time and ignition on	> 11.00 V > 3.00 sec = TRUE -	fail conditions exists for 0.50 s monitor runs with 0.01 s rate whenever enable conditions are met	A
					and basic enable conditions met:	= see sheet - enable tables		
NOx Sensor Circuit Bank 1 Sensor 2	P229E	open circuit status	Open circuit downstream NOx signal error	= TRUE -	battery voltage battery voltage battery voltage SCR downstream temperature SCR downstream temperature Engine Running for time	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
- Oystein	Oode				Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	= TRUE - = TRUE - >= 3 sec > 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables		mum.
		Open circuit error of the binary lambda signal of Downstream NOx sensor via the CAN message	Open circuit lambda binary error of downstream NOx sensor via CAN message	= TRUE -	battery voltage battery voltage SCR downstream temperature SCR downstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition)	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec = TRUE - = TRUE - >= 3 sec > 9.8 V < 655.34 V = TRUE -	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cycloni	0000	Боотрион	Ornoriu	Eogio ana valuo	no pending or confirmed faults basic enable conditions met:	= see sheet - inhibit tables = see sheet - enable tables	rtoquirou	mum
		linear lambda signal of Downstream NOx sensor via the CAN	Open circuit lambda linear error of downstream NOx sensor via CAN message	= TRUE -	battery voltage battery voltage SCR downstream temperature SCR downstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec = TRUE - = TRUE - = 3 sec > 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	Logic and Value	Parameters		Conditions		Required	Illum.
		Downstream NOx sensor short circuit error via the CAN message	Short circuit NOx signal error of downstream NOx sensor via CAN	=	TRUE -	following conditions for time	>	0.50	sec	fail conditions exists for more than 13 s monitor runs with 0.1 s rate	
			message			battery voltage battery voltage SCR downstream temperature SCR downstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time	>=	11.00 655.34 94.96 3003.56 TRUE 20.00 TRUE	V V °C °C - sec -	with 0.1 s rate whenever enable conditions are met	
						battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults	\ \ \ = =	3 9.8 655.34 TRUE see sheet inhibit tables	sec V V -		
						basic enable conditions met:	=	see sheet enable tables	-		
		Short circuit error of binary lambda signal of Downstream NOx sensor via the CAN message	Short circuit lambda binary error of downstream NOx sensor via CAN message	=	TRUE -	battery voltage battery voltage battery voltage SCR downstream temperature SCR downstream temperature	^	0.50 11.00 655.34 94.96 3003.56	sec V V °C °C	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are met	

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Engine Running for time Can Bus Initialized (CAN Bus is Active)	= TRUE - >= 20.00 sec = TRUE -		
					consisting of: ignition on for time battery voltage battery voltage Downstream NOx sensor dewpoint achieved	= TRUE - >= 3 sec > 9.8 V < 655.34 V = TRUE -		
					(please see the definition) no pending or confirmed faults basic enable conditions met:	= see sheet - inhibit tables = see sheet - enable tables		
		Short circuit error of linear lambda signal of Downstream NOx sensor via the CAN message	Short circuit lambda linear error of downstream NOx sensor via CAN message	= TRUE -	following conditions for time battery voltage battery voltage SCR downstream	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are	
					temperature SCR downstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on	<= 3003.56 °C = TRUE - >= 20.00 sec = TRUE -	met	
					for time battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition)	>= 3 sec > 9.8 V < 655.34 V = TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
							no pending or confirmed faults basic enable conditions met:	II II	see sheet inhibit tables see sheet enable tables			
NOx Sensor Range / Performance - Bank 1 Sensor 2	P229F	Compares Delta NOx concentration of downstream NOx sensor with a threshold after upstream Nox concentration change is detected	Maximum deviation of downstream NOx concentration from the state machine_5	<	Min [(a) or (b)]	ppm	NO Pending or Confirmed DTCs:	=	See sheet inhibit table	i -	fail conditions exists for more than 2 event monitor runs with 0.01s rate whenever enable conditions are	В
			((a) Limit value for Stuck in range check of downstrean NOx	=	5.00	ppm	Status of NOx signal of upstream NOx sensor (please see the definition) for time Status of NOx signal of downstream NOx sensor (please see the definition)	> =	0.50 TRUE	sec	met	
			concentration and (b) = (c) * (d)				for time exhaust gas mass flow	> >=	0.50 2.78	sec g/sec		
			and with ((c) Weighting factor for calculating the peak limit value based on the SCR temperature and	=	32.767	factor	engine speed for time	> >	100.00 10.00	rpm sec		
			the NOx mass flow (d) Average upstream NOx concentration	=	measured parameter	ppm	Status of the SCR adaptation plausibility check active (please see the definition) for time	= >	FALSE	- sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					((SCR catalyst average temperature SCR catalyst average temperature	<= 299.96 °C >= -0.04 °C		
					or (SCR catalyst average temperature SCR catalyst average	<= 999.96 °C >= 349.96 °C		
					temperature)) State of Reductant injection valve Component Protection	= FALSE -		
					(please see definition) for time (State machine_0 : starting	> 120.00 sec		
					state and waiting for low upstream NOx mass flow / concentration			
					Filtered upstream NOx mass flow	< 0.02 g/sec		
					Filtered NOx concentration Exhaust mass flow	< 170.00 ppm < 69.40 g/sec		
					for time)	< 1.00 sec		
					State machine_1 : low upstream NOx mass flow /concentration reached			
					Old State machine_0 : starting state and waiting for low upstream NOx mass flow / concentration	= TRUE -		
					for time Filtered upstream NOx mass flow	>= 1.00 sec < 0.02 g/sec		
					Filtered NOx concentration	< 170.00 ppm		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Exhaust mass flow captured minimum downstream NOx concentration in State machine_1)	< 69.40 g/sec = Measured - parameter		
					State machine_2 : start Upstream NOx peak (Old State machine_1 : low upstream NOx mass flow	= TRUE -		
					/concentration reached (Filtered upstream NOx mass flow or Filtered NOx concentration	> 0.02 g/sec > 170.00 ppm		
					or Exhaust mass flow	> 69.40 g/sec		
) for time Absolute deviation of downstream NOx concentration: (a) - (b) and with	< 2.00 sec = Measured - parameter		
					(a) Filtered downstream NOx concentration	= Measured - parameter		
					(b) captured minimum downstream NOx concentration in State machine_1, 2, and 3	= Measured - parameter		
					State machine_3 : Upstream NOx peak detection (
					Old State machine_2 : start Upstream NOx peak for time	= TRUE - >= 2.00 sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Filtered upstream NOx mass flow Filtered NOx concentration Exhaust mass flow message for time Absolute deviation of downstream NOx concentration: (a) - (b) and with	>= 0.04 g/sec >= 190.00 ppm >= 125.00 g/sec < 0.50 sec = Measured ppm parameter		
					(a) Filtered downstream NOx concentration	Measured ppm parameter		
					(b) captured minimum downstream NOx concentration in State machine_1, 2, and 3	= Measured ppm parameter		
					State machine_4 : delay for downstream NOx peak evaluation			
					Old State machine_3 : Upstream NOx peak detection	= TRUE -		
					for time Filtered and estimated NOx conversion efficiency of SCR catalyst	>= 0.50 sec <= 0.60 facto r		
					Absolute deviation of downstream NOx concentration: (a) - (b) and with	= Measured ppm parameter		
					(a) Filtered downstream NOx concentration	Measured ppm parameter		
					(b) captured minimum downstream NOx concentration in State machine_1, 2, and 3	= Measured ppm parameter		
					for time (see Look-Up-Table #89)	< 4.5 to 5.5 sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Logic and Value	State machine_5 : end of downstream NOx peak and evaluation Filtered and estimated NOx conversion efficiency of SCR catalyst for time (Old State machine_4 : delay for downstream NOx peak evaluation for time (see Look-Up-Table #89) Maximum deviation of downstream NOx concentration among different states of state machine Average SCR catalyst temperature Average upstream NOx mass flow in state machine_3 and _4 Average upstream NOx concentration in state machine_3 and _4	<pre>Conditions <= 0.80 - > 0.10 sec = TRUE - >= 3 to 5.5 sec = Measured ppm parameter > 149.96 °C >= 0.04 mg/s >= 190.00 ppm</pre>	Time Required	MIL Illum.
					NO Pending or Confirmed DTCs:)) basic enable conditions met:	= see sheet - inhibit tables = see sheet - enable tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \	'alue	Parameters		Conditions	S	Required	Illum.
NOx Sensor Circuit High Bank 1 Sensor 2	P22A1	Detects an out of range high fault of the downstream NoX Sensor	Downstream Nox sensor signal (raw information received via CAN from Nox sensor)	>	2500.00	ppm	Downstream Nox sensor ready status (see parameter definition) Valid NOx signal from CAN is received (no Nox sensor	=	TRUE	-	fault exists for more than 10 sec; monitor runs at 0.1 s when enable conditions are met	В
							communication failures)					
NOx Sensor Circuit Low Bank 1 Sensor 2	P22A0	Detects an out of range low fault of the downstream NoX Sensor	Downstream Nox sensor signal (raw information received via CAN from Nox sensor)	<	-90.00	ppm	Engine Running (see parameter definition)	=	TRUE	-		
							for time and	>	20.00	sec		
							Injection Quantity	>	8.00	mm^ 3/rev		
							or Downstream NOx sensor dewpoint achieved (please	=	TRUE	-		
							see the definition) for time	>	600.00	sec		
NOx Heater Control Circuit Bank 1 Sensor 2	P22A3	Downstream NOx sensor heater open circuit error via the CAN message	Open circuit heater error of downstream NOx sensor via CAN message	=	TRUE		following conditions for time	>	0.50	sec	fail conditions exists for more than 13 s monitor runs	А
		o/ ii v meddage	mesoage				battery voltage	>=	11.00	V	with 0.1 s rate	
							battery voltage	<=	655.34	V	whenever	
							SCR downstream temperature	>=	94.96	°C	enable conditions are	
							SCR downstream	<=	3003.56	°C	met	
							temperature Engine Running	=	TRUE	_		
							for time	>=	20.00	sec		
							Can Bus Initialized (CAN Bus is Active) consisting of:	=	TRUE	-		
							ignition on	=	TRUE	-		
			I I				for time	>=	3	sec		!

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Cinteria	Logic and value	battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	> 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables	Requireu	mum.
			Short circuit heater error of downstream NOx sensor via CAN message	= TRUE -	battery voltage battery voltage SCR downstream temperature SCR downstream temperature Engine Running for time Can Bus Initialized (CAN Bus is Active) consisting of: ignition on for time battery voltage battery voltage battery voltage Downstream NOx sensor dewpoint achieved (please see the definition) no pending or confirmed faults basic enable conditions met:	> 0.50 sec >= 11.00 V <= 655.34 V >= 94.96 °C <= 3003.56 °C = TRUE - >= 20.00 sec = TRUE - = TRUE - = 3 sec > 9.8 V < 655.34 V = TRUE - = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for more than 13 s monitor runs with 0.1 s rate whenever enable conditions are met	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Val	ue	Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
NOx Heater Performance Bank 1 Sensor 2	P22A7	Monitoring of the downstream NoX sensor signal readiness	Downstream NOx sensor heater temperature has reached setpoint	=	FALSE	-	battery voltage and battery voltage and SCR downstream temperature and SCR downstream temperature and Engine running for time and Downstream Nox Sensor Dewpoint end is reached (please see the parameter definition)) for time and basic enable conditions met: No Pending or Confirmed DTCs	>= <= >= > = > = =	11.00 655.34 94.96 3003.56 TRUE 20.00 TRUE	V V°C °C - sec -	fault exists for more than 1 event when dewpoint end is reached; monitor runs at 0.02 s when enable conditions are met	B
NOx Sensor Performance - Slow Response High to Low Bank 1 Sensor 1	P22FA	which the NOx concentration falls is slower than a calibrated threshold a fault is set.	Time it takes for the NOx concentration level to fall from 70% to 40% of the initial Nox concentration value	>	2.30	sec	State of the NOx sensor dynamic monitoring state machine	=	Evaluate falling edge of NOx concentra tion signal	-	fail conditions exist for 1 event, test is performed in the 0.01 ms rate when enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	alue	Parameters		Conditions		Required	Illum.
			Downstream NOx concentration	>	40% of Initial Nox Concentr ation Level	-	Injection quantity for current cylinder	<		mm^ 3/rev		
			for time	>	5.00	sec	for time	<	1.05	sec		
Exhaust Gas High Temperature	P2428		Any two of the following four conditions: ((a) and (b)) or ((a) and (c)) or ((a) and (d)) or ((b) and (c)) or ((c) and (d)) or ((c) and (d)) with				basic enable conditions met:	=	see sheet enable tables	-	fail conditions exists for 6 s test performed continuously 0.1 s rate	A
			(a) oxidation catalyst upstream temperature and with	>	799.96	°C	and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
			(b) oxidation catalyst downstream temperature and with	>	799.96	°C						
			(c) SCR downstream temperature and with	>	799.96	°C						
			(d) particulate filter downstream temperature	>	799.96	°C						

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V		Parameters		Conditions	;	Required	Illum.
Exhaust Temperature Sensor 3 Performance	P242B	Detects a fault in the exhaust temperature sensor 3 performance by comparing the heat quantity on the sensor position to a threshold.	integrated heat quantity of exhaust gas temperature sensor 3	<	(a) / (b) * (c) / (d) * (e) * (f)		exhaust gas system regeneration mode	=	FALSE	-	fail conditions exists for xxs monitor runs with 0.1 s rate whenever enable	В
			or integrated heat quantity of exhaust gas temperature sensor 3	>	(a) / (b) * (c) / (d) * (e) * (g)		for time	>	1500.00	sec	conditions are met	
			with (a) exhaust gas mass flow	=	calculated parameter	-	and time since start	>	327.00	sec		
			and with (b) factor and with	=	3.60	g/sec	and (exhaust-gas temperature sensor 3	>	-60.04	°C		
			(c) heat capacity and with	=	1050.00	J/Kg/°C	and exhaust-gas temperature sensor 3	<	1999.96	°C		
			(d) factor and with (e) correction factor for heat flow quantity depending on exhaust gas mass flow for temperature sensor 3	=======================================	1.00	kW/°C factor) and change in exhaust-gas temperature sensor 3	<	7.00	°C		
			and with (f) minimum permissible temperature deviation for exhaust gas temperature sensor	=	-100.00	°C	for time and	=	5.00	sec		
			3 and with				engine operation point suitable for diagnostic (see Look-Up-Table #29)	=	0 to 255	-		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Val		Parameters		Conditions		Required	Illum.
			(g) maximum permissible temperature deviation for exhaust gas temperature sensor 3	=	100.00	°C	time and change in modeled exhaust- gas temperature sensor 3 and (heat quantity for exhaust gas temperature sensor 3 and heat quantity for exhaust gas temperature sensor 3) and engine has been in normal mode for time or engine has been in exhaust warm-up mode for time and basic enable conditions met: and NO Pending or Confirmed DTCs:	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	0.05 4.00 10.00 12.00 1.00 1.00 see sheet enable tables see sheet inhibit tables	sec °C kJ kJ sec		
Exhaust Gas Temperature (EGT) Sensor 3 Circuit Low Voltage	P242C		voltage of SCR downstream catalyst temperature sensor same as	<	0.65	V	((engine speed	<=	6000.00	rpm	fail conditions exists for more than 5.0 sec. monitor runs with 0.1 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		ogic and V		Parameters		Conditions		Required	Illum.
			Downstream SCR Catalyst temperature	v	-50	°C	engine speed current injection quantity current injection quantity engine coolant temperature time since engine start exhaust-gas mass flow downstream of the exhaust manifold) or SCR catalyst temperature) for time NO Pending or Confirmed DTCs: basic enable conditions met:	<pre>>=</pre>	0.00 800.00 0.00 -50.04 0.00 0.00 -45.04 0.00 see sheet inhibit tables see sheet enable			
Exhaust Gas Temperature (EGT) Sensor 3 Circuit High Voltage	P242D	Detects high voltage condition of the downstream SCR catalyst temperature sensor circuit, indicating an OOR high condition	voltage of SCR downstream catalyst temperature sensor same as Downstream SCR Catalyst temperature	>	2.21	V °C	engine speed engine speed current injection quantity current injection quantity engine coolant temperature time since engine start	<= >= >= >= > >	6000.00 0.00 800.00 0.00 -50.04 0.00	rpm rpm 3/rev mm^ 3/rev °C sec	fail conditions exists for more than 5.0 sec. monitor runs with 0.1 s rate whenever enable conditions are met	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value				Illum.
Diesel Particulate Filter Differential Pressure Sensor Performance	Fault Code	Detects in range faults on the DPF differential pressures sensor.	Criteria	< -1.00 kPa/sec	exhaust-gas mass flow downstream of the exhaust manifold) or SCR catalyst temperature) for time NO Pending or Confirmed DTCs: basic enable conditions met:	Conditions	Required	MIL Illum.
					basic enable conditions met: and NO Pending or Confirmed DTCs:	see sheet - enable tablessee sheet - inhibit tables		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	ld	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and \	/alue	Parameters	Conditions		Required	Illum.
			Path 2:				Engine State	= After Run		fail conditions exists for 0.5 s monitor runs with 0.1 s rate	
			differential pressure sensor	>	3.20	kPa	for time and basic enable conditions met:	> 35.00 = see sheet enable tables	sec -	whenever enable conditions are met	
							and NO Pending or Confirmed DTCs:	= see sheet inhibit tables	-		
Diesel Particulate Filter Differential Pressure Sensor Circuit Low Voltage	P2454	Detects low voltage readings on the DPF differential pressure sensor circuit, indicating an OOR low condition on the circuit	voltage of differential pressure sensor	<	0.83	V	ignition on	= TRUE	-	fail conditions exists for 3 s test performed continuously 0.020 s rate	В
			same as differential pressure	<	-4.20	kPa	and basic enable conditions met:	= see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	= see sheet inhibit tables	-		
Diesel Particulate Filter Differential Pressure Sensor Circuit High Voltage	P2455	Detects high voltage readings on the DPF differential pressure sensor circuit, indicating an OOR high condition on the circuit	voltage of differential pressure sensor	>	4.67	V	ignition on	= TRUE	-	fail conditions exists for 3 s test performed continuously 0.020 s rate	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
System	Code	Description	differential pressure	>	91.70	kPa	basic enable conditions met: and NO Pending or Confirmed DTCs:	=	see sheet enable tables see sheet inhibit tables	-	Required	illum.
Exhaust Gas (EGR) Cooler Performance		Performs a check of the EGR cooler performance by monitoring the EGR efficiency and comparing it to a threshold value	EGR cooler efficiency	<	0.45		(engine speed and engine speed) and (injection quantity and injection quantity) and (recirculated exhaust-gas mass flow downstream of the EGR cooler and recirculated exhaust-gas mass flow downstream of the EGR cooler and recirculated exhaust-gas mass flow downstream of the EGR cooler) and	>= <= >= <=	1400.00 2800.00 20.00 320.00 12.50 34.72	rpm rpm mm^ 3/rev mm^ 3/rev g/sec		В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					EGR controller is active and DPF is not in regeneration mode and	= TRUE -		
					(engine temperature and	>= 69.96 °C		
					engine temperature)	<= 122.96 °C		
					and (actual valve position of	>= 10.00 %		
					exhaust-gas recirculation) and (and control value provided for	<= 5.00 %		
					EGR cooling bypass) and ambient pressure and (>= 74.80 kPa		
					ambient temperature and	>= -7.04 °C		
					ambient temperature)	<= 3003.56 °C		
					and diagnostic performed in current dc	= FALSE -		
					and NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
					for time and basic enable conditions met:	>= 90.00 sec = see sheet - enable tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Regeneration Frequency	P2459	Detects a DPF that is regeneration too frequently by comparing a threshold to a soot model.	soot mass in the particulate filter	>	minimum of (((a) * (b) + (c)) - (f)) + ((((a) * (b) + (c)) - (f)) * (((d)) * (((a) * (b) + (c)) - (f)) * (e))) or 327.67	g	particulate filter regeneration - transition false to true	=	TRUE -	fail conditions exists for more than 1 event monitor runs 0.1 s rate whenever enable conditions are met	В
			with (a) engine out soot mass flow in the exhaust-gas	=	measured parameter	-	and last particulate filter regeneration successful	=	TRUE -		
			and with (b) delta time step	=	calculated parameter	-	or particulate filter regeneration must have been completed	=	TRUE -		
			and with (c) simulated maximum base soot mass from previous time step	=	measured parameter	-	and basic enable conditions met:	=	see sheet - enable tables		
			and with (d) factor for calculation of a soot mass value offset depending on the simulated maximum base soot mass (see Look-Up-Table #65) and with	=	0 to 450	g	and NO Pending or Confirmed DTCs:	=	see sheet - inhibit tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
System	Code	Description	(e) factor for determination of correction factor for ash in the particulate filter and with (f) amount of remaining soot from previous regen cycle	=	1 calculated parameter	factor	raidileteis		Sonditions	Nequireu	mum.
Diesel Particulate Filter - Soot Accumulation	P2463	Detects high levels of soot in the DPF as indicated by the soot model.	soot mass in the particulate filter	>	69.60	g	ignition on and basic enable conditions met: and NO Pending or Confirmed DTCs:	= =	TRUE - see sheet - enable tables see sheet - inhibit tables	fail conditions exists for 30 s test performed continuously 0.1 s rate	A
Exhaust Temperature Sensor 4 Performance	P246F	Detects a fault in the exhaust temperature sensor 4 performance by comparing the heat quantity on the sensor position to a threshold.	integrated heat quantity of exhaust gas temperature sensor 4 or integrated heat quantity of exhaust gas temperature sensor 4 with	< >	(a) / (b) * (c) / (d) * (e) * (f) (a) / (b) * (c) / (d) * (e) * (g)	-	exhaust gas system regeneration mode for time	= ^	FALSE - 1500.00 sec	fail conditions exists for xxs monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \	/alue	Parameters		Conditions		Required	Illum.
			(a) exhaust gas mass flow	=	calculated parameter	-	time since start	>	327.00	sec		
			and with (b) factor and with	=	4.60	g/sec	and (exhaust-gas temperature sensor 4	>	-60.04	°C		
			(c) heat capacity and with	=	1050.00	J/Kg/°C	and exhaust-gas temperature sensor 4	<	1999.96	°C		
			(d) factor and with	=	1000	kW/°C) and					
			(e) correction factor for heat flow quantity depending on exhaust gas mass flow for temperature sensor	=	1.00	factor	change in exhaust-gas temperature sensor 4	<	7.00	°C		
							for					
			and with (f) minimum permissible temperature deviation for exhaust gas temperature sensor	=	-100.00	°C	time and	=	5.00	sec		
			and with				engine operation point suitable for diagnostic (see Look-Up-Table #29)	=	0 to 255	-		
			(g) maximum permissible temperature deviation for exhaust gas temperature sensor 4	=	100.00	°C	for					
							time and change in modeled exhaust-	>=	0.05 4.00	sec °C		
							gas temperature sensor 4 and					

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and V	alue	Parameters		Conditions		Required	Illum.
							heat quantity for exhaust gas temperature sensor 4 and heat quantity for exhaust	>	10.00 12.00	kJ kJ		
							gas temperature sensor 4) and engine has been in normal mode for time or	>=	1.00	sec		
							engine has been in exhaust warm-up mode for time and basic enable conditions	>=	1.00 see sheet	sec		
							met: and		enable tables			
							NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Exhaust Gas Temperature (EGT) Sensor 4 Sensor Circuit Low Voltage	P2470	readings on the EGT 4 circuit, indicating an	particulate filter downstream temperature sensor voltage same as particulate filter downstream temperature	<	-60	V °C	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables	-	fail conditions exists for 3 s monitor runs 0.05 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary	Enable	Time	MIL
System Exhaust Gas Temperature (EGT) Sensor 4 Circuit High Voltage	P2471	Description Detects high voltage readings on the EGT 4 circuit, indicating an OOR high condition on the EGT 4	temperature sensor	>	2.21 999.6	°C	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	Required fail conditions exists for 3 s monitor runs 0.05 s rate whenever enable conditions are met	B B
Closed loop Reductant Injection Control at Limit- Flow too high	P249D	Detects an out of range high of the long term Reductant quantity adaptation factor	long term adaptation factor of Reductant quantity	>	1.69	factor	long term adaptation triggered NO Pending or Confirmed DTCs basic enable conditions met:	= TRUE - = see sheet - inhibit tables = see sheet - enable tables	fault exists for more than 0.1 s; monitor runs at 0.1 s whenever enable conditions are met	В
Closed loop Reductant Injection Control at Limit- Flow too low	P249E	Detects an out of range low of the long term Reductant quantity adaptation factor	long term adaptation factor of Reductant quantity	<	0.41	factor	long term adaptation triggered NO Pending or Confirmed DTCs	= TRUE - = see sheet - inhibit tables	fault exists for more than 0.1 s; monitor runs at 0.1 s whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold Logic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Cystem	Oouc	Bescription	Ontena		Eogio una ve		basic enable conditions met:	=	see sheet enable tables		required	mum.
Closed Loop Particulate Filter Regeneration Control At Limit - Temperature Too Low	P24A0	Detects insufficient HCI temperature. Temperature readings are compared to desired temperature values as an indication of an insufficient exhaust gas temperature.	commanded control value of the HCI temperature controller	>=	0.00	-	current engine operating point is suitable for monitoring deviation of exhaust gas temperature control - depending on engine speed and injection quantity (see Look-Up-Table #25)	=	0 to 1	-	fail conditions exists for 300 s monitor runs with 0.1 s rate whenever enable conditions are met	В
			and deviation from the temperature setpoint for HCl control loop	>	maximum of (a) and (b+c)	-	for time	>	30.00	sec		
			with (a) temperature threshold value and with	=	100.00	°C	and (exhaust gas temperature control is active	=	TRUE			
			(b) temperature value for threshold of monitoring and with (c) basic temperature threshold value for monitoring	==	100	°C	(temperature upstream of the oxidation catalyst	>	224.96	°C		
							and (particulate filter temperature and	>	229.96	°C		
							(particulate filter temperature or	<	719.96	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					particulate filter temperature for activated post injection)) and release status means (vehicle speed and vehicle speed	< 749.96 °C = TRUE - >= 14.92 mph <= 124.30 mph		
					and Actual time spent in coastdown mode) and basic enable conditions met: and NO Pending or Confirmed DTCs:	< 60.00 sec = see sheet - enable tables = see sheet - inhibit tables		
Closed Loop Particulate Filter Regeneration Control At Limit - Temperature Too High		Detects excessive HCI temperature. Actual HCI controller ratio and temperature readings are compared to desired HCI controller ratio and temperature values as an indication of an excessive exhaust gas temperature.	commanded control value of the HCI temperature controller and deviation from the temperature setpoint for HCI control loop	<= 0.00 - < minimum - of (a) and (b+c-(d-	current engine operating point is suitable for monitoring deviation of exhaust gas temperature control - depending on engine speed and injection quantity (see Look-Up-Table #26)	= 0 to 1 -	fail conditions exists for 300 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction			Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Va	lue	Parameters	Conditio	ns	Required	Illum.
			with (a) and with	-75.00	°C	and (exhaust gas temperature control is active	= TRUE			
			(b) temperature value for threshold of monitoring with (c) basic temperature threshold value for monitoring	100	°C	means (temperature upstream of the oxidation catalyst	> 224.96	°C		
						and (particulate filter temperature and (> 229.96			
						particulate filter temperature or	< 719.96	°C		
						particulate filter temperature for activated post injection)	< 749.96	°C		
						and release status means (= TRUE	-		
						vehicle speed and	>= 14.92	mph		
						vehicle speed and	<= 124.30			
						Actual time spent in coastdown mode) and	< 60.00			
						basic enable conditions met: and	= see she enable tables	;		

Component /	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	,	Threshold ogic and Val	110	Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Criteria		ogic and van	ue	NO Pending or Confirmed DTCs:	=	see sheet - inhibit tables	Required	mum.
ECM Power Relay Circuit Performance	P2510	Detects stuck power relay that is not responding to ECM commands to power down or a relay that is opening too early in power down. Stuck on is determined by timer values longer than possible if relay opened at end of after run.	counter value out of EEPROM for open the main relay	>	1.00		and engine pre drive and basic enable conditions met:		TRUE - see sheet - enable conditions	fail conditions exists for 0.02 s monitor runs once per driving cycle during predrive with 0.02 s rate whenever enable conditions are met	В
			sticky main relay is detected	=	TRUE	-	ignition off	=	TRUE -	fail conditions exists for 0.02 s monitor runs once per driving	
			means time after request to open the main relay	>	1.40		and engine pre drive and	=	FALSE -	cycle during predrive with 0.02 s rate whenever enable	

Component /	Fault Code	Monitor Strategy	Primary Malfunction Criteria		Threshol		Secondary		Enable Conditions		Time	MIL Illum.
System	Code	Description	Criteria		ogic and V	alue	Parameters battery voltage and basic enable conditions met: and NO Pending or Confirmed DTCs:	> =	0.50	- -	Required conditions are met	ilium.
Transition Torque Request Signal Message Counter Incorrect	P2544	Detects implausible torque request information received from the TCM	Path 1: amount of errors in consecutive frames received from TCM with number of consecutive frames or Path 2: number of protection value errors in TCM message	\= \ \ \ \	7.00 15.00	counts	ignition on and new message received and basic enable conditions met: and NO Pending or Confirmed DTCs:		TRUE TRUE see sheet enable tables see sheet inhibit tables		fail conditions exist for 0.005 s test performed continuously 0.005 s rate	В
Turbocharger Boost Control Position Sensor Circuit Low Voltage	P2564	Detects low voltage readings on the turbo boost control position sensor circuit, indicating an OOR low condition on the circuit		<	0.15	V %	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables	-	fail conditions exists for 5 s test performed continuously 0.01 s rate	А

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshol Logic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Cyotom	0000	Dooripaon	Omona		Logio una v	uiuo	i didiliotoro		Conditions		required	mum.
Turbocharger Boost Control Position Sensor Circuit High Voltage	P2565	Detects high voltage readings on the turbo boost control position sensor circuit, indicating an OOR high condition on the circuit	voltage of boost pressure position sensor	>	4.75	V	ignition on	=	TRUE		fail conditions exists for 5 s test performed continuously 0.01 s rate	A
			same as boost pressure position	>	95	%	and basic enable conditions met:	=	see sheet enable tables	-		
Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck Low		, ,	turbo charger control deviation calculated out of difference between desired and actual value	>	15.00	%	engine speed	>=	-16384.00	rpm	fail conditions exists for 10 s monitor runs with 0.02 s rate whenever enable	В
							engine speed (see Look-Up- Table #91)	>	600 to 850	rpm	conditions are met	
Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck High	P2599	,	turbo charger control deviation calculated out of difference between desired and actual value	<	-15.00	%	for time (see Look-Up-Table #92) and	>	30to 327.67	sec		
							(engine coolant temperature	>=	69.96	°C		
							and engine coolant temperature) and	<=	122.96	°C		
							(ambient temperature and	>=	-15.04	°C		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					ambient temperature) and offset learning for turbo charger (VNT) actuator position sensor is active during idling - in order to compensate sensor drift and valve aging the valve is closed and opened fully once in a driving cycle during engine idling, the read positions for opening and closing are averaged and used for the calculation of offset drift of the valve and offset learned since last clearing of fault code memory and basic enable conditions met: and No Pending or Confirmed DTCs:	= TRUE - = see sheet - enable tables = see sheet - inhibit tables		
Control Module Ignition Off Timer Performance	P2610	Detects a failure in the engine off timer calculation during ECM power up or afterrun, when the EOT timer IC is not responding	amount of retries in case of communication or bus error	> 5.00 counts	ignition on and engine pre drive and	= TRUE -	fail conditions exists for 0.01 s monitor runs once per driving cycle with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable	Time	MIL
System	Code	Description	Criteria		Logic and Val	ue	Parameters		Conditions	Required	Illum.
							basic enable conditions met:	=	see sheet - enable tables		
				_		_					
		Detects a failure in the engine off timer if during the after run the internal SW timer and the EOT do not correlate. A failure is detected when the respective timers are started after a calibration time then both are stopped					time since engine post drive/ afterun	<	20.00 sec	fail conditions exists for 0.01 s monitor runs once per driving cycle with 0.01 s rate whenever enable conditions are met	
			acquired stop counter time or	<	((a) - (b - c))*d	-	and engine post drive/ afterun	=	TRUE -		
			Path 2:				and				
			acquired stop counter time	>	((a) + (b - c))*d	-	basic enable conditions met:	=	see sheet - enable tables		
			where (a) and	=	100	%					
			(b) tolerance threshold and	=	17.19	%					
			(c) correction factor and	=	7.5	%					

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		Detects an interrupted supply voltage.	(d) system time since engine post drive/ afterun) permanent supply voltage is interrupted	= calculated - parameter = TRUE -	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for more than 1 event monitor runs once per driving cycle with 0.01 s rate whenever enable conditions are met	
Fuel Injector Calibration Not Programmed	P268A	programmed Injector Calibration Data (IQA) in ECM	Path 1: the checksum of the injector adjustment code words is correct	= FALSE -	engine pre drive and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exist for 1 s monitor runs once per driving cycle during predrive with 1 s rate	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Injector Data Incorrect (IQA)	P268C	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 1 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 1 are valid and basic enable conditions met: and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exist for 1 s test performed continuously with 1 s rate	A
Cylinder 2 Injector Data Incorrect (IQA)	P268D	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 2 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 2 are valid and basic enable conditions met: and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exist for 1 s test performed continuously with 1 s rate	A
Cylinder 3 Injector Data Incorrect (IQA)		in IQA values between	IQA (injection quantity adjustment) value of injector 3 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 3 are valid	= TRUE -	fail conditions exist for 1 s test performed continuously with 1 s rate	А

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and basic enable conditions met: and NO Pending or Confirmed DTCs:	= see sheet - enable tables = see sheet - inhibit tables		
Cylinder 4 Injector Data Incorrect (IQA)	P268F	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 4 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 4 are valid	= TRUE -	fail conditions exist for 1 s test performed continuously with 1 s rate	A
					and basic enable conditions met: and NO Pending or Confirmed DTCs:	see sheet - enable tablessee sheet - inhibit tables		
Cylinder 5 Injector Data Incorrect (IQA)	P2690	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 5 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 5 are valid	= TRUE -	fail conditions exist for 1 s test performed continuously with 1 s rate	А
					and basic enable conditions met: and	= see sheet - enable tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				-	NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		
Cylinder 6 Injector Data Incorrect (IQA)	P2691	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 6 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 6 are valid and basic enable conditions met: and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exist for 1 s test performed continuously with 1 s rate	A
Cylinder 7 Injector Data Incorrect (IQA)	P2692	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 7 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	= FALSE -	transmitted IQA data from GPCM (glow plug module) for cylinder 7 are valid and basic enable conditions met: and NO Pending or Confirmed DTCs:	= TRUE - = see sheet - enable tables = see sheet - inhibit tables	fail conditions exist for 1 s test performed continuously with 1 s rate	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions		Required	Illum.
Cylinder 8 Injector Data Incorrect (IQA)	P2693	Detects a miss match in IQA values between ECM and GPCM	IQA (injection quantity adjustment) value of injector 8 transmitted via CAN from GPCM (glow plug module) match with the stored ECM value	=	FALSE	-	transmitted IQA data from GPCM (glow plug module) for cylinder 8 are valid	=	TRUE		fail conditions exist for 1 s test performed continuously with 1 s rate	A
							and basic enable conditions met:	=	see sheet enable tables	-		
							and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-		
Exhaust Nox Concentration High - Unknown Reason	P2BAD	Compare EWMA filtered NOx conversion efficiency of SCR catalyst with a threshold value	EWMA filtered delta SCR catalyst efficiency of (a) - (b)	<	0.00	factor	NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-	fail conditions exists for more than 1 event monitor runs with 0.01 s rate	А
			where (a) measured SCR catalyst efficiency	=	calculated parameter	-	for time	>	300.00	sec	whenever enable conditions are met	
			(b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	=	calculated parameter	-	Status of NOx signal of upstream NOx sensor (please see the definition)	=	Active	-		
			ioi details)				for time Status of NOx signal of downstream NOx sensor (please see the definition)	> =	60.00 Active	sec -		
							for time	>	60.00	sec		
							Release of dosing strategy (please see the definition)	=	TRUE	-		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Condition	5	Required	Illum.
					for time (a) Turn on delay time 1 of status metering strategy (b) Turn on delay time 2 of status metering strategy)	>= (a) + (b) 380.00 20.00	sec sec sec		
					(Status for disabling SCR Efficiency monitoring following an SCR Adaptation completion (please see the definition)	= FALSE	-		
					for time (a) Debounce time after	> (a) + (b) > 0.50	sec sec		
					pre controlled dosing over (b) delay time the status of disabling SCR Efficiency monitoring	> 80.00	sec		
					or integrated upstream NOx)	>= 3276.70	g		
					(Status of pre controlled dosing (please see the definition)	= FALSE	-		
					for time (a) Debounce time after pre controlled dosing off	> (a) + (b) = 0.50	sec		
					(b) Delay time after pre controlled dosing off or	= 180.00	sec		
					integrated upstream NOx) (>= 3276.70	g		
					Decrease of Reductant load level (please see the definition)	= FALSE	-		
					for time)	> 300.00	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(Average slow filtered NOx mass flow upstream SCR for time Monitor disable time based on average NOx mass flow and the time (see Look-Up- Table #88)	<= 0.12 g/sec > 0.50 sec > 0 to 85 sec		
					for time with ((Delta SCR temperature (see Look-Up-Table #85) or	> 15.00 sec <= 23.96 to °C 74.96		
					Delta SCR temperature Delta SCR temperature or	> 524.96 °C < 199.96 °C		
					Initialization time of temperature gradient calculation	< 2.50 sec		
					or Delta SCR temperature or	< 229.96 °C		
					Delta SCR temperature for time	> 499.96 °C 10.00 sec		
					normalized HC load in SCR catalyst)	> 21.00 facto r		
					ambient pressure ambient temperature	>= 74.80 kPa >= -7.04 °C		
					(Stuck reductant dosing valve fault was healed last particulate filter regeneration successful)	= FALSE - = TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					Status of the SCR adaptation plausibility check active (please see the definition) for time	= FALSE - > 600.00 sec		
) Reductant Delivery performance completed this drive cycle	= FALSE -		
					(engine speed engine speed for time)	>= 1000.00 rpn <= 3000.00 rpn > 0.00 sec	1	
					SCR estimated current Reductant load (see Look- Up-Table #77)	>= 0.06 to g 1.3		
					SCR estimated current Reductant load (see Look- Up-Table #76)	<= 0.2 to 2.7 g		
					Difference between nominal and estimated Reductant (see Look-Up-Table #79)	>= -0.35 to - g 0.05		
					Difference between nominal and estimated Reductant (see Look-Up-Table #78)	<= 0.05 to g 0.2		
					SCR in Pre-Control State (please see the definition)	= FALSE -		
					Disable after adaptation with	= FALSE -		
					for time)	> 600.00 sed		
					(((a) - (b) (see Look-Up-Table #86) for time)	<= 44.96 to °C 74.96 > 0.00 sec		
					(

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					(a) - (b) (see Look-Up-Table #87) for time (a) upstream SCR catalyst temperature	>= -40.04 to - °C 0.04 > 0.00 sec = measured - parameter		
					(b) downstream SCR catalyst temperature	= measured - parameter		
					Integrated NOx mass upstream SCR for time	> 3.00 g > 0.00 sec		
					Average SCR Temperature Average SCR Temperature Downstream SCR catalyst temperature	<= 399.96 °C >= -3549.94 °C <= 3003.56 °C		
					Downstream SCR catalyst temperature Filtered and delayed upstream NOx raw emission	>= -3549.94 °C <= 750.00 ppm		
					Filtered and delayed upstream NOx raw emission	>= 100.00 ppm		
					Filtered and delayed NOx raw emission mass flow upstream of SCR	<= 250.00 mg/s		
					Filtered and delayed NOx raw emission mass flow upstream of SCR	>= 0.07 g/sec		
					Filtered exhaust gas mass flow Filtered exhaust gas mass	<= 236.11 g/sec >= -910.22 g/sec		
					flow MAP for valid engine operation points for SCR efficiency monitoring (see	= 0 to 1 facto		
					Look-Up-Table #84) for time Inverse calculated accelerator pedal value	> 0.00 sec > 5.00 %		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					For time EWMA fast initialization mode: filter coefficient for fast initialization number of SCR efficiency	> 0.00 sec = 0.50 facto r >= 2.00 coun		
					measurements for fast initialization mode EWMA Rapid Response mode: EWMA filtered delta SCR catalyst efficiency (a) - (b)	t > 0.10 facto r < -0.02 facto		
					(a) measured SCR catalyst efficiency	r = measured - parameter		
					(b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	= measured - parameter		
					offset-corrected modeled SCR catalyst efficiency (please see the general description for details) filter coefficient for Rapid Response mode	> 0.00 facto r = 0.30 facto r		
					number of SCR efficiency measurements for Rapid Response mode EWMA filtered value too	>= 6.00 coun t		
					small in Fast Init. And Rapid Response modes: EWMA filtered delta SCR catalyst efficiency of (a) - (b)	< 0.00 facto r		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		·		,	(a) measured SCR catalyst efficiency (b) offset-corrected modeled SCR catalyst efficiency (please see the general description for details)	= measured - parameter = measured - parameter		
					EWMA stabilized mode: filter coefficient for stabilized mode number of SCR efficiency measurements for stabilized mode	= 0.10 facto r = 1 coun t		
					basic enable conditions met:	= see sheet - enable tables		
CAN A BUS OFF	U0073	BUS A off monitoring	CAN A Bus-Off reported by CAN hardware	= TRUE -	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable tables	fail conditions exists for 5 s test performed continuously 0.01 s rate	В
CAN B BUS OFF	U0074	BUS B off monitoring	CAN B Bus-Off reported by CAN hardware	= TRUE -	ignition on	= TRUE -	fail conditions exists for 5 s test performed continuously 0.01 s rate	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and V	aiue	Parameters basic enable conditions met:	=	conditions see sheet enable tables	-	Required	Illum.
Lost Communications with Transmission Control Module	U0101	communication	time since last message from transmission control module was received	>	0.18	sec	ignition on for time and battery voltage and battery voltage and basic enable conditions met: and NO Pending or Confirmed DTCs:	= >= <= =	3.00 9.00 16.00 see sheet enable tables see sheet inhibit tables	sec V V	fail conditions exists for 10 s test performed continuously 0.01 s rate	В
Lost Communications with Glow Plug Control Module	U0106	communication	time since last message from glow plug control module was received	>	0.25	sec	ignition on for time and battery voltage and	>= >=	3.00 9.00	sec	fail conditions exists for 10 s test performed continuously 0.02 s rate	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Threshold ogic and Va		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
- Oystein	Code	Безсприон	Ontena		ogic and va		battery voltage and basic enable conditions met: and NO Pending or Confirmed DTCs:	<= = =	see sheet enable tables see sheet inhibit tables	- -	Required	mum.
Lost Communication with Reductant Control Module	U010E	CAN frame not received after the specified number of times	counts up when message is not received in the time out interval	>	40.00	counts	CAN Bus is Active Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	=	TRUE 5.00 16.00 9.00	- sec V	fail conditions exists for more than 5 sec monitor runs with 0.1 s rate	A
		CAN message sliding window detection Check of level sensor	DLS1 Sliding Window error counter within a number of message frames	>=		counts	CAN Bus is Active Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	=	TRUE 5.00 16.00 9.00	- sec V	monitor runs with 1 s rate	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		ogic and		Parameters		Conditions		Required	Illum.
		CAN message sliding window detection Check of temperature sensor	DLS2 Sliding Window error counter within a number of message frames	\ 	9.00	counts	CAN Bus is Active Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time	= >	TRUE TRUE 5.00	- sec	monitor runs with 1 s rate	
		CAN manage eliding	DI 62 Cliding Window		9.00	opunto	battery voltage battery voltage	>	16.00 9.00	V	monitor was	
		window detection Check of error states	DLS3 Sliding Window error counter within a number of message frames	=	9.00	counts	CAN Bus is Active Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= > < >	TRUE 5.00 16.00 9.00	sec V V	monitor runs with 1 s rate	
Lost Communications with Auxiliary Heater Control Module	U0166	Detects loss of communication between ECM (on-board control unit) and Auxiliary Heater Control Module	time since last message from auxiliary heater control module was received	>	2.50	sec	for time and battery voltage and battery voltage and battery voltage	= >= >= <=	3.00 9.00 16.00	sec V	fail conditions exists for 12 s test performed continuously 0.01 s rate	Special C

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					basic enable conditions met: and NO Pending or Confirmed DTCs:	= see sheet - enable tables = see sheet - inhibit tables		
Engine Out NOx Sensor Can Message #1		Detects a failure when a certain number of Engine Out NOx sensor relative NOx concentration messages within a defined message group checksum or rolling count values are incorrect	Error count for engine out NOx relative NOx concentration message group	>= 8.00 counts	and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and Engine out NOx sensor CAN Message 1 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on	= TRUE - = TRUE - = TRUE - = TRUE -	fault exists for 1 message group; monitor runs whenever enable conditions are met.	A

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and		Parameters	(Conditions	s	Required	Illur
		Engine Out NOx sensor linear lambda messages within a defined message group checksum or rolling count values	Error count for engine out NOx sensor status message group	>=	8.00	counts	Engine out NOx sensor CAN Message 1 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
		are incorrect					and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and Engine out NOx sensor	=	FALSE	-		
							CAN Message 1 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on	=	TRUE	-		
			counts up when message is not received in the base time interval	>	5.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= >> <	TRUE 3 9.8 18.1	- sec V	fault exists for more than 20 seconds; monitor runs every 0.05 s whenever enable conditions are met.	
							, ,					

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh	old	Secondary		Enable		Time	M
System	Code	Description	Criteria	L	ogic and		Parameters		Conditions		Required	III
Engine out NOx Sensor CAN Message #2	U029D	a certain number of Engine Out NOx sensor error messages within a defined message group checksum or rolling count values	Error count for engine out NOx sensor error status message group	>=	8.00	counts	Engine out NOx sensor CAN Message 2 Received	=	TRUE	-	fault exists for 1 message group ; monitor runs whenever enable conditions are met.	
		are incorrect					and Inhibit Status (no inhibiting faults) (No pending or stored DTC)	=	FALSE	-		
							and Engine out NOx sensor CAN Message 2 Enabled and	=	TRUE	-		
							No rolling count or protection value errors. (sliding window errors)		TRUE	-		
							and ignition on	=	TRUE	-		
		Detects a failure when a certain number of Engine Out NOx sensor linear lambda messages within a defined message group checksum or rolling count values are incorrect	Error count for engine out NOx linear lambda signal message group	>	8.00	counts	Engine out NOx sensor CAN Message 2 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
		are morreot					and Inhibit Status (no inhibiting faults) (No pending or stored DTC)	=	FALSE	-		
							and Engine out NOx sensor CAN Message 2 Enabled	=	TRUE	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		hreshold c and Value	Secondary Parameters	C	Enable Conditions	;	Time Required	MIL Illum.
						and No rolling count or protection value errors. (sliding window errors) and ignition on	=	TRUE	-		
		NOx Sensor CAN Message #2 frame not received after the specified number of times	counts up when message is not received in the base time interval	> 5	5.00 counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	=	TRUE 3 9.8 18.1	- sec V V	fault exists for more than 20 seconds; monitor runs every 5 ms whenever enable conditions are met.	
Engine out Nox Sensor CAN Message #3	U029D	Engine out NOx sensor CAN message #3 frame not received after the specified number of times	counts up when message is not received in the base time interval	> 5	5.00 counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= >> <	TRUE 3 9.8 18.1	sec V V	fault exists for more than 20 seconds; monitor runs every 5 ms whenever enable conditions are met.	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh	old	Secondary	E	nable	Time	MIL
System	Code	Description	Criteria		Logic and	Value	Parameters	Coi	nditions	Required	Illum
		a certain number of Engine Out NOx sensor oxygen concentration messages within a defined message group checksum or rolling count values	Error count for engine out NOx oxygen concentration signal message group	>=	8.00	counts	Engine out NOx sensor CAN Message 3 Received	= '	TRUE -	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
		are incorrect					and Inhibit Status (no inhibiting faults) (No pending or stored DTC)	= F	FALSE -		
							and Engine out NOx sensor CAN Message 3 Enabled and		TRUE -		
							No rolling count or protection value errors. (sliding window errors) and ignition on		TRUE -		
		Engine Out NOx sensor binary lambda messages within a defined message group checksum or rolling count values	Error count for engine out NOx binary lambda signal message group	>=	8.00	counts	Engine out NOx sensor CAN Message 3 Received	= '	TRUE -	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
		are incorrect					and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and	= F	FALSE -		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Thresho	alue	Secondary Parameters Engine out NOx sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on	=	Enable Conditions TRUE TRUE	- -	Time Required	MIL Illum.
Engine out Nox Sensor CAN Message #4	U029D	Engine out NOx sensor CAN message #4 frame not received after the specified number of times	counts up when message is not received in the base time interval	>	25.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= >> <	TRUE 3 9.8 18.1	sec V V	fault exists for more than 20 seconds; monitor runs every 5 ms whenever enable conditions are met.	
		Detects a failure when a certain number of Engine Out NOx sensor heater resistance messages within a defined message group checksum or rolling count values are incorrect	Error count for engine out NOx heater resistance signal message group	>=	8.00	counts	Engine out NOx sensor CAN Message 4 Received	=	TRUE	-	fault exists for 1 message group ; monitor runs whenever enable conditions are met.	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		reshold and Value	Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
dystem	Odde	Description	Ontena	Logic	ound value	Inhibit Status (no inhibiting faults) (No pending or stored DTC)	=	FALSE	-	required	mam.
						and Engine out NOx sensor CAN Message 3 Enabled and	=	TRUE	-		
						No rolling count or protection value errors. (sliding window errors) and		TRUE	-		
						ignition on	=	TRUE	-		
Engine out Nox Sensor CAN Message #5	U029D	Engine out NOx sensor CAN message #5 frame not received after the specified number of times	counts up when message is not received in the base time interval	> 25	5.00 counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	^ ^ V	3 s	- sec V V	fault exists for more than 20 seconds; monitor runs every 100 ms whenever enable conditions are met.	
Post Catalyst NOx Sensor CAN Message #1	U029E	Detects a failure when a certain number of Post Catalyst NOx sensor relative NOx concentration messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx sensor relative NOx concentration message group	>= 8	.00 counts	Post Catalyst NOx sensor CAN Message 1 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	A

and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and	uired III	Illum.
Inhibit Status (no inhibiting faults) (No pending or stored DTC) and		
NOx sensor CAN Message = TRUE - 1 Enabled and		
No rolling count or = TRUE - protection value errors. (sliding window errors) and		
ignition on = TRUE -		
a certain number of Post Catalyst NOx sensor status message group sensor linear lambda messages within a defined message	cists for 1 ge group ; cor runs enever able ions are net.	
and Inhibit Status (no inhibiting = FALSE - faults) (No pending or stored DTC)		
and NOx sensor CAN Message = TRUE - 1 Enabled		
and No rolling count or = TRUE - protection value errors. (sliding window errors)		
and ignition on = TRUE -		

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresh		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and		Parameters	(Conditions	6	Required	Illum.
		Post Catalyst NOx sensor CAN message #1 frame not received after the specified number of times	counts up when message is not received in the base time interval	۸	5.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= > > <	TRUE 3 9.8 18.1	sec V V	fault exists for more than 21 seconds; monitor runs every 5 ms whenever enable conditions are met.	
Post Catalyst NOx Sensor CAN Message #2	U029E	Detects a failure when a certain number of Post Catalyst NOx sensor error messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx sensor error status message group	>=	8.00		and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and NOx sensor CAN Message 2 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on	= = =	TRUE TRUE TRUE		fault exists for 1 message group; monitor runs whenever enable conditions are met.	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters	(Conditions		Required	Illum.
		Detects a failure when a certain number of Post Catalyst NOx sensor linear lambda messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx linear lambda signal message group	>=	8.00	counts	Post Catalyst NOx sensor CAN Message 2 Received	II	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
							and Inhibit Status (no inhibiting faults) (No pending or stored DTC)	=	FALSE	-		
							and NOx sensor CAN Message 2 Enabled and	=	TRUE	-		
							No rolling count or protection value errors. (sliding window errors)	=	TRUE	-		
							and ignition on	=	TRUE	-		
		Message #2 frame not received after the	counts up when message is not received in the base time interval	>	5.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	=	TRUE 3 9.8 18.1	sec V V	fault exists for more than 21seconds; monitor runs every 5 ms whenever enable conditions are met.	

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters	(Conditions	3	Required	Illum.
Post Catalyst Nox Sensor CAN Message #3	U029E	Post Catalyst NOx sensor CAN message #3 frame not received after the specified number of times	counts up when message is not received in the base time interval	۸	5.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= > > <	TRUE 3 9.8 18.1	sec V V	fault exists for more than 21 seconds; monitor runs every 5 ms whenever enable conditions are met.	
		Detects a failure when a certain number of Post Catalyst NOx sensor oxygen concentration messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx sensor oxygen concentration signal message group	>=	8.00	counts	Post Catalyst NOx sensor CAN Message 3 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
							and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and NOx sensor CAN Message 3 Enabled	=	FALSE TRUE	-		
							and No rolling count or protection value errors. (sliding window errors) and ignition on	=	TRUE			

Code	Description Detects a failure when	Criteria		ogic and \							
	Detects a failure when	I —		ogic and \		Parameters		onditions		Required	III
	a certain number of Post Catalyst NOx sensor binary lambda messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx sensor binary lambda signal message group	>=	8.00	counts	Post Catalyst NOx sensor CAN Message 3 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
						and Inhibit Status (no inhibiting faults) (No pending or stored DTC)	=	FALSE	-		
						NOx sensor CAN Message 3 Enabled	=	TRUE	-		
						No rolling count or protection value errors. (sliding window errors) and	=	TRUE	-		
						ignition on	=	TRUE	-		
U029E	Post Catalyst NOx sensor CAN message #4 frame not received after the specified number of times	counts up when message is not received in the base time interval	>	25.00	counts	Can Bus Initialized (CAN Bus is Active)	=	TRUE	-	fault exists for more than x seconds; monitor runs every 5 ms whenever	
						ignition for time battery voltage battery voltage	> > <	3 9.8 18.1	sec V V	enable conditions are met.	
	U029E	rolling count values are incorrect U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified	U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified counts up when message is not received in the base time interval	V029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified counts up when message is not received in the base time interval	rolling count values are incorrect U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified counts up when message is not received in the base time interval	U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified Total values are incorrect Counts up when message is not received in the base time interval Post Catalyst NOx sensor CAN message time interval	rolling count values are incorrect and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and NOx sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified number of times Counts up when message is not received in the base time interval > 25.00 counts Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage	rolling count values are incorrect and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and NOx sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on = U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified number of times Post Catalyst NOx counts up when message is not received in the base time interval Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage	rolling count values are incorrect and Inhibit Status (no inhibiting faults) (No pending or stored DTC)) and NOx sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on = TRUE U029E Post Catalyst NOx sensor CAN message #4 frame not received after the specified number of times Consisting of: ignition for time time base time interval Consisting of: ignition for time battery voltage > 9.8	rolling count values are incorrect and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and NOx sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on = TRUE - #4 frame not received after the specified number of times #4 frame not received after the specified number of times #5 consisting of: ignition for time	rolling count values are incorrect and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and Nox sensor CAN Message 3 Enabled and No rolling count or protection value errors. (sliding window errors) and ignition on = TRUE - Would be a trained by the protection of the protection

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and \		Parameters		Conditions		Required	Illum.
		Detects a failure when a certain number of Post Catalyst NOx sensor heater resistance messages within a defined message group checksum or rolling count values are incorrect	Error count for post catalyst NOx sensor heater resistance signal message group	>=	8.00	counts	Post Catalyst NOx sensor CAN Message 4 Received	=	TRUE	-	fault exists for 1 message group; monitor runs whenever enable conditions are met.	
							and Inhibit Status (no inhibiting faults) (No pending or stored DTC) and	=	FALSE	-		
							NOx sensor CAN Message 4 Enabled and	=	TRUE	-		
							No rolling count or protection value errors. (sliding window errors) and	=	TRUE	-		
							ignition on	=	TRUE	-		
Post Catalyst Nox Sensor CAN Message #5	U029E	Post Catalyst NOx sensor CAN message #5 frame not received after the specified number of times	counts up when message is not received in the base time interval	>	25.00	counts	Can Bus Initialized (CAN Bus is Active) consisting of: ignition for time battery voltage battery voltage	= =	TRUE 3 9.8 18.1	- sec V	fault exists for more than 21 seconds; monitor runs every 100 ms whenever enable conditions are met.	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		gic and V		Parameters		Conditions	5	Required	Illum.
Glow Plug Control Module Performance	P064C	Electronic circuitry determines fault with GP switch	Glow Plug Current and Glow plug is commanded and voltage at glow plug	= =	6.6 On 0	volts	glow plugs are commanded on DTCs P163C, P0671- P0678	=	True Not set		fail conditions exists for 3.5 seconds. monitor runs with 0.5 s rate whenever enable conditions are met.	В
		Checksum error between calculated and stored values are compared	ROM error: Checksums match	=	NO		Module power		On		fail conditions exists for 4.5 s. monitor runs with 1.5 s rate whenever enable conditions are met.	
		Compariarson of read write values	RAM error: Read write values match	=	NO		Module power		On		fail conditions exists for 3.2 seconds. monitor runs with 0.2 s rate whenever enable conditions are met.	
		Checksum error between calculated and stored values	EEPROM error: Checksums match	=	NO		Module power		On		fail conditions exists for 3.2 seconds. monitor runs with 0.2 s rate whenever enable conditions are met.	
		measured voltage of charge pump is determined to be out of tolerance	Charge Pump Under voltage	"	Battery voltage at GPCM + 7	volts	Battery voltage at GPCM	>	6		fail conditions exists for 3.13 seconds. monitor runs with 0.13 s rate whenever enable conditions are met.	
		measured voltage of charge pump is determined to be out of tolerance	Charge Pump Over voltage	>=	Battery voltage at GPCM + 18	volts	Battery	<	19.9	volts	fail conditions exists for 3.16 seconds. monitor runs with 0.16 s rate whenever enable conditions are met.	

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	-	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	gic and V	alue	Parameters		Condition	S	Required	Illum.
Cyclon	9946	Elecrtonic circuitry determines that the reverse polarity protection voltage drop is in range	GPCM reverse polarity switch "high voltage drop" Path 1 [Battery voltage at GPCM - mean glow plug voltage value] Path 2 (Battery voltage at GPCM - mean glow plug voltage value with charge pump off) - (Battery - mean glow	>	0.300	volts	glow plugs are commanded Battery voltage at GPCM GP current GP current P0671,P0672, P0675, P0676 Battery voltage at GPCM stable for 30ms	=	On 6 6 60 Not set 2	volts amps amps volts	Path1: fail conditions exists for 9 seconds. monitor runs with 6 s rate whenever enable conditions are met. Path2: fail conditions exists for 13 seconds. monitor runs with 10 s rate whenever	
		Internal and external Watchdogs are monitored for interuption Monitor for undefined instruction code interupt Monitor for osolation stop detection	plug voltage value with charge pu GPCM running reset: number of running resets or undefined instruction code detected or Osolation stop detection	>	9 events in a row		none				enable conditions are met. fail conditions exists for 5 seconds. monitor runs with 2 s rate whenever enable conditions are met.	
		GMLAN Battery voltage from ECM is compared to GPCM internal measured battery voltage	internal and external value of battery voltage too high abs[GPCM internal measured battery voltage - GMLAN Battery voltage]	^	3	volts	glow plugs are commanded GMLAN battery signal glow command message Battery voltage at GPCM RPM RPM	= = > = >=	On valid valid 6 10 400		fail conditions exists for 3.19 seconds. monitor runs with 0.19 s rate whenever enable conditions are met.	
		monitor internal chip supply voltage	system basic chip VSUPLOW : internal chip supply voltage	<=	5.8	volts	Intake Air Heater commanded Battery supply at GPCM	>	On 9		fail conditions exists for 3.13 seconds. monitor runs with 0.13 s rate whenever enable conditions are met.	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V		Secondary Parameters		Enable Condition	s	Time Required	MIL Illum.
		measure temperature of the SBC	system basic chip (SBC) over temperature: temperature of the high side switch inside the SBC	^	155	deg C	Internal GPCM temperature	<	100	,	fail conditions exists for 3.13 seconds. monitor runs with 0.13 s rate whenever enable conditions are met.	
		Electronic circuitry detects a failure in the NOx sensor power supply	NOx sensor power supply fault: Path1: DC/DC booster current. For Path 2: DC/DC booster current. Path 3: voltage at main switch Path 4: (DC/DC Booster	^ ^ /	25 640 60 (by hardware protectio n (time varies with temperat ure)) 0	amps msec amps volts	Battery voltage at the GPCM Battery voltage at the GPCM	^ II	6 8 to 14	volts	fail conditions exists for 9 seconds. monitor runs with 6 s rate whenever enable conditions are met.	
			voltage - GPCM battery voltage)									
		Checksum error between calculated and stored values	DEF heater current not calibrated.: Checksums match	=	No		Ignition on				fail conditions exists for 3.2 seconds. monitor runs with 0.2 s rate whenever enable conditions are met.	
Glow Plug 1 through 8 Circuit Fault	P0671- P0678	glow plug open: electronic circuitry determines a fault exists on GP circuit	Glow Plug Current and voltage at glow plug pin	>	4.25 and 6.0	amps	Ignition - glow plugs are commanded on P163D,P163C Supply voltage	= >	On 5 not set 6	volts	fail conditions exists for 1.13 seconds. monitor runs with 0.13 s rate whenever enable conditions are met.	В

Component /	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Le	Threshol ogic and V		Secondary Parameters		Enable Condition	6	Time Poguired	MIL
System	Code				60					3	Required Path1: fail	Illum.
		glow plug short: electronic circuitry determines a fault	Path 1: Glow Plug Current		80	amps	Ignition glow plug command over temperature	= =	on on false		conditions exists for 1.13 seconds.	
		exists on GP circuit	Path 2: Hardware over current				condition over voltage condition abs[Battery supply at GPCM - IGN voltage at GPCM]	= <	false 6.0	volts	monitor runs with 0.13 s rate whenever enable conditions are met. Path2: fail conditions exists for 1.26 seconds. monitor runs with 0.26 s rate whenever enable conditions are met.	
		glow plug high resistance: electronic circuitry determines a fault exists on GP circuit	Glow Plug Resistance AND Glow Plug Current		1.0 4.25	ohm	Ignition on Battery voltage at GPCM glow plugs are commanded on over temperature condition over voltage condition abs[Battery supply at GPCM - IGN voltage at GPCM]		on 7.0 on false false 7.0		fail conditions exists for 1.16 seconds. monitor runs with 0.16 s rate whenever enable conditions are met.	
		Glow plug low resistance: electronic circuitry determines a fault exists on GP circuit	Glow Plug Resistance	<	0.25	ohm	glow plugs are commanded on over temperature condition over voltage conditionabs[Battery supply at GPCM - IGN voltage at GPCM]	= = <	on false false 7.0	volts	fail conditions exists for 1.16 seconds. monitor runs with 0.16 s rate whenever enable conditions are met.	
Engine Calibration Information Not Programed In The Control Module	P160C	Engine Calibration Information Not Programmed – GPCM: ECM monitors serial data from GPCM for P160C Error Message indicating GPCM is not programmed with injector trim values.	Glow Plug Control Module determines IQA data has <u>not</u> been programmed in the GPCM				Ignition		ON		fail conditions exists for 1.2 seconds. monitor runs with 0.2 s rate whenever enable conditions are met.	А

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshol ogic and V		Secondary Parameters		Enable Conditions	s	Time Required	MIL Illum.
Lost Communication With Glow Plug Control Module	U0106	GMLAN Communication ECM -> GPCM: ECM monitors serial data from GPCM for U0106. Error Message indicating GPCM is not receiving major GMLAN signals.	Timeout of message \$C9 or Timeout of message \$4C1 or Timeout of message \$4F1	> >	0.100 0.200 0.300	sec sec sec	Ignition 1 battery voltage at GPCM	^ ^	3.9 7.0	volts	fail conditions exists for 11 seconds. monitor runs with 10 s rate whenever enable conditions are met.	В
Intake Air (IA) Heater Feedback Circuit	P154A	Electronic GPCM circuitry determines if faults related to the IA heater feedback circuit exist.	PATH1: IAH indicates its state is AND IAH current OR PATH2: IAH indicates its state is	>	OFF 20 ON	amp	DTCs not active Path1 IAH Commanded and Battery voltage at IAH OR Path2 IAH Commanded	= ^	P0640, P154B, P154D, P154C, P166B ON 8.6	volts	fail conditions exists for 3.65 seconds. monitor runs with 0.65 s rate whenever enable conditions are met.	В
Intake Air (IA) Heater voltage Signal Circuit	P154B	Electronic GPCM circuitry determines if faults related to the voltage level present at the IA heater exist.	PATH1: voltage signal line IAH Battery voltage OR PATH2: IAH Battery voltage AND GPCM IGN voltage AND GPCM Battery voltage IAH Battery voltage	< >	1.5 6.9 6.9 16.0 9.5	volt volt volt volt volt	Path 1: IAH Commanded Path 2: DTCs not active IAH Commanded	11	OFF for more then 65 msec P064C, P154D, P154C, P166B ON		fail conditions exists for 4 seconds. monitor runs with 1 s rate whenever enable conditions are met.	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshol gic and V		Secondary Parameters		Enable Conditions	8	Time Required	MIL Illum.
Intake Air (IA) Heater Current Signal Circuit		Electronic GPCM circuitry determines if faults related to the IA heater current signal circuit or heater grid exist.	PATH1: IAH current IAH voltage signal feedback to GPCM	< >	20 0.9	amp volt	DTC's are not set IAH Commanded Battery voltage at IAH GPCM Ignition voltage or	= > >=	P154B, P154D, P0640, P0154A ON 6.9	volt volt	fail conditions exists for 8 seconds. monitor runs with 5 s rate whenever enable conditions are met.	В
			PATH2: IAH current IAH voltage signal feedback to GPCM or PATH3:IAH current	< < <	20 0.9 4.96	amp volt volt	DTC's are not set IAH Commanded Battery voltage at IAH GPCM Ignition voltage or IAH Command	= >>===================================	P154B, P154D, P0640, P0154A ON 6.9 6.9	volt volt		
			signal feedback to GPCM or PATH 4:IAH grid current IAH heater grid calculated resistance	^ ^	20 0.500	amp ohm	or DTC's are not set IAH Commanded Battery voltage at IAH	= >	off P154B, P154D, P0640, P0154A ON 8.0	volt		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	d	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Lo	ogic and V	alue	Parameters		Conditions	;	Required	Illum.
Intake Air (IA) Heater Temperature Signal Circuit	P154D	Electronic GPCM circuitry determines if faults related to the temperature feedback circuit of the IA heater exist.	PATH1: IAH temperature AND GMLAN signal "IntakeAirTemperature"	>	-20 +20	°C	IAH Commanded Battery voltage at IAH Engine General Status (engine sensor info) IntakeAirtemperature message from ECM	= > = =	P154B, P0640, P0154A, , P154C, P166B ON 11.0 valid valid	volts	fail conditions exists for 3 seconds. monitor runs with 0.65 s rate whenever enable conditions are met.	В
			or	=	Open		or					
			PATH2:IAH temperature signal feedback line or PATH3: IAH	>	4.96	volt	IAH Commanded active test function or DTC's are not set	=	OFF ON			
			temperature signal feedback line				IAH Commanded Battery voltage at IAH	= > <	,	volts volts		
			or		short to B+				P154C, P166B ON 6.0 15.0			
			PATH4; IAH temperature signal feedback line or		or short to ground		IAH		OFF			

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V		Secondary Parameters		Enable Condition	s	Time Required	MIL Illum.
			PATH5: IAH temperature sign						OFF			
Intake Air (IA) Heater Switch/Control Circuit	P0640	Electronic GPCM circuitry determines if faults related to the control circuit of the IA heater exist.	Activation Reply signal (digital response) from IAH	=	high when heartbe at signal is activat ed		DTC's are not set	=	P154A OFF		fail conditions exists for 3 seconds. monitor runs with 2 s rate whenever enable conditions are met.	В
Intake Air (IA) Heater Over Temperature		ECM monitors serial data from GPCM for P166B Error Message indicating GPCM detects IAH overtemperature	Internal Temperature of IAH module	۸	80	°C	DTC's are not set IAH Commanded engine run time Battery voltage at IAH Conditions PATH1 P16AB	= > =	P154B, P154C, P0640, P154D ON 40 sec 6.9 True	sec volt	fail conditions exists for 3 seconds. monitor runs with 0.65 s rate whenever enable conditions are met.	В
Glow Plug Control Module Not Programed	P161A	ECM monitors serial data from GPCM for P161A. GPCM is configured as service part by calibration parameter	Glow Plug Control Module determines settings of configuration parameter located in calibration data set				IGNITION	Ξ	ON		fail conditions exists for 3.2 seconds. monitor runs with 0.2 s rate whenever enable conditions are met.	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V	-	Secondary Parameters		Enable Conditions	S	Time Required	MIL Illum.
Glow Plug Module Primary Circuit	P163C	Electronic GPCM circuitry determines the voltage supply to GPCM is out of range	PATH 1: voltage supply to GPCM or PATH 2: (IGN - voltage supply to GPCM) or PATH 3: (ECM reported voltage via CAN - voltage supply to GPCM)	\ \ \ \ \ \	6.0 +/-5 +/-3	volt volt volt	GPCM Ignition voltage or GPCM voltage supply GPCM Ignition voltage or GPCM supply voltage Engine speed	> < > <	9.0 16 6.0 4.0 6 10< rpm >400	volt	fail conditions exists for 4 seconds. monitor runs with 1 s rate whenever enable conditions are met.	В
Glow Plug Module Secondary Circuit	P163D	Electronic GPCM circuitry determines serveral signal voltage levels to GPCM are out of range	Path 1: Key state (Ign 1) or Path 2: Electronic circuitry determines voltage at glow plug pin or Path 3: [GPCM ground - GP ground]	- ^ ^	OFF 6.0	volts	Path 1 glow plug activation request from ECM or Path 2 GP commanded or Path 3 GP commanded DTCs not set IAH dutycycle	= =	ON or Off or ON P0671, P0675 0 or 100		fail conditions exists for 4 seconds. monitor runs with 1 s rate whenever enable conditions are met.	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V	-	Secondary Parameters		Enable Condition	s	Time Required	MIL Illum.
Reductant Heater 1 Control Circuit	P20B9	ECM monitors serial data from GPCM for P20B9 Error Message indicating GPCM detects reductant heater not connected to GPCM or an interruption	reductant heater current and voltage at heater pin		0.2 and 3.0	amp volt	DTCs not set: reductan heater commanded: GPCM temperature GPCM battery supply voltage	= < >	P20BB ON 123 7.0	°C volt	fail conditions exists for 3.94 seconds. monitor runs with 3.44 s rate whenever enable conditions are met.	А
Reductant Heater 1 Control Circuit Low voltage	P20BB	ECM monitors serial data from GPCM for P20BB Error Message indicating GPCM detects reductant heater output shorted to ground or an overload condition	Path 1: Reductant Heater Plug Current or Path 2: load at output (detected by hardware) Path 3: hardware over current Path 4: hardware over temperature condition	<	21 or 0.047 27 175	amp ohm amp °C	reductan heater commanded: GPCM temperature GPCM supply voltage KL30 or reductan heater commanded: GPCM temperature GPCM supply voltage KL30	=	ON 123 7.0 or ON 123 7.0		fail conditions exists for 1.5 seconds. monitor runs with 1 s rate whenever enable conditions are met.	A
Reductant Heater 1 Control Circuit High voltage	P20BC	ECM monitors serial data from GPCM for P20BC Error Message indicating GPCM detects reductant heater to be shorted to battery	hardware (power stage) determines voltage at reductant heater output pin		V _{batt} - 0.8	volt	reductan heater commanded:	Ξ	OFF		fail conditions exists for 2.5 seconds. monitor runs with 2 s rate whenever enable conditions are met.	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshol ogic and V	-	Secondary Parameters		Enable Condition	S	Time Required	MIL Illum.
Reductant Heater 2 Control Circuit	P20BD	ECM monitors serial data from GPCM for P20BD Error Message indicating GPCM detects reductant heater not connected to GPCM or an interruption	reductant heater current and voltage at heater pin		3.0	amp volt	DTCs not set: reductan heater commanded: GPCM temperature GPCM battery supply voltage	= < >	P20BF ON 123 7.0	°C volt	fail conditions exists for 3.94 seconds. monitor runs with 3.44 s rate whenever enable conditions are met.	А
Reductant Heater 2 Control Circuit Low voltage	P20BF	ECM monitors serial data from GPCM for P20BF Error Message indicating GPCM detects reductant heater output shorted to ground or an overload condition	Path 1: Reductant Heater Plug Current or Path 2: load at output (detected by hardware) Path 3: hardware over current Path 4: hardware condition	<	21 or 0.047 27 175	amp ohm amp °C	reductan heater commanded: GPCM temperature GPCM supply voltage KL30 or reductan heater commanded: GPCM temperature GPCM supply voltage KL30	=	ON 123 7.0 or ON 123 7.0		fail conditions exists for 1.5 seconds. monitor runs with 1 s rate whenever enable conditions are met.	A
Reductant Heater 2 Control Circuit High voltage	P20C0	ECM monitors serial data from GPCM for P20C0 Error Message indicating GPCM detects reductant heater to be shorted to battery	hardware (power stage) determines voltage at reductant heater output pin		V _{batt} - 0.8	volts	reductan heater commanded:	Ξ	OFF		fail conditions exists for 2.5 seconds. monitor runs with 2 s rate whenever enable conditions are met.	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V	-	Secondary Parameters		Enable Condition	S	Time Required	MIL Illum.
Reductant Heater 3 Control Circuit	P20C1	ECM monitors serial data from GPCM for P20C1 Error Message indicating GPCM detects reductant heater not connected to GPCM or an interruption	reductant heater current and voltage at heater pin		0.2 and 3.0	amp volt	DTCs not set: reductan heater commanded: GPCM temperature GPCM battery supply voltage	= < >	P20C3 ON 123 7.0	°C volt	fail conditions exists for 3.94 seconds. monitor runs with 3.44 s rate whenever enable conditions are met.	А
Reductant Heater 3 Control Circuit Low voltage	P20C3	ECM monitors serial data from GPCM for P20C3 Error Message indicating GPCM detects reductant heater output shorted to ground or an overload condition	Path 1: Reductant Heater Plug Current or Path 2: load at output (detected by hardware) Path 3: hardware over current Path 4: hardware over temperature condition	<	21 or 0.047 27 175	amp ohm amp °C	reductan heater commanded: GPCM temperature GPCM supply voltage KL30 or reductan heater commanded: GPCM temperature GPCM supply voltage KL30	=	ON 123 7.0 or ON 123 7.0	°C volt volt or °C volt	fail conditions exists for 1.5 seconds. monitor runs with 1 s rate whenever enable conditions are met.	A
Reductant Heater 3 Control Circuit High voltage	P20C4	ECM monitors serial data from GPCM for P20C4 Error Message indicating GPCM detects reductant heater to be shorted to battery	hardware (power stage) determines voltage at reductant heater output pin		V _{batt} - 0.8	volts	reductan heater commanded:	Ξ	OFF		fail conditions exists for 2.5 seconds. monitor runs with 2 s rate whenever enable conditions are met.	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V		Secondary Parameters		Enable Conditions	Time Required	MIL Illum.
Nox Sensor	P220A	ECM monitors serial	PATH 1:GPCM	LC	gic and V	aiue	status DC/DC booster	=	OFF,	fail conditions exists	B B
Supply voltage Circuit Bank 1 Sensor 1		data from GPCM for P220A Error Message indicating GPCM detects DC/DC booster	Electronic circuitry determines voltage at DC/DC booster output pin	>	5.0	volt	or		power up proced ure has started	for 5.5 seconds. monitor runs with 5 s rate whenever enable conditions are met.	
		output shorted to					OI		after	are met.	
		ground or shorted to battery	or	>	5.0	amp	status DC/DC booster	=	reset		
			PATH 2: DC/DC booster output current duration	>	0.010	sec	or		ON		
			or	>	37.5 0.0000 20	amp sec	status Dc/DC booster	=			
			PATH 3: DC/DC booster output current duration						ON		
Nox Sensor Supply voltage Circuit Bank 1 Sensor 2	P220B	ECM monitors serial data from GPCM for P220B Error Message indicating GPCM detects DC/DC booster output shorted to ground or shorted to battery	PATH 1:Electronic circuitry determines voltage at DC/DC booster output pin or PATH 2: DC/DC booster output current duration	^ ^ ^	5.0 5.0 0.010	volt amp sec	status DC/DC booster or status DC/DC booster or	=	OFF, power up proced ure has started after reset or	fail conditions exists for 5.5 seconds. monitor runs with 5 s rate whenever enable conditions are met.	В
			or PATH 3: DC/DC booster output current duration	>	37.5 0.0000 20	amp sec	status Dc/DC booster	=	or ON		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol	-	Secondary		Enable		Time	MIL
System	Code	Description	Criteria		gic and V		Parameters		Conditions		Required	Illum.
Glow Plug Control Module Temperature Sensor Circuit Low	P16AD	ECM monitors serial data from GPCM for P16AD Error Message	PATH 1: GPCM temperature sensor voltage	<	0.210	volts	Engine Off Timer (GMLAN) and Intake Air Temperature (GMLAN)	>= >=	28800 -7	sec °C	fail conditions exists for 1.81 seconds. monitor runs with 1.31 s rate	В
voltage		indicating GPCM detects GPCM temperature sensore voltage out of range low					or Engine Coolant Temperature (GMLAN) and Intake Air Temperature (GMLAN)	> >	70 -10	°C °C	whenever enable conditions are met.	
			PATH 2: GPCM temperature sensor voltage	<	0.615	volts	(GIVILAIV)	< <	28800 -7 60	sec °C		
							(Engine Off Timer (GMLAN) or Intake Air Temperature (GMLAN)) and (Engine Coolant Temperature (GMLAN) or In	<= <=	-10	°°°		
Glow Plug Control Module Temperature Sensor Circuit High voltage	P16AE	ECM monitors serial data from GPCM for P16AE Error Message indicating GPCM detects GPCM temperature sensore voltage our of range high	GPCM temperature sensor voltage	>	4,94	volts	Engine Off Timer (GMLAN) and Intake Air Temperature (GMLAN) or Engine Coolant Temperature (GMLAN) and Intake Air Temperature (GMLAN)	>= >= >= >	28800 -7 70 -10	sec °C °C °C	fail conditions exists for 1.81 seconds. monitor runs with 1.31 s rate whenever enable conditions are met.	В

	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Lo	Threshologic and V	-	Secondary Parameters		Enable Condition	S	Time Required	MIL Illum.
Glow Plug Control P Module Temperature- Intake Air Heater Temperature Not Plausible		ECM monitors serial data from GPCM for P16A8 Error Message indicating GPCM detects GPCM temperature and IAH temperature are not plausible	Tenperature difference between internal temperature of GPCM and internal temperature of IAH module	>	absolut e 22	°C	Engine Off Timer (GMLAN) and Intake Air Temperature (GMLAN) and IAH Battery voltage and IAH PWM and DTC P154D	>= > = =	28800 -7 10,5 100 not set	volts %	fail conditions exists for 2.5 seconds. monitor runs with 2 s rate whenever enable conditions are met.	В
Intake Air Heater Temperature Sensor Circuit Low voltage		ECM monitors serial data from GPCM for P16AA Error Message indicating GPCM detects IAH temperature sensore voltage out of range low	IAH temperature sensor voltage	V	thresho ld selecte d by look-up table refer to table 97 in "Calibr ation Look- Up Tables"	volts	Engine Off Timer (GMLAN) and Intake Air Temperature (GMLAN) and IAH Battery voltage and IAH PWM and DTC P154D or IAH Run Time and IAH PWM Intake Air Temperature (GMLAN) IAH Battery voltage and DTC P154D or Intake Air Temperature (GMLAN)	\" \ \	28800 -7 11 100 not set 120 100 -35 11 not set 25 11 100 not set	volts %	fail conditions exists for 1.81 seconds. monitor runs with 1.31 s rate whenever enable conditions are met.	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshol		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		ogic and V		Parameters		Condition		Required	Illum.
Intake Air Heater Temperature Sensor Circuit	P16AB	ECM monitors serial data from GPCM for P16AB	PATH1: IAH temperature sensor voltage	>	IAH Battery voltage *	volts	Engine Off Timer (GMLAN) and Intake Air Temperature	>= >=	28800 -7	°C	fail conditions exists for 1.155 seconds. monitor runs with	В
High voltage		Error Message indicating GPCM detects IAH temperature sensore voltage out of range	voltage		158/512		(GMLAN) and DTC P154D	=	not set		0.655 s rate whenever enable conditions are met.	
		high					IAH Run Time and IAH PWM and	> >	120 90	sec %		
							Intake Air Temperature (GMLAN) and	> =	-35 not set	°C		
							DTC P154D or			0.0		
						volts	Intake Air Temperature (GMLAN) and	>	25 not set	°C		
			PATH2: IAH temperature sensor voltage	>	IAH Battery voltage* 146/512		DTC P154D					
					140/312		(Engine Off Timer (GMLAN) or	< <	28800 -7	sec °C		
							Intake Air Te	< < <	120 90 -35	sec % °C		
								< >	60 40	°C sec		
								=	not set			
I								I				

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
Cold Start Emission Reduction Control System	P1400	Detects problems resulting in improper delivery of fuel for catalyst light off and after treatment system preparation	Path 1: Pilot Injection 1 is prohibited due to exceeding the allowed number of injections (see general description for details)		engine operating mode	= exhaust - warm-up	fail conditions exists for 20 revs test performed continuously 0.01 s rate	В
			or		which means: Cold Start Injection Monitoring and	= ENABLED -		
			Path 2:		engine operating mode state transition and	= FALSE -		
			Pilot Injection 1 is prohibited due to collision (overlap) with Main	= TRUE -	engine coolant temperature	> 16.00 °C		
			Injection and Pilot Injection 2 (see general description for details)		and engine coolant temperature	< 71.00 °C		
			or					
			Path 3: Injector circuit or activation errors (setpoint deviation) occurred when the injector was being energized for Pilot Injection 1 (see general description for details)	= TRUE -				
			or					
			Path 4: Pilot Injection 2 is prohibited due to exceeding the allowed number of injections (see general description for details)	= TRUE -				
			or					

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Jystein	Code	Description	Path 5: Pilot Injection 2 is prohibited due to collision (overlap) with Pilot Injection 1 (see general description for details) or	= TRUE -	r arameters	Continuons	Required	mum.
			Path 6: Injector circuit or activation errors (setpoint deviation) occurred when the injector was being energized for Pilot Injection 2 (see general description for details) or	= TRUE -				
			Path 7: Injector circuit or activation errors (setpoint deviation) occurred when the injector was being energized for Main Injection (see general description for details) or	= TRUE -				
			Path 8: Post Injection 2 is prohibited due to exceeding the allowed number of injections (see general description for details) or	= TRUE -				

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
			Path 9: Post Injection 2 is prohibited due to collision (overlap) with Main Injection and Post Injection 1 (see general description for details) or	= TRUE -				
			Path 10: Injector circuit or activation errors (setpoint deviation) occurred when the injector was being energized for Post Injection 2 (see general description for details) or	= TRUE -				
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 2 Low Voltage	P1411	Diagnoses the EGR Cooler Bypass high side driver circuit for circuit faults.	Voltage low during driver on state (indicates short to ground)	= Short to ground: ≤ 0.5 Ω impedance between signal and controller ground	(fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В
					battery voltage for time and battery voltage for time	> 11 V > 3 sec < 655.34 V > 3 sec		

-	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System (Code	Description	Criteria	Logic and Value	Parameters .	Conditions	Required	Illum.
					and starter is active cranking for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	= FALSE - > 3 sec = ACTIVE - = see sheet - enable tables		
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 2 High Voltage		Diagnoses the EGR Cooler Bypass high side driver circuit for circuit faults.	Voltage high during driver off state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedance between signal and controller power	battery voltage for time and battery voltage for time) and starter is active cranking for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	> 11 V > 3 sec < 655.34 V > 3 sec = FALSE - > 3 sec = ACTIVE - = see sheet - enable tables	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters		Enable onditions		Time Required	MIL Illum.
					_	>		V sec V sec		
					starter is active cranking for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	> = /	3 ACTIVE see sheet enable tables	sec		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Current Performance	P1414	-	Voltage high during driver	= Open Circuit: ≥ 200 K Ω impedance between ECU pin and load signal and controller ground	battery voltage for time and battery voltage for time) and starter is active cranking for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	> 11 V > 3 sec < 655.34 V > 3 sec = FALSE - > 3 sec = ACTIVE - = see sheet - enable tables	fail conditions exists for 2 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions		Required	Illum.
PTO Engine Speed Request Signal Message Counter Incorrect	P1598	If the number of communication errors in a calibrated number of frames exceeds a threshold a permanent error is detected	Number of errors in window	>=	4	counts	Number of frames received	> =	10	cou nts	fail conditions exists for 0.1 s monitor runs once per trip with 0.1 s rate whenever enable conditions are	Special C
							Can Bus Initialized consisting of: ignition on for time battery voltage battery voltage	= > <	TRUE 3 9.8 16	sec V V	met	
Secondary Fuel Sensor Performance	P2066	Detects an error in the secondary fuel tank sensor performance by comparing the decrease of the fuel level for a certain driven mileage to	(a) - (b)	<	100	miles	Engine Running (see parameter definition)	=	TRUE	-	fail conditions exists for 0.02s monitor runs 0.02 s rate whenever enable	В
		a threshold.	with (a) total vehicle distance	=	measured parameter	-	for time	>=	60	sec	conditions are met	
			and with (b) change in mileage	=	measured parameter	-	and diagnosis tester connected	=	FALSE	-		
			and (c) - (d) with	<	2.64	%	and fuel transfer pump active means	=	FALSE	-		

(c) maximum volume of fuel reached in secondary tank during driving cycle and with (d) minimum volume of fuel reached in secondary tank during driving cycle and filtered fuel volume in secondary tank during driving cycle and filtered fuel volume in secondary tank > 0 % filtered fuel volume in secondary tank or filtered fuel volume in secondary tank or filtered fuel volume in secondary tank or time	Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
tables	Component / System		Monitor Strategy Description	Criteria (c) maximum volume of fuel reached in secondary tank during driving cycle and with (d) minimum volume of fuel reached in secondary tank during driving cycle and filtered fuel volume in	Logic and Value = measured - parameter = measured - parameter > 0 %	(((filtered fuel volume in primary tank or filtered fuel volume in secondary tank for time and cumulative transfer pump on time in current ignition cycle) and fuel level zone 1 means (filtered fuel volume in primary tank and filtered fuel volume in secondary tank) and basic enable conditions met: and NO Pending or Confirmed	Conditions > 88.80 % < 6.61	Time Required	

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	- 14	Threshol ogic and V		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Fuel Level Sensor 2 Circuit Low	P2067	Detects low voltage readings in the fuel level sensor circuit, indicating an OOR low condition on the fuel level sensor circuit	voltage of fuel level sensor 2 same as fuel level	>	100	%	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables		fail conditions exists for 24 s test performed continuously 0.1 s rate	В
Fuel Level Sensor 2 Circuit High	P2068	Detects high voltage readings in the fuel level sensor circuit, indicating an OOR high condition on the fuel level sensor circuit	voltage of fuel level sensor 2 same as fuel level	>	0	V %	ignition on and basic enable conditions met:	=	TRUE see sheet enable tables		fail conditions exists for 24 s test performed continuously 0.1 s rate	В
Exhaust Gas (EGR) Cooler Performance	P2457	Performs a check of the EGR cooler performance by monitoring the EGR efficiency and comparing it to a threshold value	EGR cooler efficiency	<	0.65		(engine speed and engine speed) and	>= <=		pm pm	fail conditions exists for 0.1 s monitor runs with 0.1 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	-	Conditions	;	Required	Illum.
					(injection quantity	>=	20	mm^ 3/re v		
					and injection quantity	<=	240	mm^ 3/re v		
) and (
					recirculated exhaust-gas mass flow downstream of the EGR cooler	>=	16.67	g/se c		
					and recirculated exhaust-gas mass flow downstream of the EGR cooler	<=	40.27	g/se c		
) and EGR controller is active and DPF is not in regeneration mode	=	TRUE	-		
					and (
					engine temperature and	>=	69.96	°C		
					engine temperature) and	<=	122.96	°C		
					(actual valve position of exhaust-gas recirculation	>=	9.997559	%		
) and					
					(control value provided for EGR cooling bypass	<=	5.004883	%		
					and ambient pressure and	>=	74.8	kPa		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System	Code	Description	Criteria	Logic and value	rarameters (Conditions	Requirea	IIIum.
					ambient temperature and ambient temperature	>= -7.04 °C <= 3003.56 °C		
) and diagnostic performed in current dc and NO Pending or Confirmed DTCs:	= FALSE - = see sheet - inhibit		
) for time and basic enable conditions met:	tables >= 120 sec = see sheet - enable tables		
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit	P245A	Diagnoses the EGR Cooler Bypass low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit:≥ 200 K Ω impedance between	battery voltage	> 11 V	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever	В
		The faults of the output circuit, that are detected with this diagnosis, are an		ECU pin and load	for time and	> 3 sec	enable conditions are met	
		open circuit or an over temperature of the integrated circuit within the ECM.			starter is active cranking for time and	= FALSE - > 3 sec		

	ault	Monitor Strategy	Primary Malfunction	Threshold	Secondary		Enable Conditions		Time	MIL
System C	code	Description	Criteria	Logic and Value	Parameters EGR Cooling Bypass Solenoid Control Circuit and for time and (open load diagnostics is triggered after offset learning of valve is completed or NO Pending or Confirmed DTCs) and basic enable conditions met:	= =	see sheet inhibit tables see sheet enable tables	sec	Required	Illum.
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 1 Low Voltage			Voltage low during driver off state (indicates short-to- ground)	= Short to ground: ≤ 0.5 Ω impedance between signal and controller ground	battery voltage for time and battery voltage for time)	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	11 3 655.34 3	V sec V sec	fail conditions exists for 3 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
					for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	> 3 sec = ACTIVE - = see sheet - enable tables		
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 1 High Voltage		Diagnoses the EGR Cooler Bypass low side driver circuit for circuit faults.	Voltage high during driver on state (indicates short to power)	= Short to power: ≤ 0.5 Ω impedance between signal and controller power	battery voltage for time and battery voltage for time) and starter is active cranking for time and EGR Cooling Bypass Solenoid Control Circuit and basic enable conditions met:	> 11 V > 3 sec < 655.34 V > 3 sec = FALSE - > 3 sec = ACTIVE - = see sheet - enable tables		В

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria		Thresho		Secondary Parameters		Enable Conditions		Time Required	MIL Illum.
Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Current Performance	P2493	Detects a controller deviation in EGR cooling bypass valve. Actual deviation readings are compared to a threshold.	controller deviation of EGR cooling bypass valve actuator calculated out of difference between desired and actual value or controller deviation of EGR cooling bypass valve actuator calculated out of difference between desired and actual value	\ \ \	10.00 -10.00	% %	engine coolant temperature and offset learning of EGR cooling bypass valve actuator active and offset learning in the previous driving cycle was complete and engine speed and EGR Cooler Bypass Valve Actuator and basic enable conditions met: and NO Pending or Confirmed DTCs:	> = =	-7.04 FALSE TRUE 100 ACTIVE see sheet enable tables see sheet inhibit tables	°C - rpm -	fail conditions exists for 8 s monitor runs with 0.02 s rate whenever enable conditions are met	B B
EGR Cooling Bypass Position Sensor Circuit Low Voltage	P2494	Detects low voltage readings on the EGR cooling bypass position circuit, indicating an OOR low condition on the EGR position circuit	voltage of EGR cooling bypass actuator position sensor same as EGR cooling bypass actuator position	<	0.25	V %	ignition on and NO Pending or Confirmed DTCs:	=	TRUE see sheet inhibit tables		fail conditions exists for 5 s test performed continuously 0.01 s rate when enable conditions are met	A

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and basic enable conditions met:	= see sheet - enable tables		
EGR Cooling Bypass Position Sensor Circuit High Voltage	P2495	Detects high voltage readings on the EGR cooling bypass position circuit, indicating an OOR high condition on the EGR position circuit	voltage of EGR cooling bypass actuator position sensor same as EGR cooling bypass actuator position	> 114 %	ignition on and NO Pending or Confirmed DTCs: and basic enable conditions met:	= TRUE - = see sheet - inhibit tables = see sheet - enable tables	fail conditions exists for 5 s test performed continuously 0.01 s rate when enable conditions are met	A
EGR Cooling Bypass Performance	P24C4	Detects adaptation values of EGR cooling bypass valve that are not plausible. Compares the difference between the maximum and minimum adaptation values to a threshold.	Path 1: difference between the max and min EGR cooler bypass valve offset values	> 50 %	(fail conditions exists for 0.5 s monitor runs with 0.01 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold		Secondary		Enable		Time	MII
System	Code	Description	Criteria	Logic and Va	lue	Parameters		Conditions		Required	Illu
			or			active cleaning mode of EGR cooler bypass valve - no movement in EGR cooling bypass valve	=	FALSE	-		
			Path 2: learned offset value for EGR cooler bypass valve in the present driving cycle	16.003418	%	and engine post drive/ afterun	=	TRUE	-		
			or learned offset value for EGR cooler bypass valve in the present driving cycle	-16.00342	%	and (
			or Path 3:			battery voltage and	>=	10	V		
			mean value for EGR cooling bypass valve offset learned at the open end during the current driving cycle over multiple open- close cycles or	13.000488	%	battery voltage	<=	30	V		
			mean value for EGR cooling bypass valve offset learned at the open end during the current driving cycle over multiple open- close cycles	-16.00342	%	and					
						engine coolant temperature and	>=	5.06	°C		
						engine coolant temperature)	<=	123.06	°C		
) or offset learning active or	=	TRUE	-		
						diagnosis tester present) and	=	FALSE	-		
						completion of offset learning	=	TRUE	-		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and basic enable conditions met: and NO Pending or Confirmed DTCs:	= see sheet - enable tables = see sheet - inhibit tables		
		Detects a jammed EGR cooling bypass valve during opening or closing the valve.	Path 1:		EGR cooler bypass valve is opening	= TRUE -		
			EGR cooler bypass valve stuck during opening which means	= TRUE -	or EGR cooler bypass valve is closing and	= TRUE -		
			(a) + (b) with (a) position of the EGR cooling bypass valve	>= 75.012207 % = measured - parameter	((active cleaning mode of EGR cooler bypass valve - no movement in EGR cooling bypass valve	= FALSE -		
			and with (b) learned offset value of EGR cooler bypass valve in the previous driving cycle		and engine post drive/ afterun	= TRUE -		
			and (a) - (b) with (a) position of the EGR cooling bypass valve	>= 0.9887695 % = measured - parameter	and (battery voltage and	>= 10 V		
			and with		battery voltage	<= 30 V		

Component /	Fault	Monitor Strategy	Primary Malfunction		Threshold		Secondary		Enable		Time	MIL
System	Code	Description	Criteria		Logic and Va		Parameters		Conditions		Required	Illum.
			(b) position of the EGR cooling bypass valve of the previous process cycle	=	calculated parameter	-)					
)		_		and					
			for time	>	5	sec	(engine coolant temperature	>=	5.06	°C		
			or				and					
			Path 2:				engine coolant temperature	<=	123.06	°C		
			EGR cooler bypass valve stuck during closing which means	=	TRUE	-)					
			(position of the EGR cooling bypass valve with	<	(a) * (b)	-	or offset learning active or	=	TRUE	-		
			(a) reference position of the EGR cooling bypass valve in open position	=	calculated parameter	-	diagnosis tester present	=	FALSE	-		
			and with (b) calibrateable factor of the EGR cooling bypass valve close position	=	0.1500244) and					
			and				completion of offset learning	=	TRUE	-		
			(a) - (b)	<=	0.0244141	%	and	_	ann chact			
			with				basic enable conditions met:	=	see sheet enable tables	-		
			(a) position of the EGR cooling bypass valve	=	measured parameter	-	and					
			and with				NO Pending or Confirmed DTCs:	=	see sheet inhibit	-		
			(b) position of the EGR cooling bypass valve of the previous process cycle	=	calculated parameter	-			tables			

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			for time	> 5 sec				
Fuel Transfer Pump Relay Control Circuit	P2632	Diagnoses the Fuel Transfer Pump low side driver circuit for circuit faults.	Voltage low during driver off state (indicates open circuit)	= Open - Circuit: ≥ 200 K Ω impedance between ECU pin and load	ignition on and basic enable conditions met:	= TRUE - = see sheet - enable	fail conditions exists for 3 s monitor runs 0.02 s rate whenever enable conditions are met	В
Fuel Transfer	P2633	Diagnoses the Fuel	Voltage low during driver off	= Short to -	ignition on	tables = TRUE -	fail conditions	В
Pump Relay Control Circuit Low	F2033	Transfer Pump low side driver circuit faults.	state (indicates short-to- ground)	ground: ≤ 0.5 Ω impedance between signal and controller ground	ignition on	- IRUE -	exists for 3 s monitor runs 0.02 s rate whenever enable conditions are met	Б
					and basic enable conditions met:	= see sheet - enable tables		

Component / System	Fault Code	Monitor Strategy Description	Primary Malfunction Criteria	Threshold Logic and Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Transfer	P2634	Diagnoses the Fuel	Voltogo biek during driver	= Short to -	ing it in a su	= TRUE -	fail conditions	В
Pump Relay Control Circuit High	F2034	Transfer Pump low side driver circuit faults.	Voltage high during driver on state (indicates short to power)	power: ≤ 0.5 Ω impedance between signal and controller power	and basic enable conditions met:	= see sheet - enable tables	exists for 3 s monitor runs 0.02 s rate whenever enable conditions are met	D
Fuel Transfer Pump Performance	P2636	Detects an error in the fuel tank transfer pump performance by comparing the decrease of the fuel level in both tanks.	Path 1: change in fuel volume in primary tank and change in fuel volume in secondary tank or Path 2: change in fuel volume in primary tank	< 0.90 % < 0.53 % < 0.90 %	parameter definition) and fuel transfer pump active means (= TRUE - = TRUE -	fail conditions exists for 140s monitor runs 0.02 s rate whenever enable conditions are met	В

Component /	Fault	Monitor Strategy	Primary Malfunction		Thresho	old	Secondary		Enable		Time	MIL
System	Code	Description	Criteria	L	ogic and	Value	Parameters		Conditions		Required	Illum.
			and change in fuel volume in secondary tank or	>=	0.53	%	filtered fuel volume in primary tank or filtered fuel volume in secondary tank	^	71.94 6.61	%		
			Path 3: change in fuel volume in primary tank and change in fuel volume in secondary tank	>=	0.90	%	and time between activations of transfer pump and	>	5	sec		
							fuel level zone 5 means (filtered fuel volume in primary tank and filtered fuel volume in secondary tank)) vehicle speed and diagnosis tester and	< > = =	99.93 1.32 0 FALSE	% % mph -		
							NO Pending or Confirmed DTCs:) for time and basic enable conditions met:	> =	see sheet inhibit tables 20 see sheet enable tables	sec		

Component /	Fault	Monitor Strategy	Primary Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Logic and Value	Parameters	Conditions	Required	Illum.
4WD Switch Circuit	P2771	Checks plausibility of the 4WD-Low switch with 4WD state based on 4WD state from transmission turbine speed, transmission output shaft speed, and transmission gear ratio.	Debounced value of 4WD- Lo switch	= FALSE -	Current Transmission Gear	!= Park/Neut - ral	fail conditions exists for 0.05 s test performed continuously 0.02 s rate	В
			and 4WD-Lo active based on transmission turbine speed, output shaft speed, and gear ratio	= TRUE -	and Current Transmission Gear	!= Reverse -		
					and Torque converter clutch open and	= FALSE -		
					Engine is Running and	= TRUE -		
					vehicle speed and	> 12.43 mpl	ו	
					accelerator pedal position and	< 100 %		
					accelerator pedal position and	> 10.00 %		
					engine speed and			
					engine speed and			
					basic enable conditions met: and	= see sheet - enable tables		
					NO Pending or Confirmed DTCs:	= see sheet - inhibit tables		

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
Battery Voltage		Battery Voltage Correction Factor	battery voltage correction factor = Nominal Declared Battery Voltage divided by measured battery voltage	=	13.6	V
Engine Cooling System States		Status of the Block Heater	active under following conditions (
			engine speed	>	500	rpm
			for			
			time	>	60	sec
			and (a) - (b)	>	1.8	°C
			with (a) reference temperature (engine coolant	=	measured	_
			temperature) captured during start		parameter	-
			and with (b) engine coolant temperature	=	measured	_
			(a) angina adam tamparatara		parameter	
)			
		status of Block Heater monitor time	active under following conditions			
			engine speed	>	500	rpm
			for			
			time	>	60	sec
						_
		Status of Sun Load Detection	active under following condition			
		(high thermal input from the sun	(Vehicle speed	>	14.92	mnh
		which influences system behavior)	for		14.32	mph
			time	>	300	sec
			and engine speed (see Look-Up-Table #14)	>	600 to 850	rpm
			for time	>	600	sec
	I	•	ume	-	000	300

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			and (a) - (b) with	>	4.5	°C
			(a) intake at temperature at start	=	measured parameter	-
			and with (b) minimum intake air temperature value for the comparison with the reference temperature during driving cycle)		measured parameter	-
				_	_	
		Status of Sun Load Detection time	active under following condition			
			(Vehicle speed for	>	14.92	mph
			time and	>	300	sec
			engine speed (see Look-Up-Table #14)	>	600 to 850	rpm
			for time)	>	600	sec
ECM Operating States		Engine Pre-Drive	processor operating normally ignition	=	TRUE OFF	-
			processor powerup boot initialization	=	complete	-
			or key off bookkeeping cleanup (accessory, post-wake-up, pre-sleep)	=	complete	-
					_	
		Engine Running (see Look-Up table #70)	ignition engine speed engine speed was at start	>=	ON 100 850	- rpm rpm
		Engine Post-Drive/ Afterun	processor operating normally		TRUE	-
1	I	also includes	ignition	=	OFF	-

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
		"engine stopping" during engine spin down	key off bookkeeping cleanup	=	in process	-
Engine Operating Modes	Exhaust Operating Mode focus	Normal Mode				
		Particulate Filter Regeneration Mode				
		Particulate Filter Regen Service Mode				
		Exhaust Gas Temperature (Active) Management Mode		=	Warm Up or Maintain Temperature	-
		also known as Engine Operating Mode		=	Exhaust Warm-up	
Exhaust Gas Recirculation (EGR)		Exhaust Gas Recirculation (EGR)	EGR controller is active			
(EGR)		Control is enabled	continuously with exceptions for failures detected EGR controller is active Overrun Long Idle Transmission Gear Shift Cold Start extreme temperature or pressure Critical Regeneration Modes			
			Overrun			
			Gear Shifting			
			Overlong Idle			
			permanent control deviation			
			Demand of the drift compensation			
	1		System error			

Component / System	State or Status Sub-Grouping	Description of State or Status found in 12OBDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			Error exhaust gas recirculation valve			
			Error throttle valve			
			Engine Brake Status			
			Atmospheric pressure too low			
			Battery voltage too low			
			Switch-off coordinator			
			Environmental temperature too low			
			Environmental temperature too high			
			Engine temperature too low			
			Engine temperature too high			
			Cold start			
			Injection quantity too large			
			Operating-mode coordinator			
			Rich Idle			
			External control intervention			
			Rich Idle Regen			
			Environmental Temperature too low in Regeneration			
			EGR Stroking			
			EGR controller is active in Overrun (warm exhaust system)			
			EGR controller is active in Overrun (Cold exhaust system)			
			AFS Faults			
			Request via SCR monitoring (NOx sensor plausibility check)			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Atmospheric Pressure too low in	Logic	Values	Units
			Regeneration			
			Engine Temperature too low in			
			Regeneration			
			Engine Temperature too high in			
			Regeneration			
Engine Position Management		Engine Position Sync Complete	synchronization completed consisting of:			
			crankshaft sensor pulses received			
			camshaft sensor pulse received and aligned properly			
			or sync via crank only invoked			
			then crankshaft rotations	>=	4	counts
Fuel System		Fuel System is in Fuel Shut Off	engine running	=	TRUE	
. do: eyele		also known as	required actual engine torque		1	Nm
		Decel Fuel Shut Off or Over-Run	-	-	-	-
		Status of Diesel Fuel Refill Detection	((
			Filtered total fuel volume available	>	(a) + (b)	-
			(a) Amount of fuel volume change that		25.26	%
			indicates a refueling event occurred (b) captured remaining diesel fuel volume	=	measured	-
			under the following conditions		parameter	
			(Vehicle speed	<=	1.24	mph
			time	>	4	sec
) and			
			((4.04	mah
			Vehicle speed time	<= >	1.24 30	mph sec
))			
			or			

Component /	State or Status	Description of State or Status found in 120BDG09	Defined by:	Enable	Enable Values	Enable Units
System	Sub-Grouping	Tourid In 120BDG09	at initialization of Diesel fuel level	Logic	TRUE	Offics
Idle Speed Control		Idle Speed Controller Active "normal" low idle speed governor	no overrides for: Gear-Shift Harmonization Intrusive Diagnosis Action Power Take Off or other working load handling	=	TRUE	
		Engine Idling Time Ratio	= (time accumulated at idle divided by time since engine start)	_		_
NO. O		Otatus of NO. simple for the serve				
NOx Sensor		Status of NOx signal of upstream NOx sensor	(
			following condition met for time:	>	30	sec
			Integrated heat quantity (see Look-Up- Table #1)	>=	375 to 500	kJ
			NOx status signal received via CAN message (Please see the definition)	=	TRUE	-
			for time	>	0.5	sec
			calculated lambda value based on air mass flow and injection quantity	>	0.9	-
			for time	>	0.5	sec
			engine speed	>	100	rpm
			for time NO Pending or Confirmed DTCs:	> =	20 see sheet inhibit tables	sec -
))			
		Upstream Nox Sensor Signal Ready	following condition met for time:	>	30	sec
		opsusam Nox Sensor Signal Reduy	ionowing conducti met for time.		50	366

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
Oystem	Sub-Grouping	or Upstream Nox SensorDewpoint Reached or Lambda signal from NOx sensor ready	Integrated heat quantity (see Look-Up- Table #1)	>=	375 to 500	kJ
		Status of NOx signal of downstream NOx sensor				
			following condition met for time:	>	30	sec
			() Integrated heat quantity (see Look-Up- Table #2)	>=	0 to 350	kJ
			NOx status signal received via CAN message (Please see the definition)	=	TRUE	-
			for time	>	0.5	sec
			calculated lambda value based on air mass flow and injection quantity		0.9	-
			for time	>	0.5	sec
			engine speed		100	rpm
			for time NO Pending or Confirmed DTCs:	> =	20 see sheet inhibit tables	sec -
		Upstream Nox Sensor Signal Ready	following condition met for time:	>	30	sec
		or Upstream Nox SensorDewpoint Reached or Lambda signal from NOx sensor ready	(Integrated heat quantity (see Look-Up- Table #2)	>=	0 to 350	kJ
		Enabling Downstream NOx sensor heater diagnosis				

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
1			SCR Catalyst downstream temperature	>=	94.96	°C
			SCR Catalyst downstream temperature		3003.56	°C
			battery voltage	>=	11	V
1			battery voltage	<=	655.34	V
			and		0 to 250	l. I
			Integrated heat quantity (see Look-Up-	>=	0 to 350	kJ
			Table #2) for time	>	30	sec
			ioi tiine		30	Sec
) and			
			for time	>	1	sec
			NO Pending or Confirmed DTCs:	=	see sheet inhibit	-
			140 1 chaing of committee b 103.		tables	
					tables	
		Enabling Downstream NOx sensor				
		heater diagnosis				
			(
			SCR Catalyst upstream temperature	>=	94.96	°C
			SCR Catalyst upstream temperature	<=	3003.56	°C
			battery voltage	>=	11	V
			battery voltage	<=	655.34	V
			and		075 1- 500	1.1
			Integrated heat quantity (see Look-Up-	>=	375 to 500	kJ
			Table #1)		30	222
			for time	>	30	sec
) and			
			for time	>	1	sec
			NO Pending or Confirmed DTCs:	=	see sheet inhibit	- -
1			140 F chaing of Committee D10s.	_	tables	-
					asios	
Rail Pressure Control System						
Operating States		Rail Control at ECM Start	reset condition	=	TRUE	-
1			or			

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
	·		NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		Rail Pre-Control (Just after start)	Rail Control at ECU Start and engine speed and (rail pressure or (a) - (b) (a)Fuel Rail Pressure Setpoint (b)Maximum Rail Pressure for last 10ms		TRUE 300 15000 5000 measured paramter measured paramter	rpm kPa kPa -
		Rail Control - PCV Closed Loop Control Only PCV = Pressure Control Valve	Rail Pressure Precontrol (Just after start) and Number of Crankshaft revolutions since entering Rail Pressure Precontrol) or (state machine rail pressure control transitioning pressure control valve mode and setpoint volume flow of the metering unit out of rail pressure control (see Look-Up-Table #6) or (Fuel system pressure and high pressure pump outlet and engine status	= ^ v	TRUE 10 TRUE 600000 to 2240000	revs - mm^3/rev kPa -

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
		Rail Control - Metering Unit Closed Loop Control	state machine rail pressure control equal transitioning to metering unit pressure control mode	=	TRUE	-
			and Controller for PCV not wound-up (large corrective control)	=	TRUE	-
		Rail Control - Metering Unit + PCV Closed Loop Control	state machine rail pressure control transitioning to coupled pressure control	=	TRUE	-
		Closed Edop Control	mode (rail pressure is controlled by metering unit and pressure control valve) and			
			(a) + (b) (see Look-Up-Table #7)	<	12 to 400	mm^3/rev
			(a)Torque Generating fuel injection quantity	=	calculated parametet	-
			(b)Non-Torque generating fuel injection quantity	=	calculated parametet	-
		Switchover Between Metering Unit + PCV Closed Loop Control to Metering Unit Closed Loop Control only	(
		o.i.y	state machine rail pressure control equal to pressure control valve or			
			state machine rail pressure control transitioning pressure control valve mode)			
			and (a) + (b) (a)Torque Generating fuel injection quantity	< =	(c) + (d) calculated	- -
			(b)Non-Torque generating fuel injection quantity	=	parametet calculated parametet	-
			(c) (see Look-Up-Table #7)	=	12 to 400	mm^3/rev

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
- Jeto	Can Crouping		4.0			
			(d)	=	12	mm^3/rev
			and NO Pending or Confirmed DTCs:	=	see sheet inhibit	_
			·		tables	
			or (
			state machine rail pressure control equal to metering unit control mode			
			state machine rail pressure control equal transitioning to metering unit pressure control mode			
			and NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
			Fuel system pressure and high pressure pump outlet and	<	0	kPa
			engine status)	=	RUNNING	-
) and NO Pending or Confirmed DTCs:)	=	see sheet inhibit tables	-
					_	
		Switchover between PCV or Metering Unit closed loop control to Metering Unit + PCV Closed Loop Control	(
			state machine rail pressure control equal to pressure control valve	=	TRUE	-
			state machine rail pressure control equal coupled pressure control (rail pressure is controlled by metering unit and pressure control valve)	=	TRUE	-

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable Units
System	Sub-Grouping	found in 12OBDG09	state masking vail procesure control	Logic =	Values TRUE	
			state machine rail pressure control transitioning pressure control valve mode	_	IRUE	-
			or			
			state machine rail pressure control equal	=	TRUE	-
			transitioning to metering unit pressure			
			control mode			
			<i>)</i> and			
			and (
			ì			
			exhaust gas system regeneration mode	!=	REGEN	-
			and NO Pending or Confirmed DTCs:	=	see sheet inhibit	_
			rto i chang of committed birds.		tables	
		Switchover Between Metering Unit +				
		PCV Closed Loop Control to PCV	(
		Closed Loop Control only				
			state machine rail pressure control equals		TRUE	-
			coupled pressure control (rail pressure is			
			controlled by metering unit and pressure control valve)			
			or			
			state machine rail pressure control	=	TRUE	-
			transitioning to coupled pressure control			
			mode (rail pressure is controlled by			
			metering unit and pressure control valve)			
			and			
			(a) + (b) (see Look-Up-Table #7)	<	12 to 400	mm^3/rev
			where			
			(a)Torque Generating fuel injection quantity	=	calculated parametet	-
			(b)Non-Torque generating fuel injection	=	calculated	_
			quantity		parametet	
			, i			
Regeneration of the Diesel		Status thermal regeneration active				
Particulate Filter		Cara and man regeneration active				

Component /	State or Status	Description of State or Status	- a	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Defined by:	Logic	Values	Units
			Reduced particle mass flow in simulation by			
			thermal regeneration			
			(a) * (b) * (c)	>	0	-
			(a) Correction factor for thermal soot burn-	=	0 to 4.0	factor
			out dependent on lambda and oxygen			
			mass flow (see Look-Up-Table #4)		0.4.00=	
			(b) Effect of temperature on regenerated	=	0 to 2.97	-
			particle mass (see Look-Up-Table #5) (c) Basis value of produced soot mass flow	=	0.02 to 0.29	g/sec
			dependent on actual soot mass (see Look-	_	0.02 10 0.29	g/sec
			Up-Table #3)			
			Op Tubic #0)			
SCR System	NOx Control System	Release of dosing of the dosing				
	Reductant Dosing Strategy	strategy				
	Active State		status of SCR control state (please see the	=	Metering Control	-
			definition) Reductant dosing is released	=	TRUE	
			Deactivation of dosing to execute the NOx		FALSE	-
			Offset test (Please see the definition)	_	FALSE	-
			since start for time	>=	0.02	sec
			gradient of exhaust gas temperature	<=	300	°C/sec
			since start for time	>=	0.01	sec
			Average temperature inside the SCR	>	179.96	°C
			catalyst:			
			SCR catalyst wall temperature	>	89.96	°C
			Vehicle speed	>=	-0.62	mph
			engine speed	>	400	rpm
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
					lables	
	NOx Control System		ignition	=	on	-
	Reductant Dosing Pressure	State of Reductant Pressure Control	Dwell time in the state of standby	<	5	sec
	Control System States	System: Standby				
			NO Pending or Confirmed DTCs:	=	see sheet inhibit	-
					tables	
1						

Component / System	State or Status Sub-Grouping	Description of State or Status found in 12OBDG09	Defined by:	Enable Logic	Enable Values	Enable Units
	·	State of Reductant Pressure Control System: No Pressure control	Old SCR control state (please see the definition)	=	Stand by	-
			ignition	=	on	_
			Dwell time in the state of standby	>=	5	sec
			Dwell time in the state of no pressure	<	2	sec
			control NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		State of Dadustant Procesure Control	Old CCD control state (places are the	_	NO Proceuro	
		State of Reductant Pressure Control System: Pressure control	Old SCR control state (please see the definition)	=	NO Pressure Control	-
		System. Flessure control	ignition	=	on	
			engine speed	>	550	rpm
			Dwell time in the state of no pressure control		2	sec
			exhaust gas temperature Upstream SCR	>=	169.96	°C
			Reductant Defrost check (please see the definition) or	=	TRUE	-
			The component protection release of the heater control (please see the definition) or	=	TRUE	-
			Preliminary release of the heater control for the	=	TRUE	-
			main state machine (please see the definition)			
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		State of Reductant Pressure Control System: Refilling Reductant in pressure line (substate of Pressure control)	SCR control state (please see the definition)	=	Pressure Control	-
			Reductant filling state in the pressure line and	<	50	%
		1	Reductant Pump Module Pressure	<	200	kPa

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
) Set-point duty cycle for Reductant dosing	=	100	%
			valve		40.00	0/
			Set-point duty cycle for the Reductant Pump pressure Motor actuator	=	40.00	%
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		State of Reductant Pressure Control System: Pressure build up (substate of Pressure control)	SCR control state (please see the definition)	=	Pressure Control	-
			Reductant filling state in the pressure line	>=	50	%
			or Reductant Pump Module Pressure	>=	200	kPa
			for time)	>	0.5	sec
			Reductant Pump Module Pressure	<	350	kPa
			Set-point duty cycle for Reductant dosing valve	=	0%	%
			Set-point duty cycle for the Reductant Pump pressure Motor actuator	=	80.00	%
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		State of Reductant Pressure Control System: Ventilation (substate of Pressure control)	SCR control state (please see the definition)	=	Pressure Control	-
		,	Reductant Pump Module Pressure	<	350	kPa
			Dwell time in Pressure Build up substate		10	sec
			system pressurizes in pressure buildup and ventilation states	<	10	counts
			Set-point duty cycle for Reductant dosing valve	=	100	%
			Set-point duty cycle for the Reductant Pump pressure Motor actuator	=	80.00	%
			Dwell time in the sub state ventilation	<	0.23	sec
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
		State of Reductant Pressure Control System: Metering control (substate of Pressure control)	SCR control state (please see the definition)	=	Pressure Control	
		or ressure control)	Reductant Pump Module Pressure Set-point duty cycle for Reductant dosing valve	>= =	350 0	kPa %
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
		State of Reductant Pressure Control System: Pressure reduction	ignition	=	off	
			dwell time in the state of pressure reduction	<	5	sec
			Activation state of Reductant reverting valve power stage		On	-
			Set-point duty cycle for Reductant dosing valve		0	%
			Set-point duty cycle for the Reductant Pump pressure Motor actuator	=	15.00	%
			NO Pending or Confirmed DTCs:	=	see sheet inhibit tables	-
	SCR Engine State required for operation	SCR Engine State	Ignition on	=	TRUE	-
			engine speed	^	550	rpm
	Reductant Dosing Strategy based on DPF Fload	Status fill level decrease (please see the definition)	Particulate Filter Regeneration demand on	=	TRUE	
			or Reductant fill level of the SCR catalyst lowed to the target value under Particle filter			
			Regeneration request (a) - (b)		0	-

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			(a) Nominal value of Reductant fill level in			
			the catalyst			
			(b) Estimated current Reductant load		400	6(
			(c) Reductant Dosing quantity limitation	=	100	factor
			or			
			or SCR catalyst temperature too high to			
			convert Reductant under Particle filter			
			Regeneration request			
			Average temperature inside the SCR	>	999.96	°C
			catalyst:		000.00	O
			outu., ott			
	Reductant Heater and Defrost					
	System Control States and					
	Status					
	Otatas					
		Reductant Defrost check	status of reductant tank heater temperature	=	TRUE	_
		reductant Benest check	(please see the definition)	_	INOL	
			State of the defrosting check of pressure	=	TRUE	_
			line (please see the definition)			
			State of the defrosting check of supply	=	TRUE	_
			module (please see the definition)			
			(
			duration, for which the conditions for a	<=	1200	sec
			hydraulic release reset of pressure line			
			heater circuit are satisfied		4.04	80
			ambient temperature	>	-4.04 FALSE	°C
			Release heater pressure line and	=	FALSE	-
			duration, for which the conditions for a	<=	1200	sec
			hydraulic release reset of supply module	,_	1200	300
			heater circuit are satisfied			
			ambient temperature	>	-4.04	°C
			Release heater supply module		FALSE	-
)		-	
		Status of reductant tank heater	status of reductant tank heater			
	I	temperature	temperature (please see the definition)			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			Reductant tank heat temperature at	>	-0.04	°C
			Standby state			
			or			
			Engine off Time	<	2147483647	sec
			Reductant tank heat temperature at	>	-9.04	°C
			Standby state			
		State of the defrosting check of	State of the defrosting check of pressure			
		pressure line	line (please see the definition)			
			(۴			
			time since pressure line heating on under	>=	0 to 3276.7	sec
			pressure line defrost mode			
			or			
			status of SCR control state (please see the	=	No Pressure	-
			definition)		Control	
			Pressure line defrost timer	=	0	sec
			or			
			ignition	=	on	sec
			engine speed	>	550	rpm
			Pressure line defrost check in last driving	=	TRUE	_
			cycle	_	INOL	
			status of SCR control state (please see the	=	No Pressure	_
			definition)		Control	
			Engine off Time	>	0	sec
			NO Pending or Confirmed DTCs:	=	TRUE	-
		Ctate of the defracting check of	Ctate of the defination shoots of according			
		State of the defrosting check of supply module	State of the defrosting check of supply			
		supply module	module (please see the definition) time since supply module heating on under	\-	0 to 3276.7	800
			supply module defrost mode	>=	0 10 3270.7	sec
			or			
			status of SCR control state (please see the	=	No Pressure	_
			definition)		Control	
			Supply module defrost timer	=	0	sec
			or			
			ignition	=	on	sec
			engine speed	>	550	rpm
1						

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			Pressure line defrost check in last driving	=	TRUE	-
			cycle status of SCR control state (please see the	=	No Pressure	
			definition)	_	Control	-
			Engine off Time	<	0	sec
			NO Pending or Confirmed DTCs:	=	TRUE	-
		The component protection release of	Current time for heating / not heating of	>=	0 to 299	sec
		the heater control	heater circuit 1 (tank)			
			Reductant Defrost check (please see the	=	FALSE	-
			definition)			
		Preliminary release of the heater	Preliminary release of the heater control for			
		control for the main state machine	the			
			main state machine (please see the			
			definition)			
			(
			Current time for heating / not heating of	>=	0 to 3276	sec
			heater circuit 1 (tank)		EALOE	
			status of reductant tank heater defrost status of reductant tank heater temperature		FALSE FALSE	-
			(please see the definition)	_	FALSE	-
			State of the defrosting check of pressure	=	TRUE	_
			line (please see the definition)			
			State of the defrosting check of supply	=	TRUE	-
			module (please see the definition)			
)			
			or			
			(
			ignition	=	on	sec
			engine speed	>	550	rpm
			Engine off Time State of the defrosting check of pressure		0 TRUE	sec -
			line (please see the definition)	_	INOL	-
			State of the defrosting check of supply	=	TRUE	_
			module (please see the definition)			
			and			
			if the following conditions were met in	=	TRUE	-
			previous driving cycle			
1			(

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
Gyotolii	oub Grouping	Touris in 1200000	ignition engine speed Engine off Time State of the defrosting check of pressure line (please see the definition) State of the defrosting check of supply module (please see the definition)))	= > <=	on 550 0 TRUE TRUE	sec rpm sec -
		Release of tank heater circuit	(Requested defrosting time for Reductant tank heater (see Look-Up-Table #16) or Requested heating time for Reductant tank	>=	0 to 14400 0 to 3277	sec
			heater (see Look-Up-Table #17)) or ((Requested defrosting time for Reductant tank heater (see Look-Up-Table #16)	>=	0 to 14400	sec
			or Requested heating time for Reductant tank heater (see Look-Up-Table #17)) and (0 to 3277	sec
			Requested defrosting time for pressure line heater (see Look-Up-Table #18) or Requested heating time for pressure line heater (see Look-Up-Table #20)	>=	0 to 3276.7 0 to 3276.7	sec sec
			or ((Requested defrosting time for Reductant tank heater (see Look-Up-Table #16) or Requested heating time for Reductant tank	>=	0 to 14400 0 to 3277	sec sec
			heater (see Look-Up-Table #17)	. –	0 10 0211	550

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
Oystem	oub-orouping	Iodila III 120BB003	and	Logic	Values	• · · · · ·
			(Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec
			or Requested heating time for supply module heater (see Look-Up-Table #21)))	>=	0 to 3276.7	sec
			or ((Requested defrosting time for Reductant tank heater (see Look-Up-Table #16)	>=	0 to 14400	sec
			OF Requested heating time for Reductant tank heater (see Look-Up-Table #17)) and	>=	0 to 3277	sec
			(Requested defrosting time for pressure line heater (see Look-Up-Table #18) or	>=	0 to 3276.7	sec
			Requested heating time for pressure line heater (see Look-Up-Table #20)) and	>=	0 to 3276.7	sec
			Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec
			Requested heating time for supply module heater (see Look-Up-Table #21)))	>=	0 to 3276.7	sec
			and NO Pending or Confirmed DTCs:	=	TRUE	-
		Release of pressure line heater circuit	(Requested defrosting time for pressure line heater (see Look-Up-Table #18) or	>=	0 to 3276.7	sec

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Requested heating time for pressure line	Logic >=	Values 0 to 3276.7	Units sec
			heater (see Look-Up-Table #20)	/-	0 10 3270.7	Sec
			·			
			or			
			((
			Requested defrosting time for pressure line	>=	0 to 3276.7	sec
			heater (see Look-Up-Table #18)			
			Requested heating time for pressure line	>=	0 to 3276.7	sec
			heater (see Look-Up-Table #20)			
)			
			and (
			Requested defrosting time for supply	>=	0 to 3276.7	sec
			module heater (see Look-Up-Table #19)			
			or Requested heating time for supply module	>=	0 to 3276.7	sec
			heater (see Look-Up-Table #21)		0 10 02. 0	
))			
			and			
			NO Pending or Confirmed DTCs:	=	see sheet inhibit	-
			-		tables	
		Release of tank heater circuit	(
			Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec
			or			
			Requested heating time for supply module	>=	0 to 3276.7	sec
			heater (see Look-Up-Table #21)			
)			
			or			
			((0.1	
			Requested defrosting time for Reductant tank heater (see Look-Up-Table #16)	>=	0 to 14400	sec
			or			
			Requested heating time for Reductant tank	>=	0 to 3277	sec
			heater (see Look-Up-Table #17)			
) and			
		1	and			ļ

Component / System	State or Status Sub-Grouping	Description of State or Status found in 12OBDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			(Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec
			or Requested heating time for supply module heater (see Look-Up-Table #21) ۱۱	>=	0 to 3276.7	sec
			or ((
			Requested defrosting time for pressure line heater (see Look-Up-Table #18)	>=	0 to 3276.7	sec
			Requested heating time for pressure line heater (see Look-Up-Table #20)	>=	0 to 3276.7	sec
			and (
			Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec
			Requested heating time for supply module heater (see Look-Up-Table #21)	>=	0 to 3276.7	sec
			or ((
			Requested defrosting time for Reductant tank heater (see Look-Up-Table #16) or	>=	0 to 14400	sec
			Requested heating time for Reductant tank heater (see Look-Up-Table #17)	>=	0 to 3277	sec
			and (
			Requested defrosting time for pressure line heater (see Look-Up-Table #18)	>=	0 to 3276.7	sec
			Requested heating time for pressure line heater (see Look-Up-Table #20)	>=	0 to 3276.7	sec
			and (
			Requested defrosting time for supply module heater (see Look-Up-Table #19)	>=	0 to 3276.7	sec

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			or Requested heating time for supply module heater (see Look-Up-Table #21)))	>=	0 to 3276.7	sec
			and NO Pending or Confirmed DTCs:	Н	see sheet inhibit tables	-
		Status of the battery voltage being in the valid working range for Reductant tank heater	battery voltage battery voltage for time	>	100 11 2	V V sec
		Status of the battery voltage being in the valid working range for pressure line heater	battery voltage battery voltage for time	>	100 11 2	V V sec
		Status of Reductant Tank Heater Release	(status of reductant tank heater temperature	= >	TRUE 0	- sec
			((Waiting time before tank heater released started with status of reductant tank heater temperature (please see the definition)		32767 FALSE	sec -

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
·) and (status of reductant tank heater temperature (please see the definition) Waiting time after tank heater release expired))	= >	TRUE 0	- sec
			or ((Waiting time before tank heater released started with status of reductant tank heater temperature (please see the definition)	> =	32767 FALSE	sec -
			and (status of reductant tank heater temperature (please see the definition) Waiting time after tank heater release expired))	= >	TRUE 0	sec
	Reductant Tank Level System States and Status		Tank level > full (100%) Warning (66.67%) < tank level < full (100%) Restriction (33.33%) < tank level < Warning (66.67%) Empty < tank level < Restriction (33.33%) Tank level < = 0.1%	= = = = =	Full OK Warning Restriction Empty	- - -
		Status of Reductant tank level reset when refilling is detected (please see the definition)	time since potential Reductant refill detection is set and with (>=	12	sec

Component /	State or Status	Description of State or Status	5.6.11	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Defined by:	Logic	Values	Units
			Derivation of the PT1 filtered level signal	>=	1.00	%/sec
			(DT1)			
			ignition on	=	TRUE	-
			engine speed	>	550	rpm
			Vehicle speed time since engine started	>= <=	6.22	mph
			(a) Time period for a positive slope to detect	=	(a) * (b) 12	sec
			refueling		12	300
			(b) Factor for the extension of the detection	=	20	factor
			time for refueling			
			since the following conditions met:	=	TRUE	-
			Falling edge of ignition or	=	TRUE	-
			Reductant Refill enabling conditions reset	=	TRUE	-
			timers			
)))			
			or			
			or (
			time since potential Reductant refill	>=	8	sec
			detection is set			
			and with			
			(Derivation of the PT1 filtered level signal	\	1.00	%/sec
			Derivation of the PTT filtered level signal (DT1)	>=	1.00	%/Sec
			filter release for Reductant tank level	=	TRUE	_
			calculation at ignition on on (Please see the			
			definition)			
			and with			
					TDUE	
			Frozen state is active during a certain	=	TRUE	-
			warning level (please see the definition) and with			
			and with			
			Reductant tank Temperature	>=	-100.04	°C
			or			
			Reductant low warning level (Please see	>=	0	level
			the definition)			
)))			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Definied by:	Logic	Values	Units
		Status of Reductant Tank Level Release	status of reductant tank level release (please see the definition) Status of Filter release for reductant tank level calculation (please see the definition) and	=	TRUE	-
			(() ambient temperature	>=	-100.04	°C
			status of reductant tank heater temperature (please see the definition)	=	FALSE	-
			Waiting time before tank heater released and	<	32767	sec
			status of reductant tank heater temperature (please see the definition)	=	TRUE	-
			Waiting time after tank heater release expired)	>	0	sec
			or (
			status of reductant tank heater temperature (please see the definition)	=	FALSE	-
			Waiting time before tank heater released and	>=	32767	sec
			status of reductant tank heater temperature (please see the definition)	=	TRUE	-
			Waiting time after tank heater release expired))	>=	0	sec
			or Frozen state is active during a certain warning level (please see the definition)	=	TRUE	-
			Vehicle speed) or	>=	6.22	mph
			filter release for Reductant tank level calculation at ignition on on (Please see the definition)	=	TRUE	-
		Status of Filter release for reductant tank level calculation				
			Reductant tank Temperature	>=	-100.04	°C

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			or Reductant low warning level (Please see		0	
			the definition)	>=	0	-
			NO Pending or Confirmed DTCs:	=	TRUE	-
			or Frozen state is active during a certain warning level (please see the definition)	=	TRUE	-
		Filter release for Reductant tank level calculation at Ignition on	ignition	=	on	-
			Engine on timer is expired (please see the definition)	=	FALSE	-
			Vehicle speed		0.62	mph
			Reductant low warning level (Please see the definition) and with	>=	49	level
			Raw Reductant tank level and with	>=	33.3	%
			Remaining Reductant quantity (a) - (b):	<	(a) - (b)	
			(a) Tank level for reserve mode (Restriction level) in [g]		2614	g
			(b) Tank level threshold range below Restriction threshold for ignition on refill detection release)	=	1015	g
			or Raw Reductant tank level and with	>=	66.7	%
			Remaining Reductant quantity (a) - (b):		(a) - (b)	
			(a) Tank level for reserve mode (Warning level) in [g]	=	5279	g
			(b) Tank level threshold range below WARNING threshold for ignition on refill detection release)	=	1617	g
			or Raw Reductant tank level	>=	100	%

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
	ous creuping		and with (Remaining Reductant quantity (a) - (b): (a) Tank level for reserve mode (Warning level) in [g] (b) Tank level threshold range below WARNING threshold for ignition on refill detection release))	>= =	(a) - (b) 5279 1617	g g
		Status of Refill detection of Reductant tank	Status of Refill detection of Reductant tank (please see the definition) Reductant tank level changed ((Captured Reductant tank level at last tank level change		TRUE Empty	
			Captured Reductant tank level at last tank level change) and		Restriction	-
			one or more of following conditions are met		Manaia a	
			status of Reductant tank level (please see the definition) or		Warning	-
			status of Reductant tank level (please see the definition) or	=	OK	-
			status of Reductant tank level (please see the definition))) or	=	Full	-
			Captured Reductant tank level at last tank level change or	=	Warning	-
			Captured Reductant tank level at last tank level change)	=	OK	-

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable Units
System	Sub-Grouping	found in 12OBDG09	•	Logic	Values	Units
			and (status of Reductant tank level (please see the definition)	=	Full	-
			or (Captured Reductant tank level at last tank level change status of Reductant tank level (please see the definition)		OK Full	-
		Engine on timer is expired	time since engine started	>=	(a) * (b) 12 20	sec sec
			and with ((ignition engine speed Vehicle speed	= > >=	on 550 6.22	sec rpm mph
) or (Vehicle speed NO Pending or Confirmed DTCs:	>= =	6.22 TRUE	mph
			for time)) and with timer reset conditions (Falling edge of ignition	>	1 TRUE	sec
			or Reductant Refill enabling conditions reset timers	=	TRUE	-
	Reducant Tank Level Low Warning States	Normal_Operation_OK: 0 decimal, normal operation	Reductant tank level	=	Full	·

Component / System	State or Status Sub-Grouping	Description of State or Status found in 12OBDG09	Defined by:	Enable Logic	Enable Values	Enable Units
- Cycle	ous crouping	Iodila III 12025000	and with	Logio	Values	
			(
			Warning level or	<=	49	-
			GI (
			Previous warning level	>	49	
			vehicle speed	<=	98.75	mph
			<i>"</i>			
			or Data to 10 all to 10 al		2	
			Reductant Quality state	>	0	-
		Warning_Leve1: 1 decimal, Warning	Reductant tank level	<	Full	-
		level 1	Neduciani tank level	,	i dii	
			Remaining mileage	>	1558.75	miles
			and with			
			Warning level	<=	49	Warning
			or			level
			or (
			Previous warning level	>	49	Warning
			vehicle speed	<=	98.75	level mph
))	,_	30.73	Прп
			and with		•	
			Reductant Quality state	=	0	-
		Warning_Level2: 2 decimal, Warning	Reductant tank level	<	Full	-
		level 2		`	i dii	
			Remaining mileage	<=	1558.75	miles
			and with			
			Warning level	<=	49	Warning
			or.			level
			or (
			Previous warning level	>	49	Warning
			vehicle speed	<=	98.75	level mph
		l	verlicie speeu	~-	30.13	ΠρΠ

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
)) and with Reductant Quality state	=	0	-
		Warning_Level3: 16 decimal,	Reductant tank level	<	Full	-
		Warning level 3	Remaining mileage and with	>	855	miles
			(Warning level	=	2	Warning level
			or Warning level	=	16	Warning level
) and with initialization phase after Reductant refill event is active	=	TRUE	-
			Reductant Quality state	=	0	-
		Warning_Level4: 32 decimal, Warning level 4	Reductant tank level	<	Full	-
		g	Remaining mileage and with	<=	855	miles
			(Warning level	<=	49	Warning level
			or			
			(Previous warning level	>	49	Warning level
			vehicle speed))	<=	98.75	mph
			and with Reductant Quality state	=	0	-
		Marriage Lavel For Co. Le inch			_	
		Warning_Level5: 48 decimal, Warning level 5	((

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			Reductant tank level Remaining mileage and with	< <=	Full 628.75	- miles
			(Warning level	<=	49	Warning level
			or (
			Previous warning level		49	Warning level
			vehicle speed))) or	<=	98.75	mph
			(Warning level	=	48	Warning level
			initialization phase after Reductant refill event is active))		TRUE	-
			and with Reductant Quality state	=	0	-
					_	_
		Warning_Level6: 49 decimal, Warning level 6	((
		3	Warning level	=	49	Warning level
			initialization phase after Reductant refill event is active າ		TRUE	-
			or (
			Warning level	<	49	Warning level
			Failed Reductant system pressure build up	=	1	-
			and with Reductant Quality state	=	0	-

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable Units
System	Sub-Grouping	found in 120BDG09 Warning_Level8: 80 decimal,Vehicle speed restriction mild	Warning level	Logic =	Values 80	Warning level
			initialization phase after Reductant refill event is active		TRUE	
			and with Reductant Quality state		0	
		Warning_Level10: 112 decimal,Vehicle speed restriction	Warning level	=	112	Warning level
		aggressive	initialization phase after Reductant refill event is active		TRUE	-
			and with Reductant Quality state		0	-
		Warning_Level12: 144 decimal,	Warning level	=	144	Warning
		Vehicle speed restriction severe	initialization phase after Reductant refill event is active	=	TRUE	level -
			and with Reductant Quality state		0	-
		Warning_Level14: 176 decimal,	Warning level	=	176	Warning
		Vehicle speed restriction final	initialization phase after Reductant refill event is active	=	TRUE	level -
			and with Reductant Quality state		0	-
	Reductant frozen System States	Frozen state is active during a certain warning level	ignition	=	On	-
			for time Reductant tank Temperature		5 -9.04	sec °C

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			Reductant low warning level (Please see the definition)	>=	2	level
			the definition)			
		Status of Reductant tank as frozen				
			Engine off Time	>	14400	sec
			Reductant tank Temperature	<	-11.04	°C
)			
			or /			
			(Engine off Time	<=	7200	sec
			time since the following conditions are met	<=	7200	sec
			(0	
			status of reductant tank heater defrost Vehicle speed	= >	On or Defrost 6.22	- mph
			Status of urea tank as frozen (please see	=	TRUE	- -
			the definition)			
))			
		Status of Low Reductant Pump				
		Pressure - Under Reductant warning				
		level 3 - Main state 0x30	Reductant low warning level (Please see	>=	64	
			the definition)	/-	04	-
			number of pressure build-up attempts	>=	2	counts
			and			
			(status of SCR control sub state (please see	=	Pressure Build up	_
			the definition)	_	r ressure build up	-
			Reductant Pump Module Pressure	<	350	kPa
			Dwell time in Pressure Build up substate		10	sec
			system pressurizes in pressure buildup and	>=	10	counts
			ventilation states Reductant Defrost check (please see the	=	TRUE	_
			definition)			
)			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System SCR System Diagnosis	Sub-Grouping SCR System Long Term	found in 120BDG09 Long-term Adaption Triggered	-	Logic	Values	Units
Ook Oystom Blaghosis	Adaptation Release States	Long term / tadption magered				
			underdosing detected (please see the	=	TRUE	-
			definition) OR			
			overdosing detected (please see the	=	TRUE	-
			definition)			
					_	
		Underdosing detected				
			Difference between the NOx mass of the sensor and of the model during first		10	g
			functional evaluation			
			OR Difference between the NOx mass of the		10	g
			sensor and of the model during second		.0	9
			functional evaluation OR			
			Difference between the NOx mass of the		-0.25	g
			sensor and of the model during third functional evaluation			
			idilolional evaluation			
		Overdosing detected				
			Difference between the NOx mass of the sensor and of the model during first		-6	g
			functional evaluation			
			OR Difference between the NOx mass of the	<=	-6	a
			sensor and of the model during second		-0	g
			functional evaluation OR			
			Difference between the NOx mass of the	<=	-0.8 to -0.6	g
			sensor and of the model during third			· ·
			functional evaluation (see Look-Up-Table #9)			
			,			
		Status of the SCR adaptation	(
I	I	plausibility check active	l l			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			Status of NOx signal of downstream NOx sensor (please see the definition)	=	TRUE	-
			NOx concentration downstream SCR catalyst	>	15	ppm
			for time	>	3	sec
			Estimated SCR catalyst efficiency for time	> >	0.3 3	factor sec
			ioi time		3	360
			NOx concentration deviation between sensor reading and modeled NOx concentration downstream SCR catalyst	>	measured parameter	-
			for time	>	10	sec
			(Time since when the Reductant load level adaptation and the plausibility have been locked or	>=	600	sec
			Time since when the Reductant load level adaptation and the plausibility have been locked	>=	50	sec
			Integrated NOx mass since Reductant load level adaptation and plausibility have been locked)	>=	2	g
			Difference between nominal and estimated Reductant	<	0.125	g
			Difference between nominal and estimated Reductant	>=	-0.5	g
			Filtered Upstream NOx mass flow	>=	10	mg/sec
			Filtered Upstream NOx mass flow	<=	500	mg/sec
			Upstream Nox mass flow difference : (a) - (b)	>=	0	mg/sec
			Upstream Nox mass flow difference : (a) - (b)	<=	500	mg/sec
			and with			
			(a) Filtered Upstream NOx mass flow (b) Filtered actual upstream NOx mass flow			
)			

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
System	Sub-Grouping	Tourid III 120BDG09		Logic	values	Onits
			Status of pre controlled dosing (please see the definition)	=	FALSE	-
			Difference between nominal and estimated Reductant	<	0.125	g
			Difference between nominal and estimated Reductant	>=	-0.5	g
			for time		5	sec
			HC load in SCR catalyst		10	factor
			overall aging factor of the SCR catalyst	>=	0	factor
			for time	>	1	sec
			Temperature gradient of SCR	>=	-1	°C/sec
			Temperature gradient of SCR	<=	1	°C/sec
			for time	>	18	sec
			Integrated NOx mass flow after engine start	>=	5	g
			Release of Reductant dosing	=	active	-
			engine operating condition based on engine speed and injection quantity (see Look-Up- Table #10)	>	0 to 1	factor
			(Difference between nominal and estimated Reductant		-0.05	g
			Reductant mass flow (see Look-Up-Table #8)		0 to 0.04	g
			Elapsed time of the fill level timer)	>	20	sec
		State of the NH3 (Ammonia) slip detection				
			Reductant concentration downstream SCR	<	32767	ppm
			and (a) - (b)	<	0	g/sec
			(a) Filtered NOx mass flow downstream		measured	- -
			SCR measured by the sensor		parameter	

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			(b) Filtered and delayed NOx raw emission mass flow upstream of SCR	=	measured parameter	-
			mass now apolically of Solic		parameter	
		Department of decimal to account the				
		Deactivation of dosing to execute the NOx Offset test				
		THE A CHOCK LOCK	SCR catalyst temperature	>	400.06	°C
			SCR catalyst temperature	<	999.96	°C
			time	>	60	sec
			and			
			Currently dosed Reductant mass flow	<=	0.005	g/sec
			time	>	30	sec
			une		30	3 C C
			and			
			Feed ratio			
			(a) / ((b) * (c))	<=	0.1	ratio
			(a) Currently dosed Reductant mass flow	=	measured	-
			(b) NOx raw emission mass flow	=	parameter measured	_
			(5)		parameter	
			(c) Stoichiometric conversion factor NOx to	=	calculated	-
			Reductant		parameter	
			time	>	10	sec
			and			
			Estimated current Reductant load	<=	0.3	g
			time	>	10	sec
		Release plausibility of Reductant				_
		Load				
			Release plausibility timer active	>=	600	sec
			or /			

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
- Oyotom	Gus Grouping	ISUNU III 12055000	Release plausibility timer active Integrated NOx raw emission since fill level adaptation and plausibility have been locked)	>= >=	50 2	sec g
		Status for disabling the SCR Efficiency monitor following an SCR		_		
		Adaptation cycle completion	Maximum dosing quantity	<	0.6	g/sec
			or (a) - (b) (a) Reductant Dosing quantity	> =	0 measured parameter	- -
			(b) Maximum Reductant Dosing quantity	=	calculated parameter	-
			or (a) - (b) (a) Reductant Desired value	> =	0 calculated parameter	-
			(b) Reductant Dosing quantity limitation due to frozen tank	=	calculated parameter	-
		Request for pre controlled dosing				
			Filtered exhaust gas mass flow (a) Correction factor for the upper hysteresis threshold for filtered exhaust-gas mass flow, dependent on HC-	> =	(a) * (b) 1	- factor
			contamination (b) Upper hysteresis threshold for filtered exhaust-gas mass flow, dependent on thermal ageing	=	5040.00	g/sec
			and Filtered NOx mass flow upstream SCR	>	(a) * (b)	-

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09	Definied by.	Logic	Values	Units
			(a) Correction factor for the upper	=	1	factor
			hysteresis threshold for filtered exhaust-gas			
			mass flow, dependent on HC-			
			contamination SCR			
			(b) Upper hysteresis threshold for filtered	=	0.25	g/s
			exhaust-gas mass flow, dependent on			
			thermal ageing SCR			
			and			
			Engine coolant temperature		(a) + (b)	-
			(a) Lower hysteresis threshold for engine		105.06	°C
			temperature			
			(b) Offset for lower hysteresis switch on		50	K
			threshold for engine temperature			
			Engine coolant temperature	>	108.06	°C
			and			
			ambient pressure		(a) + (b)	-
			(a) Upper hysteresis threshold for		74.5	kPa
			environment pressure			. –
			(b) Offset for upper hysteresis switch on	=	65.0	kPa
			threshold for environment pressure			
			or		740	
			ambient pressure	<	74.0	kPa
			and a			
			and Intake air temperature		(a) + (b)	
			(a) Lower hysteresis switch on threshold for		(a) + (b) -6.54	°C
			inlet air temperature		-0.54	C
			(b) Offset for upper hysteresis switch on	=	49.5	°C
			threshold for inlet air temperature	_	43.5	O
			or			
			Intake air temperature	<	-8.04	°C
			intake all temperature		0.01	Ü
)			
			'			
			and			
			(
			ambient temperature	>=	-7.04	°C
			ambient pressure	>=	74.8	kPa
			Selected temperature used for locking pre	>=	209.96	°C
			controlled mode			
			Selected temperature used for locking pre		309.96	°C
			controlled mode			

Component /	State or Status	Description of State or Status	Defined by:	Enable	Enable	Enable
System	Sub-Grouping	found in 12OBDG09		Logic	Values	Units
			engine operation in normal mode	=	TRUE	-
			SCR Nox Catalyst Efficiency check was performed this drive cycle	=	FALSE	-
			Incorrect Reductant Composition check was performed this drive cycle	=	FALSE	-
			NO Pending or Confirmed DTCs:	=	TRUE	-
			, ((
			(k) + (l) + (m)	>	75	
			(k) = (a) * (b) (a) entry condition for pre controlled dosing at sea level (see Look-Up-Table #13)	=	0 to 100	-
			(b) Altitude multiplier factor for sea level	=	measured paramter	-
			(I) = (c) * (d) * (e) (c) entry condition for online dosing at Mid level (see Look-Up-Table #12)	=	0 to 100	-
			(d) Multiplier to Mid Level enable speed load map	=	1	factor
			(e) Altitude multiplier factor for medium altitude	=	measured paramter	-
			(m) = (f) * (g) * (h) (f) Entry condition for online dosing at Hi level (see Look-Up-Table #11)	=	0 to 100	-
			(g) Multiplier to Hi Level enable speed load map	=	1	factor
			(h) Altitude multiplier factor for high altitude	=	measured paramter	-
			and Low pass filtered rNOxNSCDs signal	>	2000	-
			,			
		start temperature is captured in EERPOM if monitoring is active over several driving cycles	continuation of previously started tank temperature performance monitoring cycle (see definition)	=	1.56	°C

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
System	Sub-Grouping	Tourid III 120BBG09		Logic	values	Onito
		or				
1			(
		start temperature is captured in	continuation of previously started tank	=	FALSE	-
1		EERPOM if monitoring is not active	temperature performance monitoring cycle			
1		over several driving cycles	(see definition)			
			ignition on for time	>	60	sec
			or	=	TRUE	
1			ice detection by tank temperature			
			difference:			
			(a) - (b)	<=	-0.14	°C
			(a) filtered current tank temperature	=	measured	-
			(b) tank temperature captured at the	=	paramter measured	_
1			beginning of current monitoring cycle	_	paramter	_
1))		parao.	
1			or			
			(a) - (b)	<=	-0.14	°C
1			(a) filtered current tank temperature	=	measured	-
			4		paramter	
			(b) tank temperature captured at the	=	measured	-
1			beginning of current monitoring cycle		paramter	
1			monitoring was performed in previous			
			driving cycle			
			g 5, 2.0			
1					. = 2	
		continuation of previously started	temperature difference: (a) - (b)	<=	1.56	°C
		tank temperature performance monitoring cycle				
		monitoring cycle	(a) filtered current tank temperature	=	measured	_
			(a) morea sarront tarik temperature		paramter	
			(b) tank temperature of the previous driving	=	measured	-
			cycle		paramter	
			temperature difference: (a) - (b)	<=	0	°C
			(a) tank temperature of the previous driving	=	measured	-
			cycle		paramter	
			(b) filtered current tank temperature	=	measured	-
			temperature difference: (a) - (b)	>=	paramter 0	°C
	l l		temperature unierence. (a) - (b)		U	0

Component / System	State or Status Sub-Grouping	Description of State or Status found in 120BDG09	Defined by:	Enable Logic	Enable Values	Enable Units
- Cystem	oub-orouping	104114 III 120BB003	(a) tank temperature of the previous driving	=	measured	-
			cycle		paramter	
			start tank temperature of current monitoring cycle from EEPROM (see definition)	=	measured paramter	-
			system com EEn reem (see demmasn)		paramer	
			Engine off Time	<=	2000	sec
			This monitor was complete in the last driving cycle	=	FALSE	
			ice detection by tank temperature			
			difference:			
			(a) - (b)	>	-0.14	°C
			(a) filtered current tank temperature	=	measured paramter	-
			(b) tank temperature captured at the	=	measured	-
			beginning of current monitoring cycle		paramter	
		State of Reductant injection valve	((
		Component Protection	status of SCR control sub state (please see	=	Metering control	_
			the definition)		motoring control	
			and with			
			(
			PM Filter Regeneration	=	not active	-
			Modeled Reductant injection valve tip	>	100.96 to 114.96	°C
			temperature based on its coil temperature (see Look-Up-Table #15)			
			(000 2001.05)			
			or			
			(PM Filter Regeneration	=	active	
			Reluctant dosing valve modeled		19.96	°C
			temperature			
			//			
			or			
			(_		
			status of SCR control sub state (please see	≠	Metering control	_

Component / System	State or Status Sub-Grouping	Description of State or Status found in 12OBDG09	Defined by:	Enable Logic	Enable Values	Enable Units
			and with (PM Filter Regeneration Modeled Reductant injection valve tip temperature based on its coil temperature (see Look-Up-Table #15) or (PM Filter Regeneration Modeled Reductant injection valve tip temperature based on its coil temperature)))	= >	not active 100.96 to 114.96 active 19.96	°C
Turbo Charger		Turbocharger (VNT) wiping active	The Variable Nozzle Turbocharger Control has an intrusive mode where: VNT wiping is a sweep of the vane position control throughout its range of motion which is used to: avoid a binding of the VNT vanes due to soot accumulation during long idle operation with a cold engine.			

le no	p. Fault Codes	Label (Internal Manufacturer Reference)
1	P0101	AFS_rAirThresCor_CUR
	Intake Air Temperature (°C)	-100.04 -0.04 0.96 38.96 39.96 125.86
	Correction Factor (factor)	0.05 0.05 0 0 0
2	P2199	Air_tDiffMaxHiTAFS_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 17999 18000 28799 28800 30000 3200
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 100 100
3	P10CF	Air_tDiffMaxHiTCACDs_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 17999 18000 28799 28800 30000 320
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 100 100
4	P040F	Air_tDiffMaxHiTEGRClr2Ds_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 10000 18000 28799 28800 30000 320
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 100 100
5	P2199	Air_tDiffMaxLoTAFS_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 17999 18000 28799 28800 30000 320
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 20 20
6	P10CF	Air_tDiffMaxLoTCACDs_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 17999 18000 28799 28800 30000 320
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 35 35
7	P040F	Air_tDiffMaxLoTEGRCIr2Ds_CUR
	Engine Off Time (sec)	600 700 800 900 1000 2000 3000 4000 5000 8000 17999 18000 28799 28800 30000 320
	Delta Temperature (°C)	999 999 999 999 999 999 999 999 999 999 999 999 999 999 999 20 20
8	P0401	AirCtl_facEnvPresMinDvt_CUR
	Ambient Pressure (kPa)	65 70 75 80 85 90 95 110
	Correction Factor (-)	0.71 0.71 0.71 0.85 0.85 0.92 1 1
9	P0401	AirCtl_mEGRMinDvtLim_CUR
	Ambient Pressure (kPa)	67 70 73 76 79 82 85 88 91 94 97 100
	Air Mass Flow (g/rev)	0.8 0.8 0.8 0.8 0.85 0.9 0.95 1 1.05 1.1 1.15 1.2

Table no.	Fault Codes		Label (Interna	l Manufa	cturer R	eference)			
10	P0402		AirCtl_mMaxD	vt_MAP						
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		550	1000	1200	1300	1400	1500	2000	3000
		20	0.6	0.5	0.5	0.4	0.4	0.4	0.6	0.6
		40	0.6	0.5	0.5	0.4	0.4	0.4	0.6	0.6
		60	0.6	0.5	0.5	0.4	0.4	0.4	0.6	0.6
		80	0.6	0.5	0.5	0.4	0.4	0.4	0.6	0.6
		100	0.6	0.5	0.5	0.4	0.4	0.4	0.6	0.6
		120	0.6	0.6	0.5	0.5	0.5	0.5	0.6	0.6
		160	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6
		200	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6

11 P0400

AirCtl_mMaxDvtPwr_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	0	500	1000	1500	2000	2500	3000	3750
0	2	2	2	2	2	2	2	2
20	2	2	2	2	2	2	2	2
40	2	2	2	2	2	2	2	2
60	2	2	2	2	2	2	2	2
80	2	2	1.8	1.8	1.8	1.8	2	2
160	2	2	1.8	1.6	1.6	1.6	2	2
320	2	2	1.8	1.6	1.6	1.6	2	2
380	2	2	2	2	2	2	2	2

12 P0401

AirCtl_mMinDvt_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	550	1000	1400	1800	2200	2600	3000	3750
	-0.56	-0.56	-1	-1	-1	-1	-1.2	-1.2
20	-0.56	-0.56	-1	-1	-1	-1	-1.2	-1.2
40	-0.56	-0.56	-1	-1	-1	-1	-1.2	-1.2
60	-0.56	-0.56	-1	-1	-1	-1	-1.2	-1.2
80	-0.56	-0.56	-1	-1	-1	-1	-1.2	-1.2
100	-0.9	-0.9	-0.9	-0.9	-0.9	-0.9	-1.2	-1.2
120	-1	-1	-1	-1	-1	-1	-1.2	-1.2
150	-1	-1	-1	-1	-1	-1	-1.2	-1.2

13 P2138

APP_uSync_CUR

Accel Pedal Voltage (V)	0.5	2.1	2.5
Pedal Deviation (V)	0.12	0.18	0.18

14 P057B

Brk_facEWMASlowTest_CUR

Brake Position Sensor Voltage (V)	0	0.0346	0.035	0.04	0.045	0.051	0.0512	5
factor (-)	0	0	0	0	0	0	1	1

15 P008F

CEngDsT_tDiffMaxHi_CUR

Engine Off Time (sec)	600	700	800	900	1000	2000	3000	4000	5000	8000	17999	18000	28799	28800	30000	32767
Delta Temperature (°C)	999	999	999	999	999	999	999	999	999	999	999	999	999	100	100	100

ıble no.	Fault Codes	Label (Interna			erence)												
16	P008F	CEngDsT_tDi	fMaxLo_Cl	UR													
	Engine Off Time (sec)	600	700	800	900	1000	2000	3000	4000	5000	8000	17999	18000	28799	28800	30000	32767
	Delta Temperature (°C)	999	999	999	999	999	999	999	999	999	999	999	999	999	20	20	20
17	P0336	EpmCrS_facG	apPlausHi	gh_CA													
	-	8	5.8125	3.375	3.375												
18	P0336	EpmCrS_facIr	ıcPlausHigl	h_CA													
	-	2	1.8125	1.5	1.5												
19	P02CD, P02CF, P02D1, P02D3, P02D5, P02D7, P02D9, P02DB	ETClb_pRailS	et_CA														
	Rail Pressure Setpoint (kPa)	30000	70000	90000													
20	P02CD, P02CF, P02D1, P02D3, P02D5, P02D7, P02D9, P02DB	ETClb_tiET_N	IAX_CA														
	Injector Energizing Time (usec)	670.8	384.4	353.2													
21	P01CD, P01CF, P01D1, P01D3, P01D5, P01D7, P01D9, P01DB	ETClb_tiETFb	OfsMax_C	A													
	Injector Energizing Time (usec)	16	12	10													
22	P01CD, P01CF, P01D1, P01D3, P01D5, P01D7, P01D9, P01DB	ETClb_tiETFb	OfsMin_C <i>A</i>	A													
	Injector Energizing Time (usec)	16	12	10													
23	P144B	ETCtl_stPOp0	ctVILopMax	x_MAP													
		750 0 0 0 0 60 0	900 1 1	2250 1 1	3000 0 0												
	20		0	0	0												

e no.	Fault Codes	La	bel (Interna	l Manufa	cturer R	eference)												
	P144C		Ctl_stPOpC															
				•														
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		750	900	2250	3000												
		0	0	1	1	0												
		40	0	1	1	0												
		160	0	1	1	0												
		200	0	0	0	0												
5	P24A0	ET	CtlHCI_stP	OpCtVH(CILopMax	InjMs_MA	Р											
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		700	900	2250	3000												
		0	0	1	1	1												
		40	0	1	1	1												
		160 200	0	1	1	1												
		200	U															
6	P24A1	ET	CtlHCI_stP	OpCtVH(CILopMinI	njMs_MAI	0											
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		700	900	2250	3000												
		0	0	1	1	1												
		40	0	1	1	1												
		160	0	1	1	1												
		200	0	1	1]	1												
7	P11DC	Ex	h_facLamS	atNoCat	2Ds_CUF	R												
7	P11DC	Ex	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	1
7	P11DC - -	Ex	h_facLamS 1 0.2				5	6 1.2	7	8	9	10	11 2.2	12 2.4	13 2.6	14 2.8	15	1 3.
	P11DC P11DB		1	2 0.4	3 0.6	4									13 2.6	14 2.8		1 3.
	-		1 0.2 h_facLamS	2 0.4 atNSCD	3 0.6	4	1	1.2	1.4	1.6	1.8	2	2.2		13 2.6	14 2.8		1 3.
	-		0.2	2 0.4	3 0.6	4									13 2.6	14 2.8		1 3
В	-	Ex	1 0.2 h_facLamS	2 0.4 eatNSCD 3 0.1	3 0.6 s_CUR 4 1.25	5 1.5	6	1.2	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		3
8	- - - P11DB	Ex	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700	2 0.4 aatNSCD 3 0.1 dPlausT	3 0.6 s_CUR 4 1.25 Mon_MAF	4 0.8 5 1.5	6 3.848	7 3.889	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		1 3.
3	P11DB	Ex Ex	1 0.2 h_facLamS 0 0.1 h_stPOpMo 700 0	2 0.4 0.4 3 0.1 dPlausT	3 0.6 S_CUR 4 1.25 Mon_MAR 1500	4 0.8 5 1.5 2000 0	6 3.848 3000 0	7 3.889 3300 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		3.
8	P11DB	Ex Ex 0 20	1 0.2 h_facLamS 0 0.1 h_stPOpMo 700 0 255	2 0.4 satNSCD 3 0.1 dPlausT 1000 0 255	3] 0.6] 8_CUR 4 1.25] Mon_MAF 1500] 0 255	4 0.8 5 1.5 2000 0 0 255	3000 0 255	7 3.889 3300 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		3.
8	P11DB	Ex 0 0 20 40	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700 0 255 255	2 0.4 satNSCD 3 0.1 dPlausT 1000 0 255 255	3 0.6 S_CUR 4 1.25 Mon_MAR 1500 0 255 255	4 0.8 5 1.5 2000 0 0 255 255	3000 0 255 255	7 3.889 3300 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		1 3.
8	P11DB	Ex 0 20 40 100	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700 0 0 255 255 255	2 0.4 satNSCD 3 0.1 dPlausT 1000 0 255 255 255	3 0.6 S_CUR 4 1.25 Mon_MAR 1500 0 0 255 255 255	4 0.8 5 1.5 200 0 0 255 255 255	3000 0 255 255 255	3.889 3.889 0 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		1 3.
8	P11DB	Ex 0 20 40 100 200	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700 0 255 255 255 0	2 0.4 satNSCD 3 0.1 dPlausT 1000 0 255 255 255	3 0.6 s_CUR 4 1.25 Mon_MAR 1500 0 0 255 255 255	4 0.8 5 1.5 255 255 255 255	3000 0 255 255 255 255	3300 0 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		1 3.
8	P11DB	Ex 0 20 40 100	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700 0 0 255 255 255	2 0.4 satNSCD 3 0.1 dPlausT 1000 0 255 255 255	3 0.6 S_CUR 4 1.25 Mon_MAR 1500 0 0 255 255 255	4 0.8 5 1.5 200 0 0 255 255 255	3000 0 255 255 255	3.889 3.889 0 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		11 33.
3	P11DB	Ex 0 20 40 100 200 320	1 0.2 h_facLamS 0 0.1 h_stPOpMc 700 0 255 255 255 0	2 0.4 atNSCD 3 0.1 dPlausT 1000 0 255 255 255 255	3 0.6 S_CUR 4 1.25 Mon_MAF 1500 0 255 255 255 255 0	2000 0 255 255 255 255 0	3000 0 255 255 255 255	3300 0 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		133
9		Ex 0 20 40 100 200 320	1 0.2 h_facLamS 0 0.1 h_stPOpMo 700 0 255 255 255 0 0	2 0.4 atNSCD 3 0.1 dPlausT 1000 0 255 255 255 255	3 0.6 S_CUR 4 1.25 Mon_MAF 1500 0 255 255 255 255 0	2000 0 255 255 255 255 0	3000 0 255 255 255 255	3300 0 0 0	1.4	1.6	1.8	15	2.2		13 2.6	14 2.8		3200

Table no.	Fault Codes	Label (Inte				e)												
31	P20E2	Exh_tDiffM	axLoTOx	iCatDs_Cl	JR													
	Engine Off Time (sec)	6	00 70	00 80	0 900	1000	2000	3000	4000	5000	8000	17999	18000	28799	28800	30000	32000	
	Delta Temperature (°C)			99 99			999	999	999	999	999	999	999	999	30	30	30	
32	P0483	FanCtl_fac	DiaDrvSp	d_CUR														
	Fan Speed (rpm)	4	00 16	79 168	0 1800	2000	2400	2800	3200	3600	4000	4400	4800	5200	5600	6000	6400	6800
	factor (-)		0	0	1 1	1	1	1	1	0.9	0.8	0.7	0.6	0.4	0.2	0	0	(
33	P0483	FanCtl_fac	DiaDrvSt	ab_CUR														
	Fan Speed (rpm)	-16	00 -120	00 -70	0 -400		400	700	1200	1600								
	factor (-)		0	0 0.	6 1	1	1	0.6	0	0								
34	P0483	FanCtl_fac	DiaECT_	CUR														
	Engine Coolant Temperature (°C)	-20.	04 -7.0	04 19.9	6 68.96	69.96	79.96	99.96	104.96	124.96								
	factor (-)		0	0	0 0	0.6	0.95	1	0.95	0.9								
35	P0483	FanCtl_fac	DialAT_C	CUR														
	Intake Air Temperature (°C)	-8.)4 -7.0	0.0-0.0			19.96	44.96	69.96	99.96								
	factor (-)		0 0	0.6	2 0.7	0.8	1	1	1	0.9								
36	P0495	FanCtl_nD	iaHiSpd_	CUR														
	Fan Drive Speed (rpm)	4	00 120	00 150	0 1600	1800	2000	2400	2800	3200	3600	4000	4400	4800	5200	5600	6000	6800
	Fan Speed (rpm)	4	00 120				1500	1500	1500	1500	1500	1500	1500	1500	1500	1500	1500	1500
37	P0495	FanCtl_vol	ClthDia_0	CUR														
	Fan Drive Speed (rpm)			08 00			1400	1600	1800	2000	2200	2400	2600	2800	3000	3200	3400	3600
	Clutch Fluid Vol (L)	0.0	0.00	55 0.00	6 0.011	0.011	0.011	0.011	0.011	0.011	0.0105	0.0105	0.0105	0.0105	0.0115	0.011	0.011	0.0105
38	P0263, P0266, P0269, P0272, P0275, P0278, P0281, P0)284 FBC_qLim	Neg_MAF	Þ														
	ECT (°C) / Inj. Qty (mm^3/rev)		0		2 76	448	464	472	480									
		10.04 03.96	0	0 -1 0 -1			-17 -17	-17 -17	-17 -17									
		04.96	0	0 -1			-17	-17	-17									
		05.96	0	0 -1		-17	-17	-17	-17									
		06.96	0	0 -1	2 -17	-17	-17	-17	-17									
	11	17.06	Λ	Λ 1	2 17	17	17	17	17									

-17 -17

-17

-17 -17 -17

-17 -17

-17

-17 -17 -17

-17 -17 -17

0

-12 -12 -12

0

107.96 109.96

134.96

Table no. | Fault Codes | Label (Internal Manufacturer Reference)

39 P0263, P0266, P0269, P0272, P0275, P0278, P0281, P0284 FBC_qLimPos_MAP

ECT (°C) / Inj. Qty (mm^3/rev)	0	8	52	76	448	464	472	480
-4	0.04	0	12	17	17	17	17	17
10	3.96 0	0	12	17	17	17	17	17
10	14.96 0	0	12	17	17	17	17	17
10	5.96 0	0	12	17	17	17	17	17
10	6.96 0	0	12	17	17	17	17	17
10	7.96 0	0	12	17	17	17	17	17
10	9.96	0	12	17	17	17	17	17
13	4.96 0	0	12	17	17	17	17	17

41 P111F

FIPmpT_tDiffMaxHi_CUR

Engine Off Time (sec)	600	700	800	900	1000	2000	3000	4000	5000	8000	17999	18000	28799	28800	30000	32000
Delta Temperature (°C)	999	999	999	999	999	999	999	999	999	999	999	999	999	100	100	100

42 P111F

FIPmpT_tDiffMaxLo_CUR

Engine Off Time (sec)	600	700	800	900	1000	2000	3000	4000	5000	8000	17999	18000	28799	28800	30000	32000
Delta Temperature (°C)	999	999	999	999	999	999	999	999	999	999	999	999	999	20	20	20

43 P0171, P0172, P026C, P026D

FMO_facObsvrCmpnProtnRels_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	600	1200	1600	2200	2400	3000	3200
	0	1	1	1	1	1	1	1
28	0	1	1	1	1	1	1	1
280	0	1	1	1	1	1	1	1
300	0	0	0	1	1	1	1	1
320	0	0	0	1	1	1	0	0
340	0	0	0	1	1	1	0	0
360	0	0	0	0	1	1	0	0
380	0	0	0	0	0	0	0	0

44 P026D

FMO_qFlSysThresMax_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	400	450	500	550	700	750	800	850
12	19.6	19.6	19.6	19.6	22.4	22.4	25.6	24
16	16	19.2	19.2	19.2	23.2	23.2	26	24
24	23.2	23.2	25.2	25.2	25.2	25.2	26	28
40	23.2	23.2	25.2	25.2	25.2	25.2	26	28
56	23.2	23.2	25.2	25.2	25.2	25.2	26	28
72	23.2	23.2	25.2	25.2	25.2	25.2	26	28
84	34.8	34.8	34.8	34.8	34.8	34.8	34.8	34.8
100	34.8	34.8	34.8	34.8	34.8	34.8	34.8	34.8

o. Fault Codes	Table no.
 P026C	45
P026C	45

Injection Qty (mm^3/rev) / Engine Speed (rpm)	400	450	500	550	700	750	800	850
	2 -34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8
	6 -34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8
	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8	-34.8
	-27.6	-27.6	-27.2	-21.6	-24.4	-24.4	-24.4	-25.2
	-27.6	-27.6	-27.2	-21.6	-24.4	-24.4	-24.4	-25.2
	'2 -27.6	-27.6	-27.2	-21.6	-24.4	-24.4	-24.4	-25.2
	-27.6	-27.6	-27.2	-21.6	-24.4	-24.4	-24.4	-25.2
10	-26	-26	-26	-21.6	-21.2	-21.2	-21.2	-20

46 P0172 FMO_qOBDMax_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	700	900	1000	1100	1200	1300	1500
40	46.12	52.44	58.72	65.04	68.16	71.32	77.64	109.12
80	54.04	60.36	66.64	72.96	76.12	79.24	85.56	117.04
120	62	68.28	74.6	80.88	84.04	87.2	93.48	125
160	65.96	72.24	78.56	84.84	88	91.16	97.44	128.96
180	69.92	76.2	82.52	88.8	91.96	95.12	101.4	132.92
200	73.88	80.16	86.48	92.76	95.92	99.08	105.36	136.88
240	77.84	84.12	90.44	96.72	99.88	103.04	109.32	140.84
280	101.64	107.92	114.24	120.52	123.68	126.84	133.12	164.64

47 P0171 FMO_qOBDMin_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	700	900	1000	1100	1200	1300	1500
40	-46.12	-52.44	-58.72	-65.04	-68.16	-71.32	-77.64	-109.12
80	-54.04	-60.36	-66.64	-72.96	-76.12	-79.24	-85.56	-117.04
120	-62	-68.28	-74.6	-80.88	-84.04	-87.2	-93.48	-125
160	-65.96	-72.24	-78.56	-84.84	-88	-91.16	-97.44	-128.96
180	-69.92	-76.2	-82.52	-88.8	-91.96	-95.12	-101.4	-132.92
200	-73.88	-80.16	-86.48	-92.76	-95.92	-99.08	-105.36	-136.88
240	-77.84	-84.12	-90.44	-96.72	-99.88	-103.04	-109.32	-140.84
280	-101.64	-107.92	-114.24	-120.52	-123.68	-126.84	-133.12	-164.64

48 P0171, P0172, P026C, P026D FMO_stOutObsvr_MAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	600	1000	1200	1600	2200	2400	2800	3000	3200
0	0	0	0	0	0	0	0	0	0	0
16	0	1	1	1	1	1	1	1	1	1
240	0	1	1	1	1	1	1	1	1	1
260	0	1	1	1	1	1	1	1	1	1
280	0	1	1	1	1	1	1	1	1	1
300	0	0	0	0	1	1	1	1	1	1
320	0	0	0	0	1	1	1	1	0	0
340	0	0	0	0	1	1	1	0	0	0
360	0	0	0	0	0	1	1	0	0	0
380	0	0	0	0	0	0	0	0	0	0

	Fault Codes		Label (Interna			eference)			
49	P11B4, P11B5	I	Hegn_facLam	DiaFdbk ₋	_CUR					
	-		0	3	5	6	7	8	9	1
	factor (-)		0.1	0.1	1.25	3.848	3.889	4	6.484	1
50	P054F	1	njCtl_qDesGe	arMonM	ax_MAP					
	For (00) (5)			400	200	000	4000	5000		
	ECT (°C) / Engine Speed (rpm)	-20.04	0 57.7	400 57.7	600 57.7	800 57.7	1000 57.7	5000 57.7		
		-10.04	50	50	50	50	50	50		
		-0.04	44.2	44.2	44.2	44.2	44.2	44.2		
		19.96	38.7	38.7	38.7	38.7	38.7	38.7		
		39.96	33.8	33.8	33.8	33.8	33.8	33.8		
		69.96	31.7	31.7	31.7	35.1	35.1	35.1		
54	P0606	1	MoFCoOfs_rT	rqPtdOfs	_MAP					
	Engine Speed (rpm) / Torque (%)	1	0	10.156	19.922	30.078	39.844	50	60.156	69.922
		840	99.609375	99.609	99.609	99.609	99.609	99.609	99.609	99.60
		880	11.71875	11.719	11.719	11.719	11.719	11.719	11.719	11.71
		2000	11.71875	11.719	11.719	11.719	11.719	11.719	11.719	11.71
		3000	11.71875	11.719	11.719	11.719	11.719	11.719	11.719	11.71
		4000 5000	11.71875 11.71875	11.719 11.719	11.719 11.719	11.719 11.719	11.719 11.719	11.719 11.719	11.719 11.719	11.719
		6000	11.71875	11.719	11.719	11.719	11.719	11.719	11.719	11.719
		7000	11.71875	11.719	11.719	11.719	11.719	11.719	11.719	11.71
55	P0606		MoFInjQnt_tiZ	FCETMa	x CUR					
		<u>.</u>								
	Rail Pressure (kPa)		20000	30400	70400	90400		120800		
	Energizing Time (us)		500	500	300	256	50	50		
56	P0606	ı	MoFInjQnt_tiZ	FCETMi	n_CUR					
	Rail Pressure (kPa)	1	20000	30400	70400	90400	120000	120800		
	Energizing Time (us)		-500	-500	-300	-256	-50	-50		
57	P0606	1	MoFOvR_nEn	gStrtThre	es_CUR					
	ECT (°C)	T	-40	-30.4	-16	-10.4	9.6	20	29.6	4
	Engine Speed (rpm)		1080	1040	960	960	960	960	920	84
	J	<u>'</u>								
58	P0606		MoFOvR tiLin	ET CUI	>					
J0	1 0000	'	VIOI OVR_ULIII	IL I_CUI	`					
	Engine Speed (rpm)		0	2000	2040	4000				

le no.	. Fault Codes	Lal	bel (Interna	l Manufa	cturer Re	ference)				
59	P2263	PC	R_facMaxU	ndrBstDv	t_CUR					
	Environmental Pressure (kPa)		70	75	80	85	90	95	100	112
	factor (-)	0.	67004395	0.67	0.67	0.67	1	1	1	
60	P0234	PC	R_facPresD	vtCorMin	_CUR					
	Environmental Pressure (kPa)		70	75	80	85	90	95	100	112
	factor (-)	0.	65002441	0.65	0.75	0.75	1	1	1	
61	P0299	PC	CR_pMaxDvt	_MAP						
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		550	1000	1600	1800	2000	2500	3000	45
		0	20	15	15	15	17.5	20	20	
		160	20	15	20	20	20	30	35	
		200	20	17.5	25	25	25	30	35	
		240	25	20	30	30	30	35	40 40	
		280 320	25 25	25 25	25 25	25 25	30 30	35 30	40	
			23				30			
			30	30	30	30	30	30	40	
62	P0234	360 440	30 40 CR pMinDvt	30 40 MAP	30 40	30 40	30 40	30 40	40	
62		360 440	40 CR_pMinDvt_	40 _MAP	40	40	40	40	40	,
62	P0234 Injection Qty (mm^3/rev) / Engine Speed (rpm)	360 440	40	40						55
62		360 440 PC	40 CR_pMinDvt_ 550	40 _MAP	1700	2000	2500	3000	3500	55
62		360 440 PC	40 CR_pMinDvt_ 550 -12.5	40 MAP 1200 -12.5	1700 -12.5	2000 -15	2500 -20	3000 -25	3500 -40	55
62		360 440 PC 4 14 26 40	550 -12.5 -12.5 -12.5 -12.5	_MAP	1700 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15	2500 -20 -20 -20 -20	3000 -25 -25 -25 -25	3500 -40 -40 -40 -40	55
62		360 440 PC 4 14 26 40 60	40 CR_pMinDvt_ 550 -12.5 -12.5 -12.5 -12.5 -12.5	1200 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20	3000 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40	55
62		360 440 PC 4 14 26 40 60 80	40 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	MAP 1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20	3000 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40	55
62		360 440 PC 4 14 26 40 60 80 100	40 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20	3000 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40	55 - - - -
62		440 PC 4 14 26 40 60 80 100 120	40 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20	3000 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40	550
	Injection Qty (mm^3/rev) / Engine Speed (rpm)	360 440 PC 4 14 26 40 60 80 100 120	40 CR_pMinDvt_ 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5 -10.5	_MAP	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -20	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -40 -40	555
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120	40 CR_pMinDvt_ 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -500 -500	40 1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -20 -	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -40 -50	555
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120 PC	40 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	40 1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -20 -	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -40 -50 -50	355
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120 PC	40 550 -12.5	40 1200 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -50 -50 -50	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -50 -50 -50	355
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120 PC	40 CR_pMinDvt_ 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -15.5	1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -20 -	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -	355
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120 PC	40 CR_pMinDvt 550 -12.5 -12.	1200 -12.5 -	1700 -12.5 -12	2000 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -	350
	Injection Qty (mm^3/rev) / Engine Speed (rpm) P2263	360 440 PC 4 14 26 40 60 80 100 120 PC	40 CR_pMinDvt_ 550 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -15.5	1200 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	1700 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5 -12.5	2000 -15 -15 -15 -15 -15 -15 -15 -15	2500 -20 -20 -20 -20 -20 -20 -20 -20 -20 -	3000 -25 -25 -25 -25 -25 -25 -25 -25 -25 -25	3500 -40 -40 -40 -40 -40 -40 -40 -	355

Table no	Equit Codes		Labal (Intarn	al Manufa	oturor D	oforonoo)					
64	Fault Codes		Label (Intern			erence)					
64	P2263		PCR_pUndrB	StDVt_IMAI	Р						
	Injection Qty (mm^3/rev) / Engine Speed (rpm)		500	750	1000	1500	2000	2500			
	Injudicin Qty (IIIII C/101// Engine opeda (Ipini)	0	100	100	100	100	100	100			
		60	100	100	100	100	100	100			
		120	100	100	100	100	100	100			
		180	100	100	100	100	100	100			
		240	100	100	100	100	100	80			
		300	100	100	100	100	80	80			
		360	100	100	100	100	80	80			
		480	100	100	100	100	80	80			
0.5	D0450		DEIL O ITI	D -	OLID						
65	P2459		PFlt_mSotThr	eskgnFre	q_CUR						
	g		0	5	10	20	30	45			
	Soot Mass (g)		0	50	100	200	300	450			
67	P128E		Rail_pCPCFIt	Min CLID							
07	F120E		Kall_pororit	WIII_COR							
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		0	15000							
68	P0087		Rail_pMeUnD	vtMax_Cl	JR						
	[F : 0 I/)		500	000							
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		80000	11000							
69	P0088		Rail_pMeUnD	vtMin CU	IR						
				_							
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		-80000	-10000							
70	DADOE		Dell -Mellet	WA:- OLI	_						
70	P128E		Rail_pMeUnF	ILIVIII_COF	Υ.						
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		0	15000							
	ram recours (m s)			.0000							
71	P0087		Rail_pPCVDv	tMax_CUF	₹						
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		80000	11000							
72	P128E		Rail_pPCVFltMin_CUR								
12	F 120L		raii_pr GVI iliviiii_GGIX								
	Engine Speed (rpm)		580	630							
	Rail Pressure (kPa)		0	15000							
	• • •										

Table no. | Fault Codes | Label (Internal Manufacturer Reference)

73

SCRChk_facNOxUsDynMax_CUR

Nox Concentration (ppm)	0	400
factor (-)	0.51257324	1.025

74 P11CB

 ${\tt SCRChk_idcPOpMaxNOxUsPlaus_GMAP}$

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	600	700	800	900	1000	1100	1200	1400	1600	1800	2000	2001	2500	2600	3000
40	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
80	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
120	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
160	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
200	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
200.4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
220	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
240	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
260	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

75 P11CC

SCRChk_idcPOpMinNOxUsPlaus_GMAP

Injection Qty (mm^3/rev) / Engine Speed (rpm)	500	600	700	800	900	1000	1100	1200	1400	1600	1800	2000	2001	2500	2600	3000
40	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
80	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
120	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
160	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
200	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0
200.4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
220	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
240	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
260	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

76 P20EE

SCRChk_mEstNH3LdMax_CUR

SCR Temperature (°C)	199.96	249.96	274.96	299.96	324.96	349.96	399.96	439.96
Ammonia Load (g)	2.7	2.7	2.7	1.65	1.45	1.35	0.53	0.2

77 P20EE

SCRChk_mEstNH3LdMin_CUR

SCR Temperature (°C)	199.96	249.96	274.96	299.96	324.96	349.96	399.96	439.96
Ammonia Load (g)	1.3	1.15	1.05	0.75	0.6	0.16	0.1	0.06

78 P20EE

SCRChk_mNH3LdDvtMax_CUR

SCR Temperature (°C)	199.96	248.96	274.96	299.96	324.96	349.96	399.96	439.96
Ammonia Load (g)	0.2	0.2	0.2	0.18	0.15	0.15	0.08	0.05

Table no.	Fault Codes	Label (Intern	al Manufa	acturer R	eference)			
79	P20EE	SCRChk_mN	H3LdDvtN	/lin_CUR					
	SCR Temperature (°C)	199.96	249.96	274.96	299.96	324.96	349.96	399.96	439.96
	Ammonia Load (g)	-0.35	-0.35	-0.35	-0.25	-0.15	-0.125	-0.1	-0.05

30 P11CC

 ${\tt SCRChk_rNOxDiffThresBasMinUs_GMAP}$

Injection Qty (mm^3/rev) / Engine Speed (rpm)	800	900	1000	1200	1400	1600	1800	2000	2001	2400
40	-1	-1	-1	-1	-1	-1	-1	-1	-1	-1
60	-1	-1	-1	-0.4924	-0.4916	-0.4932	-0.4795	-0.4905	-0.4905	-1
80	-1	-1	-1	-0.4924	-0.4916	-0.4932	-0.4795	-0.4905	-0.4905	-1
120	-1	-1	-1	-0.4862	-0.4645	-0.4934	-0.4974	-0.4832	-0.4832	-1
160	-1	-1	-1	-0.4923	-0.5088	-0.4922	-0.4971	-0.4718	-0.4718	-1
200	-1	-1	-1	-0.5188	-0.4822	-0.4965	-0.507	-0.4894	-0.4894	-1
200.4	-1	-1	-1	-0.5188	-0.4822	-0.4965	-0.507	-0.4894	-0.4894	-1
220	-1	-1	-1	-1	-1	-1	-1	-1	-1	-1
240	-1	-1	-1	-1	-1	-1	-1	-1	-1	-1
260	-1	-1	-1	-1	-1	-1	-1	-1	-1	-1

81 P11CB, P11CC

SCRChk_stExhTempRlsUsPlaus_CUR

Exhaust Temp (°C)	-0.04	88.96
factor (-)	0	1

82 P11CB, P11CC

SCRChk_stInjCharNOxUsPlaus_CA

Fuel Injector Pattern (-)	24	56	58	26	0	0	0	0

83 P20EE

SCRChk_stPOpSelEta1_MAP

Filtered Exh Mass Flow (g/s) / SCR Upstream Temp (°C)	219.96	239.96	244.96	249.96	254.96	259.96	264.96	269.96	274.96	279.96	284.96	289.96	294.96	299.96	314.96	329.96
61.11	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
69.44	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
80.56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
83.33	0	0	0	0	1	1	1	1	1	1	1	0	0	0	0	0
97.22	0	0	0	0	1	1	1	1	1	1	1	0	0	0	0	0
102.78	0	0	0	1	1	1	1	1	1	1	1	0	0	0	0	0
111.11	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
119.44	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
127.78	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
136.11	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
144.44	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
152.78	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
161.11	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
169.44	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
177.78	0	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0
186.11	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

314.96

able no	. Fault Codes	Label (Intern	al Manu	facturer R	eference	·)									
84	P2BAD	SCRChk_stP				•									
	Filtered Exh Mass Flow (g/s) / SCR Upstream Temp (°C)	219.96			249.96			264.96	269.96	274.96					
	61.11	+			0	0	0	0	0	0	0	0		0	
	69.44	+			0	0	1	1	1	0	0 1	1	0		
	86.11				1	1	1	1	1	1	1	1	0		
	94.44				1	1	1	1	1	1	1	1	0		
	102.78				1	1	1	1	1	1	1	1	0	0	
	111.11	+		1	1	1	1	1	1	1	1	1	0	0	
	119.44		1	1	1	1	1	1	1	1	1	1	0	0	
	127.78	0	1	1	1	1	1	1	1	1	1	1	0	0	0
	136.11			1	1	1	1	1	1	1	1	1	0	0	
	144.44			1	1	1	1	1	1	1	1	1	0		
	152.78				1	1	1	1	1	1	1	1	0		
	161.11				1	1	1	1	1	1	1	1	0		
	169.44				1	1	1	1	1	1	1	1	0		
	177.78	+			0	0		0	0	0					
	186.11	0	0	U U	U	U	U	U	U	U	0	U	0	0	0
85	P20EE	SCRChk_tDe	eltaTemp	SCRMax_	CUR										
	Filtered SCR Temp (°C) Delta SCR Temp (°C)	-50.04 69.96		249.96 65.96	299.96 55.16			499.96 23.96	999.96 23.96						
	Delia SCR Temp (C)	09.90	74.90	05.90	55.16	47.90	29.90	23.90	23.90						
86	P20EE, P2BAD Filtered SCR Temp (°C)	SCRChk_tDif	99.96	149.96	199.96		259.96		399.96						
	Delta SCR Temp (°C)	74.96	74.96	74.96	44.96	44.96	54.96	74.96	74.96						
87	P20EE, P2BAD	SCRChk_tDif	ffSCRCat	:Min_CUR											
	Filtered SCR Temp (°C)	-0.04	99.96	149.96			259.96	349.96	399.96						
	Delta SCR Temp (°C)	-0.04	-0.04	-0.04	-0.04	-40.04	-40.04	-40.04	-40.04						
88	P20EE, P2BAD	SCRChk_tiAd	ddDisbl_N	МАР											
	Nox Peak Duration (s) / Nox Mass Flow (g/s)	0		0.08	0.12	0.16	0.2	0.24	0.3						
	0	+			0.5	1	4	20	40						
	1				0.8	1.5		30	47						
	3				2	3		40	55						
	4				5	10		55	60						
	6				20	25	60	65	70						
	10			+ +	35			70	75						
	20				50	60		75	80						
	60	40	45	50	55	65	75	80	85						
89	P229F	SCRChk_tiPe	eakMaxD	ly_CUR											
	Exhaust Mass Flow (g/sec)	83 33	111.11	125.00	138.89	152.78	166.67	194.44	277.78						
	Delay Time (sec)	5.5	5		4.5	4.5		4.5	4.5						
	Doiay Title (300)	J.3		, J	4.3	4.3	4.0	4.3	4.3						

Table no.	. Fault Codes	Label (Intern	al Manuf	acturer R	Reference)				
90	P10D0	SCRPOD_tM	axDiff_Cl	JR						
	Engine Off Time (sec)	0	299	300	28799	28800	32000	32500	32767	
	Delta Temperature (°C)	3276.7	3276.7	3276.7	3276.7	30	30	30	30	

91 Engine Running

StSys_nStrtCutOut_MAP

BARO Pressure (kPa) / ECT at Start (°C)	-40.04	-30.04	-16.04	-10.04	9.96	19.96	29.96	39.96
65	850	800	735	735	735	735	675	600
70	850	800	735	735	735	735	675	600
75	850	800	735	735	735	735	675	600
80	850	800	735	735	735	735	675	600
85	850	800	735	735	735	735	675	600
90	834	790	720	720	720	720	660	600
95	834	790	720	720	720	720	660	600
100	834	790	720	720	720	720	660	600

92 P2598, P2599

TrbCh_tiDiaEnblDly_CUR

ECT (°C)	-30.04	-20.04	-0.04	9.96	19.96	39.96	59.96	79.96
Delay Time (sec)	327.67	210	120	100	60	50	30	30

93 P01CB, P01CD, P01D7, P01D9, P01D1, P01D3, P01D5, P01CF, P01CC, P01CE, P01D8, P01DA, P01D2, P01D4, P01D6, P01D0

ZFC_stGearRls_CA

Gear (-)	0	1	2	3	4	5	6	7	8
-	0	0	0	1	1	1	1	0	0

94 P01CB, P01CD, P01D7, P01D9, P01D1, P01D3, P01D5, P01CF, P01CC, P01CE, P01D8, P01DA, P01D2, P01D4, P01D6, P01D0

ZFC_tiCldCham_CUR

ECT (°C)	0.06	9.96	16.86	26.86	36.86	46.86	56.86	66.86	76.86	86.86	96.86	106.86
Time (sec)	5	15	20	27	30	30	30	30	30	30	30	30

95 P113A

Engine Off Time (sec)	0	299	300	28799	28800	32000	32500	32767
Delta Temperature (°C)	3276.7	3276.7	3276.7	3276.7	30	30	30	30

96 P054E

InjCtl_qDesGearMonMin_MAP

ECT (°C) / Engine Speed (rpm	0	400	600	800	1000	5000
-20.04	148	148	148	148	148	148
-10.04	117.2	117.2	117.2	117.2	117.2	117.2
-0.04	94	94	94	94	94	94
19.96	72	72	72	72	72	72
39.96	52.4	52.4	52.4	52.4	52.4	52.4
69.96	44	44	44	57.6	57.6	57.6

Table no. Fault C	Codes	pel (Internal Manufacturer Reference)	

97 P16AA

Intake Air Temperature (deg C)	-30	-20	-10
Intake Air heater Temp Sensor Threshold (volts)	0.039	0.130	0.249

end S1-13OBDG09 - Calibration Tables

Calibration Parameter Definition - Calibration Tables

Status and State Calibration Tables

Table no. Status or State

Label (Internal Manufacturer Reference)

1 Status of NOx signal of upstream NOx sensor

DewDet_wThresLSU0_MAP

ECT at Start (°C) / Modeled Exhaust Wall Temp (°C)	-40.14	-20.14	-10.14	-0.14	2.86	6.86	9.86	59.96	99.96	149.96
-40.14	500	500	500	500	500	500	500	375	375	375
-20.14	500	500	500	500	500	500	500	375	375	375
-10.14	500	500	500	500	500	500	500	375	375	375
-0.14	500	500	500	500	500	500	500	375	375	375
2.86	500	500	500	500	500	500	500	375	375	375
6.86	500	500	500	500	500	500	500	375	375	375
9.86	500	500	500	500	500	500	500	375	375	375
19.86	500	500	500	500	500	500	500	375	375	375
39.86	500	500	500	500	500	500	500	375	375	375
59.86	500	500	500	500	500	500	500	375	375	375

2 Status of NOx signal of downstream NOx sensor

DewDet_wThresLSU1_MAP

P										
ECT at Start (°C) / Modeled Exhaust Wall Temp (°C)	-40.14	-30.04	-20.04	-10.04	-0.04	19.96	39.96	59.96	89.96	109.96
-40.14	350	350	250	250	200	200	200	200	200	200
-30.04	350	350	250	200	150	150	150	150	150	150
-20.04	250	250	250	200	150	100	100	100	100	100
-10.04	200	200	200	200	150	100	100	100	100	100
-0.04	200	200	200	175	125	75	75	75	75	75
9.96	200	200	200	125	100	50	50	50	50	50
19.96	200	200	200	125	75	50	50	25	25	25
39.96	200	200	200	125	75	50	25	25	25	25
59.96	200	200	200	125	75	25	25	25	25	25
79.96	200	200	200	125	75	25	25	25	25	0

L	Table no.	Fault Codes	Label (Internal Manufacturer Reference)												
	3	Status thermal regeneration active	PFltLd_dmSo	tSimRgnE	Bas_CUR										Ī
		DPF Soot Mass (g)	0	10	20	30	40	50	55	60	65	70	75	80	
		Mass Flow (g/s)	0.01	0.03	0.05	0.09	0.12	0.13	0.14	0.15	0.16	0.18	0.19	0.20	

Status thermal regeneration active

PFltLd_facO2SimRgn_MAP

Exhaust Mass Flow (g/s) / Lambda (-)	1	1.2	1.35	1.5	2	2.5	3	25
0.00	0	0.53	0.83	1.07	1.62	1.96	2.19	3.21
2.78	0	0.55	0.87	1.12	1.70	2.05	2.29	3.37
5.56	0	0.55	0.87	1.12	1.70	2.05	2.29	3.37
8.33	0	0.55	0.87	1.12	1.70	2.05	2.29	3.37
11.11	0	0.58	0.91	1.18	1.79	2.16	2.41	3.40
13.89	0	0.58	0.91	1.18	1.79	2.16	2.41	3.40
25.00	0	0.58	0.91	1.18	1.79	2.16	2.41	3.40
36.11	0	0.62	0.97	1.26	1.91	2.30	2.57	3.40

Status thermal regeneration active

PFltLd_facTempSimRgn_CUR

Particulate Filter Surface Temp (°C)	49.96	199.96	299.96	499.96	524.96	549.96	574.96	599.96	624.96	649.96	674.96	699.96
Temperature Factor (-)	0	0	0	0.02	0.05	0.10	0.20	0.34	0.60	1.03	1.72	2.81

Rail Control - PCV Closed Loop Control Only

Rail_dvolMeUnCtlUpLim_CUR

Engine Speed (rpm)	0	480	2250	5000	5005	5010	5015	5020	5025	5030	5035	5040	5045	5050	5055	5060
Rail Volume Flow (mm^3/sec)	15000	15000	56000	56000	56000	56000	56000	56000	56000	56000	56000	56000	56000	56000	56000	56000

Rail Control - Metering Unit + PCV Closed Loop Control Rail_qMeUnCtlType_CUR

Engine Speed (rpm)	900	901	1200	1400	1600	1800	2000	4800
Injection Qtv (mm^3/rev)	100	15	15	15	3	3	3	3

Status of the SCR adaptation plausibility check active

SCRAd_mNH3MinTrg_MAP

SCR Modeled Efficieny (-)/ SCR Temp (°C)	249.96	299.96	349.96	399.96	449.96	499.96
	0	0	0	0.04	0.04	0.04
0.2	2 0	0	0	0.04	0.04	0.04
0.4	0	0	0	0.04	0.04	0.04
0.0	0	0	0	0.04	0.04	0.04
3.0	0	0	0	0.04	0.04	0.04
,	0	0	0	0.04	0.04	0.04

Overdosing detected

SCRAd_mNOxOvrMetPh3_CUR

SCR Avg. Temp (°C)	249.96	299.96	349.96	424.96
Nox Mass (g)	-0.7	-0.6	-0.6	-0.6

e no	Fault Codes	Label (Interna	l Manufac	turer Ref	ference)								
10	Status of the SCR adaptation plausibility check active	SCRAd_stSpd											
	Engine Speed (rpm) / Injection Qty. (mm^3/rev)	0	80	100	120	160	200	240	280	320	360	400	48
	600	0	0	0	1	1	1	1	1	1	1	1	
	800		0	0	1	1	1	1	1	1	1	1	
	900	1	1	1	1	1	1	1	1	1	1	1	
	1200		1	1	1	1	1	1	1	1	1	1	
	1400 1600	1	1	1	1	1	1	1	1	1	1	1	
	1800		1	1	1	1	1	1	1	1	1	1	
	2000	1	1	1	1	1	1	1	1	1	1	1	
	2200	1	1	1	1	1	1	1	1	1	1	1	
	2400		1	1	1	1	1	1	1	1	1	1	
	2800	1	1	1	1	1	1	1	1	1	1	1	
	3100	1	1	1	1	1	1	1	1	1	1	1	
	Demonstration and controlled decision	CODEEC athic	ا استوریسا	MAD									
1	Request for pre controlled dosing	SCRFFC_stNC		.IMAP 160	192	216	256	320	408	480	720	800	80
	Engine Speed (rpm) / Injection Qty. (mm^3/rev)	26	136 34	40	48	54	64	80	102	120	180	200	200
	Engine Speed (rpm) / injection Qty. (min Silvey)	7	7	7	7	7	7	7	7	7	7	7	20
	1200		7	7	7	7	7	7	7	7	7	7	
	1400		7	7	7	7	7	7	7	7	7	7	
	1475	7	7	7	7	7	7	7	7	7	7	7	
	1700	7	7	7	7	7	7	7	7	7	7	7	
	2000		7	7	7	7	7	7	7	7	7	7	
	2200	7	7	7	7	7	7	7	7	7	7	7	
	2400	7	7	7	7	7	7	7	7	7	7	7	
	2600		7	7	7	7	7	7	7	7	7	7	
	2800		7	7	7	7	7	7	7	7	7	7	
	3000		7	7	7	7	7	7	7	7	7	7	
	3200	/	7	1	7	/	7	/	/	/	7	/	
2	Request for pre controlled dosing	SCRFFC_stN0	QntCurrMid	MAP									
	Engine Speed (rpm) / Injection Qty. (mm^3/rev)	26	34	40	48	54	64	80	102	120	180	200	20
	800	2	2	2	2	3	10	10	10	10	10	10	
		10	10	10	10	10	10	10	10	10	10	10	
	1200						10	10	10	10	10	10	
	1200 1400	10	10	10	10	10					വ	2	
	1200 1400 1475	10 10	10 10	10	8	7	4	4	2	2	2		
	1200 1400 1475 1700	10 10 10	10 10 10	10 10	8	7	4	2	2	2	2	2	
	1200 1400 1475 1700 2000	10 10 10 10	10 10 10 10	10 10 10	8 8 8	7 7 7	4 4 4	2	2	2	2	2	
	1200 1400 1475 1700 2000 2200	10 10 10 10 10	10 10 10 10 10	10 10 10 8	8 8 8 6	7 7 7 4	4 4 4 2	2 2 2	2 2 2	2 2 2	2 2 2	2 2 2	
	1200 1400 1475 1700 2000 2200 2400	10 10 10 10 10 10	10 10 10 10 10 10	10 10 10 8 8	8 8 8 6 6	7 7 7 4 4	4 4 4 2 2	2 2 2 2	2 2 2 2	2 2 2 2	2 2 2 2	2 2 2 2	
	1200 1400 1475 1700 2000 2200 2400 2600	10 10 10 10 10 10 10	10 10 10 10 10 10 10	10 10 10 8 8 8	8 8 8 6 6 4	7 7 7 4 4 3	4 4 4 2 2 2	2 2 2 2 2	2 2 2 2 2	2 2 2 2 2	2 2 2 2 2	2 2 2 2 2	
	1200 1400 1475 1700 2000 2200 2400	10 10 10 10 10 10 10	10 10 10 10 10 10	10 10 10 8 8	8 8 8 6 6	7 7 7 4 4	4 4 4 2 2	2 2 2 2	2 2 2 2	2 2 2 2	2 2 2 2	2 2 2 2	

Table no.	Fault Codes	Label (Intern	al Manuf	acturer F	Reference	e)							
13	Request for pre controlled dosing	SCRFFC_stN	QntCurrS	SeaLvl_M	AP								
	Engine Speed (rpm) / Injection Qty. (mm^3/rev)	26	34	40	48	54	64	80	102	120	180	200	200.4
	800	0	0	0	0	3	10	10	10	10	10	10	10
	1200	10	10	10	10	10	10	10	10	10	10	10	10
	1400	10	10	10	10	10	10	10	10	10	10	10	10
	1475	10	10	10	8	7	4	4	0	0	0	0	3
	1700	10	10	10	8	7	4	0	0	0	0	0	3
	2000	10	10	10	8	7	4	0	0	0	0	0	3
	2200	10	10	8	6	4	2	0	0	0	0	0	3
	2400	10	10	8	6	4	2	0	0	0	0	0	3
	2600	10	8	6	4	3	0	0	0	0	0	0	3
	2800	10	8	5	4	3	0	0	0	0	0	0	3
	3000	10	8	5	4	3	0	0	0	0	0	0	3
	3200	10	8	7	5	4	4	4	4	4	4	4	4

14 Engine Running

StSys_nStrtCutOut_MAP

BARO Pressure (kPa) / ECT at Start (°C)	-40.04	-20.04	-10.04	-0.04	9.96	19.96	34.96	59.96
65	850	770	755	755	755	680	600	600
70	850	770	755	755	755	680	600	600
75	850	770	755	755	755	680	600	600
80	850	770	755	755	755	680	600	600
85	850	770	755	755	755	680	600	600
90	850	770	755	755	755	680	600	600
95	834	740	720	720	720	650	600	600
100	834	740	720	720	720	650	600	600

15 State of Reductant injection valve Component Protection UDC_tUDosVlvCoPrActv_MAP

Vehicle Speed (mph) / SCR Upstream Temp (°C)	99.96	199.96	299.96	399.96	499.96	599.96
0	104.96	104.96	104.96	104.96	95.46	89.96
20	109.96	109.96	109.96	107.96	100.26	94.96
50	109.96	109.96	109.96	108.96	107.96	103.96
60	109.96	109.96	109.96	109.96	109.96	105.96
100	109.96	109.96	109.96	109.96	109.96	107.96
150	109.96	109.96	109.96	109.96	109.96	109.96

16 Release of tank heater circuit

UHC_tiC1Dfrst_CUR

Reductant Tank Temp. (°C)	-30.04	-18.04	-15.04	-11.04	-8.04	-0.04	4.96	5.06
Reductant Heater Time (sec)	3277	3277	3277	3277	300	300	300	0

17 Release of tank heater circuit

UHC_tiC1On_CUR

Reductant Tank Temp. (°C)	-30.04	-18.04	-15.04	-11.04	-7.04	-0.04	4.96	5.06
Reductant Heater Time (sec)	3277	3277	3277	3277	600	300	300	0

Table no	p. Fault Codes	Label (Internal Manufacturer Reference)
18	Release of tank heater circuit	UHC_tiDfrstC2_CUR
	Reductant Tank Temp. (°C)	-35.04 -25.04 -18.04 -10.04 -8.04 -5.04 -0.14 -0.04
	Reductant Heater Time (sec)	3276.7 3276.7 3000 600 300 300 200 0
19	Release of tank heater circuit	UHC_tiDfrstC3_CUR
	Reductant Tank Temp. (°C)	-35.04 -25.04 -18.04 -10.04 -8.04 -5.04 -0.14 -0.04
	Reductant Heater Time (sec)	3276.7 3276.7 3000 600 300 300 200 0
20	Release of tank heater circuit	UHC tiOnC2 CUR
20	Release of talk fleater circuit	OHC_HOHCZ_CON
	Reductant Tank Temp. (°C)	-30.04 -18.04 -15.04 -11.04 -7.04 -0.04 4.96 5.06
	Reductant Heater Time (sec)	3276.7 3276.7 3276.7 3276.7 600 300 90 0
21	Release of tank heater circuit	UHC_tiOnC3_CUR
	Troised of talk floator off out	0110_1101101_0011
	Reductant Tank Temp. (°C)	-30.04 -18.04 -15.04 -11.04 -7.04 -0.04 4.96 5.06
	Reductant Heater Time (sec)	3276.7 3276.7 3276.7 3276.7 600 300 90 0

end Calibration Parameter Definition - Calibration Tables

This document is intended to meet the requirements documented in section 1968.2 of Title 13, California Code of Regulations entitled Modifications to Malfunction and Diagnosis System Requirements for 2004 and Subsequent Model-Year Passenger Cars, Light-Duty Trucks, and Medium-Duty Vehicles and Engines (OBD II), paragraphs (i)(2.2) for a table detailing **supplemental** calibration parameter data for OBD II Group 13OBDG09.

Active DTC			Inh	nibited DT	Cs								
P0016 - Crankshaft to Camshaft Correlation	P0191 - Fuel Rail Pressure Sensor Performance	P0315 - Crankshaft Position System Variation Not Learned	B0404		ı								
P0045 - Turbocharger Boost Control Circuit	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive									
P0047 - Turbocharger Boost Control Circuit Low Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive									
P0048 - Turbocharger Boost Control Circuit High Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive									
P006E - Turbocharger Boost High Control Circuit Low Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive		ı							
P006F - Turbocharger Boost High Control Circuit High Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2510 - ECM Power Relay Circuit Performance								
P007C - CAC Temperature Sensor Circuit Low Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance					
P007D - CAC Temperature Sensor Circuit High Voltage	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance					
P008F - Engine Coolant Temperature (ECT)-Fuel Temperature Not Plausible	P0101 - Mass Air Flow Sensor Performance												
P0097 - Intake Air Temperature Sensor 2 Circuit Low	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance									
P0098 - Intake Air Temperature Sensor 2 Circuit High	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance									
P00CA - Fuel Pressure Regulator 1 High Control Circuit High Voltage	P2510 - ECM Power Relay Circuit Performance		ı	ı			ı		T	T			
P0101 - Mass Air Flow Sensor Performance	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P2002 - Diesel Particulate Filter (DPF) Low Efficiency	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P2453 - Diesel Particulate Filter Differential Pressure Sensor Performance	P2459 - Diesel Particulate Filter Regeneration Frequency	P246F - Exhaust Temperature Sensor 4 Performance	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High
P0102 - Mass Air Flow Sensor Circuit Low	P0101 - Mass Air Flow Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance				

Active DTC			Inh	ibited DT	Cs											
P0103 - Mass Air Flow Sensor Circuit High	P0101 - Mass Air Flow Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance							
P0106 - Manifold Absolute Pressure Sensor Performance	P0101 - Mass Air Flow Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive					•						
P0107 - Manifold Absolute Pressure (MAP) Sensor Circuit Low Voltage	P0101 - Mass Air Flow Sensor Performance	P0106 - Manifold Absolute Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P2263 - Turbo Boost System Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance					
P0108 - Manifold Absolute Pressure (MAP) Sensor Circuit High Voltage	P0101 - Mass Air Flow Sensor Performance	P0106 - Manifold Absolute Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P2263 - Turbo Boost System Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance					
P0112 - Intake Air Temperature Sensor 1 Circuit Low	P0101 - Mass Air Flow Sensor Performance	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P040F - Exhaust Gas Recirculation (EGR) Temperature Sensor 1-2 Correlation	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance							
P0113 - Intake Air Temperature Sensor 1 Circuit High	P0101 - Mass Air Flow Sensor Performance	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P040F - Exhaust Gas Recirculation (EGR) Temperature Sensor 1-2 Correlation	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance							
P0117 - Engine Coolant Temperature Sensor Circuit Low	P0106 - Manifold Absolute Pressure Sensor Performance	P0191 - Fuel Rail Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0263 - Cly 1 Balance System	P0266 - Cly 2 Balance System	P0269 - Cly 3 Balance System	P0272 - Cly 4 Balance System	P0275 - Cly 5 Balance System	P0278 - Cly 6 Balance System	P0281 - Cly 7 Balance System	P0284 - Cly 8 Balance System	P0299 - Turbocharger Engine Underboost	P0300 - Engine Misfire Detected	P0301 - Cylinder 1 Misfire Detected	P0302 - Cylinder 2 Misfire Detected	
P0117 - Engine Coolant Temperature Sensor Circuit Low	P0303 - Cylinder 3 Misfire Detected	P0304 - Cylinder 4 Misfire Detected	P0305 - Cylinder 5 Misfire Detected	P0306 - Cylinder 6 Misfire Detected	P0307 - Cylinder 7 Misfire Detected	P0308 - Cylinder 8 Misfire Detected	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P0506 - Idle Speed Low	P0507 - Idle Speed High	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance		
P0118 - Engine Coolant Femperature Sensor Circuit High	P0106 - Manifold Absolute Pressure Sensor Performance	P0191 - Fuel Rail Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0263 - Cly 1 Balance System	P0266 - Cly 2 Balance System	P0269 - Cly 3 Balance System	P0272 - Cly 4 Balance System	P0275 - Cly 5 Balance System	P0278 - Cly 6 Balance System	P0281 - Cly 7 Balance System	P0284 - Cly 8 Balance System	P0299 - Turbocharger Engine Underboost	P0300 - Engine Misfire Detected		•	
P0118 - Engine Coolant emperature Sensor Circuit High	P0301 - Cylinder 1 Misfire Detected	P0302 - Cylinder 2 Misfire Detected	P0303 - Cylinder 3 Misfire Detected	P0304 - Cylinder 4 Misfire Detected	P0305 - Cylinder 5 Misfire Detected	P0306 - Cylinder 6 Misfire Detected	P0307 - Cylinder 7 Misfire Detected	P0308 - Cylinder 8 Misfire Detected	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P0506 - Idle Speed Low	P0507 - Idle Speed High	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance
P0128 - Engine Coolant Temperature Below Thermostat Regulating Temperature	P0101 - Mass Air Flow Sensor Performance				I		1									
P014C - HO2S Slow Response Rich to Lean Sensor 1	P0171 - Fuel Trim System Lean	P0172 - Fuel Trim System Rich	P026C - Injection Quantity Too Low	P026D - Injection Quantity Too High	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1										
P0171 - Fuel Trim System Lean	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor					-									
P0172 - Fuel Trim System Rich	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1														

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	P01CB -	P01CC -	P01CD -	P01CE -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 -	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -				
P0182 - Fuel Temperature Sensor	Cylinder 1 Injection	Cylinder 1 Injection	Cylinder 2 Injection	Cylinder 2 Injection	Cylinder 3 Injection	Cylinder 3 Injection	Cylinder 4 Injection	Cylinder 4 Injection	Cylinder 5 Injection	Cylinder 5 Injection	Cylinder 6 Injection	Cylinder 6 Injection	Cylinder 7 Injection	Cylinder 7 Injection	Cylinder 8 Injection	Cylinder 8 Injection				
1 Circuit Low	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing	Timing				
	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced	Retarded	Advanced				
	P01CB - Cylinder 1	P01CC - Cylinder 1	P01CD - Cylinder 2	P01CE - Cvlinder 2	P01CF - Cylinder 3	P01D0 - Cylinder 3	P01D1 - Cylinder 4	P01D2 - Cylinder 4	P01D3 - Cylinder 5	P01D4 - Cylinder 5	P01D5 - Cvlinder 6	P01D6 - Cvlinder 6	P01D7 - Cvlinder 7	P01D8 - Cylinder 7	P01D9 - Cylinder 8	P01DA - Cylinder 8				
P0183 - Fuel Temperature Sensor 1 Circuit High	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection	Injection				
1 Gireal Flight	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced	Timing Retarded	Timing Advanced				
	P0191 - Fuel	Auvanceu	rvetarded	Auvanceu	Retarded	Auvanceu	rtetarueu	Advanced	Retarded	Auvanceu	Retarted	Auvanceu	rvetarueu	Advanced	rvetarueu	Advanced				
P0192 - Fuel Rail Pressure	Rail Pressure																			
Sensor Circuit Low	Sensor Performance																			
	P0191 - Fuel	1																		
P0193 - Fuel Rail Pressure Sensor Circuit High	Rail Pressure Sensor																			
Sensor Circuit riigii	Performance																			
P01F0 - Coolant Temperature	P2181 -	1																		
Dropped Below Diagnostic	Engine Thermostat																			
Monitoring Temperature	stuck open						1						T	1		T	1			
	P0171 - Fuel	P0172 - Fuel	P01CB - Cylinder 1	P01CC - Cylinder 1	P01CD - Cylinder 2	P01CE - Cylinder 2	P01CF - Cylinder 3	P01D0 - Cylinder 3	P01D1 - Cylinder 4	P01D2 - Cylinder 4	P01D3 - Cylinder 5	P01D4 - Cylinder 5	P01D5 - Cylinder 6	P01D6 - Cylinder 6	P01D7 - Cylinder 7	P01D8 - Cylinder 7	P01D9 - Cylinder 8	P01DA - Cylinder 8	P026C -	P026D -
P0201 - Injector 1 Control Circuit	Trim System	Trim System	Injection	Injection Quantity Too																
	Lean	Rich	Timing Retarded	Timing Advanced	Quantity Too Low	High														
	_		P01CB -	P01CC -	P01CD -	P01CE -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 -	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -		
	P0171 - Fuel	P0172 - Fuel	Cylinder 1	Cylinder 1	Cylinder 2	Cylinder 2	Cylinder 3	Cylinder 3	Cylinder 4	Cylinder 4	Cylinder 5	Cylinder 5	Cylinder 6	Cylinder 6	Cylinder 7	Cylinder 7	Cylinder 8	Cylinder 8	P026C - Injection	P026D - Injection
P0202 - Injector 2 Control Circuit	Trim System Lean	Trim System Rich	Injection Timing	Quantity Too	Quantity Too															
	Lean	Nicii	Retarded	Advanced	Low	High														
			P01CB -	P01CC -	P01CD -	P01CE -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 -	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -	P026C -	P026D -
P0203 - Injector 3 Control Circuit	P0171 - Fuel Trim System	P0172 - Fuel Trim System	Cylinder 1 Injection	Cylinder 1 Injection	Cylinder 2 Injection	Cylinder 2 Injection	Cylinder 3 Injection	Cylinder 3 Injection	Cylinder 4 Injection	Cylinder 4 Injection	Cylinder 5 Injection	Cylinder 5 Injection	Cylinder 6 Injection	Cylinder 6 Injection	Cylinder 7 Injection	Cylinder 7 Injection	Cylinder 8 Injection	Cylinder 8 Injection	Injection	Injection
1 0200 Injudici o control circuit	Lean	Rich	Timing	Quantity Too Low	Quantity Too High															
			Retarded	Advanced	LOW	riigii														
	P0171 - Fuel	P0172 - Fuel	P01CB - Cvlinder 1	P01CC - Cvlinder 1	P01CD - Cylinder 2	P01CE - Cylinder 2	P01CF - Cvlinder 3	P01D0 - Cvlinder 3	P01D1 - Cylinder 4	P01D2 - Cylinder 4	P01D3 - Cvlinder 5	P01D4 - Cvlinder 5	P01D5 - Cylinder 6	P01D6 - Cvlinder 6	P01D7 - Cylinder 7	P01D8 - Cylinder 7	P01D9 - Cylinder 8	P01DA - Cylinder 8	P026C -	P026D -
P0204 - Injector 4 Control Circuit	Trim System	Trim System	Injection	Injection Quantity Too	Injection Quantity Too															
	Lean	Rich	Timing Retarded	Timing Advanced	Low	High														
			P01CB -	P01CC -	P01CD -	P01CE -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 -	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -	P026C -	P026D -
P0205 - Injector 5 Control Circuit	P0171 - Fuel Trim System	P0172 - Fuel Trim System	Cylinder 1 Injection	Cylinder 1 Injection	Cylinder 2 Injection	Cylinder 2 Injection	Cylinder 3 Injection	Cylinder 3 Injection	Cylinder 4 Injection	Cylinder 4 Injection	Cylinder 5 Injection	Cylinder 5 Injection	Cylinder 6 Injection	Cylinder 6 Injection	Cylinder 7 Injection	Cylinder 7 Injection	Cylinder 8 Injection	Cylinder 8 Injection	Injection	Injection
P0205 - Injector 5 Control Circuit	Lean	Rich	Timing	Quantity Too Low	Quantity Too															
			Retarded	Advanced	LOW	High														
	P0171 - Fuel	P0172 - Fuel	P01CB - Cylinder 1	P01CC - Cylinder 1	P01CD - Cylinder 2	P01CE - Cylinder 2	P01CF - Cylinder 3	P01D0 - Cylinder 3	P01D1 - Cylinder 4	P01D2 - Cylinder 4	P01D3 - Cylinder 5	P01D4 - Cylinder 5	P01D5 - Cylinder 6	P01D6 - Cylinder 6	P01D7 - Cylinder 7	P01D8 - Cylinder 7	P01D9 - Cylinder 8	P01DA - Cylinder 8	P026C -	P026D -
P0206 - Injector 6 Control Circuit	Trim System	Trim System	Injection	Injection Quantity Too	Injection Quantity Too															
	Lean	Rich	Timing Retarded	Timing Advanced	Timing Retarded	Timing	Timing Retarded	Timing	Timing Retarded	Timing Advanced	Timing	Timing	Timing Retarded	Timing	Timing Retarded	Timing	Timing Retarded	Timing Advanced	Low	High
			P01CB -	P01CC -	P01CD -	P01CF -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 -	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -		
	P0171 - Fuel	P0172 - Fuel	Cylinder 1	Cylinder 1	Cylinder 2	Cylinder 2	Cylinder 3	Cylinder 3	Cylinder 4	Cylinder 4	Cylinder 5	Cylinder 5	Cylinder 6	Cylinder 6	Cylinder 7	Cylinder 7	Cylinder 8	Cylinder 8	P026C - Injection	P026D - Injection
P0207 - Injector 7 Control Circuit	Trim System Lean	Trim System Rich	Injection Timing	Injection Timina	Injection Timing	Injection Timing	Injection Timing	Quantity Too	Quantity Too											
	Eod.:	1 11011	Retarded	Advanced	Low	High														
	P0171 - Fuel	B0470 E I	P01CB -	P01CC -	P01CD -	P01CE -	P01CF -	P01D0 -	P01D1 -	P01D2 -	P01D3 - Cylinder 5	P01D4 -	P01D5 -	P01D6 -	P01D7 -	P01D8 -	P01D9 -	P01DA -	P026C -	P026D -
P0208 - Injector 8 Control Circuit	Trim System	P0172 - Fuel Trim System	Cylinder 1 Injection	Cylinder 1 Injection	Cylinder 2 Injection	Cylinder 2 Injection	Cylinder 3 Injection	Cylinder 3 Injection	Cylinder 4 Injection	Cylinder 4 Injection	Injection	Cylinder 5 Injection	Cylinder 6 Injection	Cylinder 6 Injection	Cylinder 7 Injection	Cylinder 7 Injection	Cylinder 8 Injection	Cylinder 8 Injection	Injection	Injection
	Lean	Rich	Timing	Quantity Too Low	Quantity Too High															
	P11CB - NOx	P11CC - NOx	Retarded	Advanced	Refarded	Advanced														
	Sensor	Sensor																		
P0234 - Turbocharger Engine Overboost	Performance - Signal High	Performance - Signal Low																		
Overboost	Bank 1 Sensor																			
	1	1	1																	
	P11CB - NOx Sensor	P11CC - NOx Sensor																		
P0299 - Turbocharger Engine	Performance -	Performance -																		
Underboost	Signal High	Signal Low Bank 1 Sensor																		
	Bank i Sensor	Bank i Sensor																		

P11CB - NOX Sensor Performance -Signal High Bank 1 Sensor Bank 1 Sensor

P026D -

Injection Quantity Too High

P026C - Injection Quantity Too Low

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P026D - Injection Quantity Too High	P026C - Injection Quantity Too Low	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1						
P02E7 - Diesel Intake Air Flow Position Sensor Circuit Range Performance	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive							
P02E8 - Diesel Intake Air Flow Position Sensor Circuit Low	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P122D - Diesel Intake Air Flow Position Sensor Exceeded Learning Limit	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance
P02E9 - Diesel Intake Air Flow Position Sensor Circuit High	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P122D - Diesel Intake Air Flow Position Sensor Exceeded Learning Limit	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance
P02EB - Intake Air Flow Valve Control Motor Current Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P122D - Diesel Intake Air Flow Position Sensor Exceeded Learning Limit				
P0335 - Crankshaft Position Sensor Circuit	P0102 - Mass Air Flow Sensor Circuit Low	P0103 - Mass Air Flow Sensor Circuit High	P0191 - Fuel Rail Pressure Sensor Performance	P0315 - Crankshaft Position System Variation Not Learned	P0506 - Idle Speed Low	P0507 - Idle Speed High			
P0336 - Crankshaft Position Sensor Performance	P0102 - Mass Air Flow Sensor Circuit Low	P0103 - Mass Air Flow Sensor Circuit High	P0191 - Fuel Rail Pressure Sensor Performance	P0315 - Crankshaft Position System Variation Not Learned	P0506 - Idle Speed Low	P0507 - Idle Speed High			
P0340 - Camshaft Position Sensor Circuit	P0191 - Fuel Rail Pressure Sensor Performance	P0315 - Crankshaft Position System Variation Not Learned							
P0341 - Camshaft Position Sensor Performance	P0191 - Fuel Rail Pressure Sensor Performance	P0315 - Crankshaft Position System Variation Not Learned			_				
P0400 - Exhaust Gas Recirculation (EGR) Flow Incorrect	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High					
P0401 - Exhaust Gas Recirculation Flow Insufficient	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P2459 - Diesel Particulate Filter Regeneration Frequency	P246F - Exhaust Temperature Sensor 4 Performance	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High
P0402 - Exhaust Gas Recirculation Flow Excessive	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P2459 - Diesel Particulate Filter Regeneration Frequency	P246F - Exhaust Temperature Sensor 4 Performance	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High
P0405 - Exhaust Gas Recirculation Position Sensor Circuit Low	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P049D - EGR Control Position Not Learned	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance		

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7.000 510	P0401 -	P0402 -	1	P2080 -	P2084 -	P242B -	P246F -
P0406 - Exhaust Gas	Exhaust Gas	Exhaust Gas	P049D - EGR Control	Exhaust	Exhaust	Exhaust	Exhaust
Recirculation Position Sensor	Recirculation	Recirculation	Position Not	Temperature	Temperature	Temperature	Temperature
Circuit High	Flow Insufficient	Flow Excessive	Learned	Sensor 1 Performance	Sensor 2 Performance	Sensor 3 Performance	Sensor 4 Performance
	P040F -	LACESSIVE		Fellolliance	Ferioritatice	renomance	renormance
	Exhaust Gas						
P040C - Exhaust Gas	Recirculation						
Recirculation (EGR) Temperature Sensor 2 Circuit Low Voltage	(EGR) Temperature						
Ochsor 2 Orean Low Voltage	Sensor 1-2						
	Correlation						
	P040F -						
P040D - Exhaust Gas	Exhaust Gas Recirculation						
Recirculation (EGR) Temperature	(EGR)						
Sensor 2 Circuit High Voltage	Temperature Sensor 1-2						
	Correlation						
	P040F -						
	Exhaust Gas						
P041C - Exhaust Gas Recirculation (EGR) Temperature	Recirculation (EGR)						
Sensor 1 Circuit Low Voltage	Temperature						
	Sensor 1-2						
	Correlation	-					
	P040F - Exhaust Gas						
P041D - Exhaust Gas	Recirculation						
Recirculation (EGR) Temperature	(EGR) Temperature						
Sensor 1 Circuit High Voltage	Sensor 1-2						
	Correlation		_				
	P249D -	P249E -					
	Closed Loop Reductant	Closed Loop Reductant					
P0420 - NMHC Catalyst Efficiency Below Threshold Bank 1	Injection	Injection					
Below Threshold Bank 1	Control At	Control At					
	Limit - Flow Too Low	Limit - Flow Too High					
				P2080 -	P2084 -	P242B -	P246F -
P046C - Exhaust Gas	P0101 - Mass Air Flow	P0234 - Turbocharger	P0299 - Turbocharger	Exhaust	Exhaust	Exhaust	Exhaust
Recirculation(EGR) Position Sensor Performance	Sensor	Engine	Engine	Temperature Sensor 1	Temperature Sensor 2	Temperature Sensor 3	Temperature Sensor 4
Ochsor i chomiane	Performance	Overboost	Underboost	Performance	Performance	Performance	Performance
	P2080 -	P2084 -	P20E2 -				
P0545 - Exhaust Gas	Exhaust	Exhaust	Exhaust Gas Temperature	P2428 - Exhaust Gas			
Temperature (EGT) Sensor 1	Temperature Sensor 1	Temperature Sensor 2	(EGT) Sensors	High			
Circuit Low Voltage	Performance	Performance	1-2 not plausible	Temperature			
			P20E2 -				
P0546 - Exhaust Gas	P2080 - Exhaust	P2084 - Exhaust	Exhaust Gas	P2428 -			
Temperature (EGT) Sensor 1	Temperature	Temperature	Temperature	Exhaust Gas			
Circuit High Voltage	Sensor 1	Sensor 2	(EGT) Sensors 1-2 not	High Temperature			
	Performance	Performance	plausible	romporataro			
P0575 0 1 5 1 1	P0567 - Cruise	P0568 - Cruise					
P0575 - Cruise Control Input Circuit	Control Resume	Control Set					
S. ouit	Switch Circuit	Switch Circuit]				
	P057D - Brake		_				
P057C - Brake Pedal Position	Pedal Position						
Sensor Circuit High Voltage	Sensor Circuit Low Voltage						
	Low voltage	4					
	P057C - Brake						
P057D - Brake Pedal Position	Pedal Position						
Sensor Circuit Low Voltage	Sensor Circuit High Voltage	1					
		D04.40	D0450	D2455	1		
	P2146 - Injector	P2149 - Injector	P2152 - Injector	P2155 - Injector			
P0606 - Control Module Internal	Positive	Positive	Positive	Positive			
Performance	Voltage Control Circuit	Voltage Control Circuit	Voltage Control Circuit	Voltage Control Circuit			
	Group 1	Group 2	Group 3	Group 4			
	P11DB - NOx	P2209 - N0x			•		
B0040 01 B1 0 1	Sensor	Heater					
P064C - Glow Plug Control Module Performance	Current Performance	Performance					
	Bank 1 Senso	Bank 1 Sensor					
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0651 - 5 Volt Reference 2 Circuit	P2127 - Accelerator Pedal Position Sensor 2 Circuit Low	P2128 - Accelerator Pedal Position (APP) Sensor 2 Circuit High Voltage	
'0697 - 5 Volt Reference 3 Circuit	Sensor 1 Circuit Low	P2123 - Accelerator Pedal Position Sensor 1 Circuit High	
P0851 - Park/Neutral Position PNP) Switch Circuit Low Voltage	P0852 - Park/Neutral Position (PNP) Switch Circuit High Voltage		
P0852 - Park/Neutral Position PNP) Switch Circuit High Voltage	P0851 - Park/Neutral Position (PNP) Switch Circuit Low Voltage		
P1048 - Reductant Injector High Control Circuit Low Voltage	P202E - Reductant Injector Performance	20540 504	1
P1049 - Reductant Injector High Control Circuit High Voltage	P202E - Reductant Injector Performance P249D -	P2510 - ECM Power Relay Circuit Performance P249E -	
P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	Closed Loop Reductant Injection Control At Limit - Flow Too Low	Closed Loop Reductant Injection Control At Limit - Flow Too High	
P11DC - NOx Sensor Current Performance Bank 1 Sensor 2	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High	
P1224 - Injector 1 Control Circuit Shorted	P0201 - Injector 1 Control Circuit	P0606 - Control Module Internal Performance	P2146 - Injector Positive Voltage Control Circuit Group 1
P1227 - Injector 2 Control Circuit Shorted	P0202 - Injector 2 Control Circuit	P0606 - Control Module Internal Performance	P2152 - Injector Positive Voltage Control Circuit Group 3
P122A - Injector 3 Control Circuit Shorted	P0203 - Injector 3 Control Circuit	P0606 - Control Module Internal Performance	P2155 - Injector Positive Voltage Control Circuit Group 4
P122D - Diesel Intake Air Flow Position Sensor Exceeded Learning Limit	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient
P1233 - Injector 4 Control Circuit Shorted	P0204 - Injector 4 Control Circuit	P0606 - Control Module Internal Performance	P2146 - Injector Positive Voltage Control Circuit Group 1
P1236 - Injector 5 Control Circuit Shorted	P0205 - Injector 5 Control Circuit	P0606 - Control Module Internal	P2152 - Injector Positive Voltage Control Circuit

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P1239 - Injector 6 Control Circuit Shorted		P0206 - Injector 6 Control Circuit	P0606 - Control Module Internal Performance	P2149 - Injector Positive Voltage Control Circuit Group 2			
P1242 - Injector 7 Control Circuit Shorted		P0207 - Injector 7 Control Circuit	P0606 - Control Module Internal Performance	P2149 - Injector Positive Voltage Control Circuit Group 2			
P1247 - Injector 8 Control Circuit Shorted		P0208 - Injector 8 Control Circuit	P0606 - Control Module Internal Performance	P2155 - Injector Positive Voltage Control Circuit Group 4			
P125B - Fuel Pressure Regulator 2 High Control Circuit High Voltage		P2510 - ECM Power Relay Circuit Performance				•	
P140B - Exhaust Gas Recirculation Slow Response- Increasing Flow		P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High		
P140C - Exhaust Gas Recirculation Slow Response- Decreasing Flow		P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High		
P140F - Exhaust Gas Recirculation (EGR) Motor Current Performance		P0101 - Mass Air Flow Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P049D - EGR Control Position Not Learned
P1414 - Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Current Performance		P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P140A - EGR Cooler BY Pass Position Sensor Exceded Learning Limit			
P163C - Glow Plug Control Module Primary Circuit		P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P2209 - N0x Heater Performance Bank 1 Sensor 1				
P2002 - Diesel Particulate Filter (DPF) Low Efficiency		P2459 - Diesel Particulate Filter Regeneration Frequency					
P2032 - Exhaust Gas Temperature (EGT) Sensor 2 Circuit Low Voltage		P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P2428 - Exhaust Gas High Temperature	P242B - Exhaust Temperature Sensor 3 Performance	
P2033 - Exhaust Gas Temperature (EGT) Sensor 2 Circuit High Voltage		P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P2428 - Exhaust Gas High Temperature	P242B - Exhaust Temperature Sensor 3 Performance	
P2047 - Reductant Injector Control Circuit		P202E - Reductant Injector Performance					
P2048 - Reductant Injector Control Circuit Low Voltage		P202E - Reductant Injector Performance					
P2049 - Reductant Injector Control Circuit High Voltage		P202E - Reductant Injector Performance	P2510 - ECM Power Relay Circuit Performance				

Active DTC			Int	nibited DT	Cs
P204B - Reductant Pump Pressure Sensor Performance	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High		
P204C - Reductant Pump Pressure Sensor Circuit Low	P204B - Reductant Pump Pressure Sensor Performance	P20A1 - Reductant Purge Valve Performance		•	
P204D - Reductant Pump Pressure Sensor Circuit High	P204B - Reductant Pump Pressure Sensor Performance	P20A1 - Reductant Purge Valve Performance			
P205C - Reductant Tank Temperature Sensor Circuit Low	P20BA - Reductant Heater 1 Performance				
P205D - Reductant Tank Temperature Sensor Circuit High	P205B - Reductant Tank Temperature Sensor Performance	P20BA - Reductant Heater 1 Performance			
P208A - Reductant Pump Control Circuit	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20A1 - Reductant Purge Valve Performance	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High	
P208D - Reductant Pump Control Circuit High Voltage	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20A1 - Reductant Purge Valve Performance	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High	P2510 - ECM Power Relay Circuit Performance
P20A0 - Reductant Purge Valve Control Circuit	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20A1 - Reductant Purge Valve Performance	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High	
P20A2 - Reductant Purge Valve Control Circuit Low Voltage	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20A1 - Reductant Purge Valve Performance	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High	
P20A3 - Reductant Purge Valve Control Circuit High Voltage	P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	P20A1 - Reductant Purge Valve Performance	P20E8 - Reductant Pressure Too Low	P20E9 - Reductant Pressure Too High	P2510 - ECM Power Relay Circuit Performance
P20CB - Exhaust Aftertreatment Fuel Injector Control Circuit	P2510 - ECM Power Relay Circuit Performance				
P20CE - Exhaust Aftertreatment Fuel Injector Control Circuit High Voltage	P2510 - ECM Power Relay Circuit Performance				
P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	P0101 - Mass Air Flow Sensor Performance	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance

Active DTC			Inh	nibited DT	Cs
P2122 - Accelerator Pedal Position Sensor 1 Circuit Low	P2138 - Accelerator Pedal Position (APP) Sensor 1-2 Correlation				
P2123 - Accelerator Pedal Position Sensor 1 Circuit High	P2138 - Accelerator Pedal Position (APP) Sensor 1-2 Correlation				
P2127 - Accelerator Pedal Position Sensor 2 Circuit Low	P2138 - Accelerator Pedal Position (APP) Sensor 1-2 Correlation				
P2128 - Accelerator Pedal Position (APP) Sensor 2 Circuit High Voltage	P2138 - Accelerator Pedal Position (APP) Sensor 1-2 Correlation				
P2146 - Injector Positive Voltage Control Circuit Group 1	P0606 - Control Module Internal Performance				
P2149 - Injector Positive Voltage Control Circuit Group 2	P0606 - Control Module Internal Performance				
P2152 - Injector Positive Voltage Control Circuit Group 3	P0606 - Control Module Internal Performance				
P2155 - Injector Positive Voltage Control Circuit Group 4	P0606 - Control Module Internal Performance	P2146 - Injector Positive Voltage Control Circuit Group 1	P2149 - Injector Positive Voltage Control Circuit Group 2	P2152 - Injector Positive Voltage Control Circuit Group 3	
P2200 - N0x Sensor Circuit Bank 1 Sensor 1	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P2209 - N0x Heater Performance Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High	
P2202 - N0x Sensor Circuit Low Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High			
P2203 - N0x Sensor Circuit High Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High			ı
P2205 - N0x Heater Control Circuit Bank 1 Sensor 1	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P2209 - N0x Heater Performance Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High	
P2209 - N0x Heater Performance Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High			

P2080 -

Exhaust

Temperature

Performance

P2080 -

Exhaust

Temperature

Sensor 1

P2002 - Diese

Particulate Filter (DPF)

Low Efficience

P2002 - Diese

Particulate Filter (DPF) Low Efficiency

P2084 -

Exhaust

Temperature

Performance

P2084 -

Exhaust

Temperature

Sensor 2

P242B -

Exhaust

Temperature

Sensor 3

Performance

P242B -

Exhaust

Temperature

Sensor 3

P246F -

Exhaust

Temperature Sensor 4

Performance

P2459 - Diese

Particulate

Filter

Regeneration Frequency

P246F -

Exhaust

Temperature

Sensor 4

Active DTC			Inh	ibited DT	Ce			
P220A - N0x Sensor Supply Voltage Out Of Range Bank 1 Sensor 1	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P2209 - N0x Heater Performance Bank 1 Sensor 1		iibited DT				
P220B - N0x Sensor Supply Voltage Out Of Range Bank 1 Sensor 2	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P2209 - N0x Heater Performance Bank 1 Sensor 1						
P2228 - Barometric Pressure Sensor Circuit Low	P0106 - Manifold Absolute Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	1	r
P2229 - Barometric Pressure Sensor Circuit High	P0106 - Manifold Absolute Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	
P2263 - Turbo Boost System Performance	P0101 - Mass Air Flow Sensor Performance	P0106 - Manifold Absolute Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive		
P229E - NOx Sensor Circuit Bank 1 Sensor 2		P11B2 - HO2S Performance - Signal Low During Moderate Load Bank 1 Sensor 2	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High				
P229F - NOx Sensor Performance Bank 1 Sensor 2	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High						
P22A3 - NOx Heater Control Circuit Bank 1 Sensor 2	P11AF - HO2S Performance - Signal High During Moderate Load Bank 1 Sensor 2	P11B2 - HO2S Performance - Signal Low During Moderate Load Bank 1 Sensor 2	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High				
P22A7 - NOx Heater Performance Bank 1 Sensor 2	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High						
P2413 - Exhaust Gas Recirculation (EGR) System Performance	P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High				
P242C - Exhaust Gas Temperature (EGT) Sensor 3 Circuit Low Voltage	P2428 - Exhaust Gas High Temperature	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance					
P242D - Exhaust Gas Temperature (EGT) Sensor 3 Circuit High Voltage	P2428 - Exhaust Gas High Temperature	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance		Γ	T	1	
P2453 - Diesel Particulate Filter Differential Pressure Sensor Performance	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P2002 - Diesel Particulate Filter (DPF) Low Efficiency	P2459 - Diesel Particulate Filter Regeneration Frequency		

Active DTC			Inh	nibited DT	Cs				
P2454 - Diesel Particulate Filter Differential Pressure Sensor Circuit Low Voltage	P2002 - Diesel Particulate Filter (DPF)	P2453 - Diesel Particulate Filter Differential Pressure		P2459 - Diesel Particulate Filter Regeneration					
Chount Loth Vollage	Low Efficiency	Sensor Performance P2453 - Diesel	Sensor Circuit High Voltage P2454 - Diesel	Frequency					
P2455 - Diesel Particulate Filter Differential Pressure Sensor Circuit High Voltage	P2002 - Diesel Particulate Filter (DPF) Low Efficiency	Particulate Filter Differential Pressure Sensor Performance	Particulate Filter Differential Pressure Sensor Circuit Low Voltage	P2459 - Diesel Particulate Filter Regeneration Frequency					
P245A - Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P140A - EGR Cooler BY Pass Position Sensor Exceded Learning Limit	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance	P2510 - ECM Power Relay Circuit Performance	
P2463 - Diesel Particulate Filter - Soot Accumulation	P2002 - Diesel Particulate Filter (DPF) Low Efficiency	P246F -	1						
P2470 - Exhaust Gas Temperature (EGT) Sensor 4 Circuit Low Voltage	P2428 - Exhaust Gas High Temperature	Exhaust Temperature Sensor 4 Performance P246F -							
P2471 - Exhaust Gas Temperature (EGT) Sensor 4 Circuit High Voltage	P2428 - Exhaust Gas High Temperature	Exhaust Temperature Sensor 4 Performance							
P2493 - EGR Cooler BY Pass Position Sensor Performance	Exhaust Gas Recirculation Flow Insufficient	Exhaust Gas Recirculation Flow Excessive		ı	P140A - EGR	ı		Г	
P2494 - EGR Cooler BY Pass Position Sensor Circuit Low	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	Cooler BY Pass Position Sensor Exceded Learning Limit	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance
P2495 - EGR Cooler BY Pass Position Sensor Circuit High	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive	P140A - EGR Cooler BY Pass Position Sensor Exceded Learning Limit	P2080 - Exhaust Temperature Sensor 1 Performance	P2084 - Exhaust Temperature Sensor 2 Performance	P242B - Exhaust Temperature Sensor 3 Performance	P246F - Exhaust Temperature Sensor 4 Performance
P2564 - Turbocharger Boost Control Position Sensor Circuit Low	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive					
P2565 - Turbocharger Boost Control Position Sensor Circuit High	P0234 - Turbocharger Engine Overboost	P0299 - Turbocharger Engine Underboost	P0401 - Exhaust Gas Recirculation Flow Insufficient	P0402 - Exhaust Gas Recirculation Flow Excessive					
P2598 - Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck Low	P0101 - Mass Air Flow Sensor Performance P0101 - Mass								
P2599 - Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck High	Air Flow Sensor Performance	P0852 -	1						
U0073 - CAN A BUS OFF	Park/Neutral Position (PNP) Switch Circuit Low Voltage	Park/Neutral Position (PNP) Switch Circuit High Voltage							

Active DTC			Inf	ibited DT	Cs									
U0101 - Lost Communications With Transmission Control System	P0851 - Park/Neutral Position (PNP) Switch Circuit Low Voltage	P0852 - Park/Neutral Position (PNP) Switch Circuit High Voltage												
U0106 - Lost Communication With Glow Plug Control Module	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High											
U029D - N0x 1 loss of comm	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High												
U029E - N0x 2 loss of comm	P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High											
Fuel Level less than 15%	P0087 - Fuel Rail Pressure Too Low	P0088 - Fuel Rail Pressure Too High	P0191 - Fuel Rail Pressure Sensor Performance	P0263 - Cly 1 Balance System	P0266 - Cly 2 Balance System	P0269 - Cly 3 Balance System	P0272 - Cly 4 Balance System	P0275 - Cly 5 Balance System	P0278 - Cly 6 Balance System	P0281 - Cly 7 Balance System	P0284 - Cly 8 Balance System	P0300 - Engine Misfire Detected	P0301 - Cylinder 1 Misfire Detected	
Fuel Level less than 15%	P0302 - Cylinder 2 Misfire Detected	P0303 - Cylinder 3 Misfire Detected	P0304 - Cylinder 4 Misfire Detected	P0305 - Cylinder 5 Misfire Detected	P0306 - Cylinder 6 Misfire Detected	P0307 - Cylinder 7 Misfire Detected	P0308 - Cylinder 8 Misfire	Performance - Signal High During	Signal Low During Moderate Load	P128E - Fuel Rail Pressure Performance				

This document is intended to meet the requirements documented in section 1968.2 of Title 13, California Code of Regulations entitled Modifications to Malfunction and Diagnosis System Requirements for 2004 and Subsequent Model-Year Passenger Cars, Light-Duty Trucks, and Medium-Duty Vehicles and Engines (OBD II), paragraphs (i)(2.2) for a table detailing **supplemental** calibration parameter data for OBD II Group 13OBDG09.

Disable Matrix for Diagnostic System Manager

Disable Matrix for Dia	<u> </u>								
DTC			asic Enable	e Condition	าร				
P0016 - Crankshaft to Camshaft Correlation	Engine not in afterrun mode (defined as engine speed greater than 0		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)					
P003A - Turbocharger Boost Control Position Not Learned	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	3		
P0045 - Turbocharger Boost Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm					
P0047 - Turbocharger Boost Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0	ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm					
P0048 - Turbocharger Boost Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0	ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm					

DTC	Α	dditional B	asic Enabl	e Conditio	าร			
P006E - Turbocharger Boost High Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	(standby state occurs after ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm				
P006F - Turbocharger Boost High Control Circuit High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)							
P007C - CAC Temperature Sensor Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P007D - CAC Temperature Sensor Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0087 - Fuel Rail Pressure Too Low	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)					

DTC		Additional B	asic Enabl	e Conditio	าร
P0088 - Fuel Rail Pressure Too High	ambient a temperature above -7 d C	e is ambient	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P008F - Engine Coolant Temperature (ECT)-Fuel Temperature Not Plausible	Engine not afterrun mo (defined a engine spe greater than rpm)	Engine speed greater than	initialization or	Engine is running which means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0090 - Fuel Pressure Regulator 1 Control Circuit/Open	Engine not afterrun mo (defined a engine spe greater tha rpm)	de (standby state s occurs after ed ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P0091 - Fuel Pressure Regulator 1 Control Circuit Low	Engine not afterrun mo (defined a engine spe greater than rpm)	de (standby state s occurs after ed ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P0092 - Fuel Pressure Regulator 1 Control Circuit High	Engine not afterrun mo (defined a engine spe greater thai rpm)	de (standby state s occurs after ed ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	

DTC	Additional Basic Enable Conditions
P0097 - Intake Air Temperature Sensor 2 Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0098 - Intake Air Temperature Sensor 2 Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 to standby state occurs after ECM initialization or following afterrun) Engine speed greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)
P00C9 - Fuel Pressure Regulator 1 High Control Circuit Low Voltage	engine is not in standby state (standby state occurs after engine speed greater than 0 rpm) engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Engine is not in standby state occurs after battery voltage is above 11 V for at least 3s Engine is running which means the engine speed is greater than 600 to 850 rpm
P00CA - Fuel Pressure Regulator 1 High Control Circuit High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following after-run)
P00EA - Intake Air Temperature (IAT) Sensor 3 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed engine is not in standby state estandby state occurs after ECM initialization or following afterrun) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)

DTC	Additional Basic Enable Conditions
P00EB - Intake Air Temperature (IAT) Sensor 3 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine is not in standby state (standby state occurs after ECM initialization or following after run) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed is above 11 V for at least 3s on or following a stall of the engine)
P00F4 - Humidity Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm (spm) Engine speed greater than 600 to 850 rpm (rpm) Engine speed greater than 600 to 850 rpm (spm) Engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Engine speed greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P00F5 - Humidity Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm following afterrun) Engine speed speed greater than 600 to 850 rpm following afterrun) Engine speed speed greater than 600 to 850 rpm following afterrun) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine is active when the indicate the engine is active when the indicate the engine speed is greater than 600 to 850 rpm to indicate the engine is active when
P00F6 - Humidity Sensor Circuit Intermittent/Erratic	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm following after-run) Engine speed speed greater than 600 to 850 rpm following after-run) Engine speed speed greater than 600 to 850 rpm following after-run) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed is greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time is greater than 10 seconds (engine speed is greater than 600 to 850 rpm to indicate the engine speed is greater than 600 to 850 rpm to indicate the engine is running)

DTC	Additi	ional Basic Enabl	e Conditio	ns					
P0101 - Mass Air Flow Sensor Performance	engine speed great	engine is not ir standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0102 - Mass Air Flow Sensor Circuit Low	engine speed great	engine is not ir standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P0103 - Mass Air Flow Sensor Circuit High	engine speed great	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P0106 - Manifold Absolute Pressure Sensor Performance	Engine speed greater than 600 to 850 rpm initialitiality	e is not in dby state dby state urs after ECM ization or ving after-run)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			•		

DTC	Ad	ditional B	asic Enable	e Condition	าร			
P0107 - Manifold Absolute Pressure (MAP) Sensor Circuit Low Voltage	(defined as	Engine speed greater than 000 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0108 - Manifold Absolute Pressure (MAP) Sensor Circuit High Voltage	(defined as	Engine speed greater than 300 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0112 - Intake Air Temperature Sensor 1 Circuit Low	(defined as	Engine speed greater than 300 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0113 - Intake Air Temperature Sensor 1 Circuit High	(defined as	Engine speed greater than 300 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	Additio	nal Basic Enab	le Conditio	ns				
P0117 - Engine Coolant Temperature Sensor Circuit Low	engine is not in standby state	voltage re 11 V						
P0118 - Engine Coolant Temperature Sensor Circuit High	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)							
P0128 - Engine Coolant Temperature Below Thermostat Regulating Temperature	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	er than ECM initialization or	Engine is	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P0131 - HO2S Bank 1 Sensor 1 circuit low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine greate 600 to 8	er than occurs after	Counter is zero (value of 0 means ECM is locked and	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0132 - HO2S Bank 1 Sensor 1 circuit high	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine greate 600 to 8	er than occurs after	Counter is zero (value of 0 means ECM is locked and	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	А	dditional B	Basic Enabl	e Conditio	าร					
P0137 - HO2S Bank 1 Sensor 2 circuit low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Counter is zero (value of	for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P0138 - HO2S Bank 1 Sensor 2 circuit high	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	initialization or	Enable Counter is	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P014C - HO2S Slow Response Rich to Lean Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Counter is zero (value of 0 means ECM	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0171 - Fuel Trim System Lean	System is not in active regeneration mode									
P0172 - Fuel Trim System Rich	System is not in active regeneration mode									

DTC	Additional Basic Enable Conditions
P0182 - Fuel Temperature Sensor 1 Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm Engine speed greater than 600 to 850 rpm Engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Engine speed greater than 600 to 850 rpm following afterrun) Engine Run Time greater than 10 seconds (engine speed is above 11 V for at least 3s) Engine Run Time greater than 10 seconds (engine speed is above 11 V for at least 3s) Engine is not in ready state (which is active when the ignition is is greater than 600 to 850 rpm to indicate the engine is running) Engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0183 - Fuel Temperature Sensor 1 Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm rpm) Engine speed greater than following afterrun) Engine speed greater than following afterrun) Engine speed standby state (standby state occurs after ECM initialization or following afterrun) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)
P0191 - Fuel Rail Pressure Sensor Performance	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0192 - Fuel Rail Pressure Sensor Circuit Low	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s
P0193 - Fuel Rail Pressure Sensor Circuit High	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s

DTC	Δ	dditional R	asic Fnahle	Conditions
P01CB - Cylinder 1 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when	
P01CC - Cylinder 1 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	on or following a stall of the engine)	
P01CD - Cylinder 2 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01CE - Cylinder 2 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01CF - Cylinder 3 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01D0 - Cylinder 3 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC		dditional	acia Enabla Canditiana
DTC	P	daitional B	asic Enable Conditions
P01D1 - Cylinder 4 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P01D2 - Cylinder 4 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P01D3 - Cylinder 5 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P01D4 - Cylinder 5 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P01D5 - Cylinder 6 Injection Timing Retarded	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P01D6 - Cylinder 6 Injection Timing Advanced	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

DTC	Additional Basic Enable Conditions	
P01D7 - Cylinder 7 Injection Timing Retarded	engine is not in ready state (which is active when the ignition is on or following a stall of the engine) engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01D8 - Cylinder 7 Injection Timing Advanced	engine is not in ready state ambient air temperature is above -7 deg C ambient pressure is above 74.8kPa C engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01D9 - Cylinder 8 Injection Timing Retarded	engine is not in ready state ambient air temperature is above -7 deg C C engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01DA - Cylinder 8 Injection Timing Advanced	engine is not in ready state (which is active when the ignition is on or following a stall of the engine) engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P01F0 - Coolant Temperature Dropped Below Diagnostic Monitoring Temperature	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm) engine is not in standby state (standby state occurs after engine speed initialization or following afterrun) engine is not in standby state (which is neans the engine speed is greater than 600 to 850 rpm following afterrun) engine is not in standby state (which is neans the engine speed is greater than 600 to 850 rpm a stall of the engine)	

DTC	A	dditional B	asic Enabl	e Condition	18					
P0234 - Turbocharger Engine Overboost	Engine not in afterrun mode (defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after		ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0263 - Cly 1 Balance System	Power Take- Off (PTO) is not engaged									
P0266 - Cly 2 Balance System	Power Take- Off (PTO) is not engaged									
P0269 - Cly 3 Balance System	Power Take- Off (PTO) is not engaged									
P026A - CAC Effiecientcy Below Threshold	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P026C - Injection Quantity Too Low	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	Power Take- Off (PTO) is not engaged	System is not in active regeneration mode						
P026D - Injection Quantity Too High	C	ambient pressure is above 74.8kPa	Power Take- Off (PTO) is not engaged	System is not in active regeneration mode						
P0272 - Cly 4 Balance System	Power Take- Off (PTO) is not engaged									
P0275 - Cly 5 Balance System	Power Take- Off (PTO) is not engaged									
P0278 - Cly 6 Balance System	Power Take- Off (PTO) is not engaged									

DTC	Ad	ditional B	asic Enable	e Condition	าร				
P0281 - Cly 7 Balance System	Power Take- Off (PTO) is not engaged								
P0284 - Cly 8 Balance System	Power Take- Off (PTO) is not engaged								
P0299 - Turbocharger Engine Underboost	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	active when the ignition is on or following
P02E0 - Intake Air Flow Valve Control Circuit	occurs after i	pattery voltage is above 11 V for at least 3s							
P02E2 - Intake Air Flow Valve Control Circuit 1 Low Voltage	occurs after i	pattery voltage is above 11 V for at least 3s							
P02E3 - Intake Air Flow Valve Control Circuit 1 High Voltage	occurs after	pattery voltage is above 11 V for at least 3s							

DTC	A	dditional B	asic Enabl	e Conditio	าร			
P02E7 - Diesel Intake Air Flow Position Sensor Circuit Range Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)		Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P02E8 - Diesel Intake Air Flow Position Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P02E9 - Diesel Intake Air Flow Position Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P02EB - Intake Air Flow Valve Control Motor Current Performance	engine is not in standby state (standby state occurs after ECM initialization or following after- run)							
P0300 - Engine Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)							

DTC	Additional Basic Enable Condition
P0301 - Cylinder 1 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0302 - Cylinder 2 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0303 - Cylinder 3 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0304 - Cylinder 4 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0305 - Cylinder 5 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0306 - Cylinder 6 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

DTC	Λ.	dditional D	acic Enabl	e Conditions
DIC		uullional B	asic Eliable	e Conditions
P0307 - Cylinder 7 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P0308 - Cylinder 8 Misfire Detected	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P0335 - Crankshaft Position Sensor Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0336 - Crankshaft Position Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0340 - Camshaft Position Sensor Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P0341 - Camshaft Position Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

DTC	А	dditional B	asic Enabl	e Conditio	าร						
P0381 - Wait to Start Lamp Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	(standby state occurs after ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm							
P0400 - Exhaust Gas Recirculation (EGR) Flow Incorrect	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	active when the ignition is on or following		
P0401 - Exhaust Gas Recirculation Flow Insufficient	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0402 - Exhaust Gas Recirculation Flow Excessive	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0403 - Exhaust Gas Recirculation (EGR) Motor Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s									

DTC	Addi	ditional Ba	asic Enable	e Condition	าร			
P0405 - Exhaust Gas Recirculation Position Sensor Circuit Low	(defined as gr	ngine speed greater than 10 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0406 - Exhaust Gas Recirculation Position Sensor Circuit High	(defined as gr	ngine speed greater than 10 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P040C - Exhaust Gas Recirculation (EGR) Temperature Sensor 2 Circuit Low Voltage	(defined as gr	ngine speed greater than 10 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P040D - Exhaust Gas Recirculation (EGR) Temperature Sensor 2 Circuit High Voltage	(defined as gr	ngine speed greater than 00 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)		engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	Addition	Il Basic Enabl	e Conditio	ns					
P040F - Exhaust Gas Recirculation (EGR) Temperature Sensor 1-2 Correlation	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed Greater than 0	rpm occurs after ECM initialization or	Engine is	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)					
P041C - Exhaust Gas Recirculation (EGR) Temperature Sensor 1 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm)	an occurs aπer	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P041D - Exhaust Gas Recirculation (EGR) Temperature Sensor 1 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed 600 to 850	occurs aπer	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P0420 - NMHC Catalyst Efficiency Below Threshold Bank 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm)	ian occurs after	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		

DTC	A	dditional B	asic Enabl	e Conditio	ns			
P0461 - Fuel Level Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0462 - Fuel Level Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0463 - Fuel Level Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P046C - Exhaust Gas Recirculation(EGR) Position Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P0480 - Cooling Fan Speed Output Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm			-	

DTC	Ac	dditional B	asic Enabl	e Conditio	ns				
P0483 - Cooling Fan System Performance	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Counter is zero (value of 0 means ECM	ambient pressure is above 74.8kPa	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P0489 - Exhaust Gas Recirculation (EGR) Motor Control Circuit 1 Low Voltage	occurs after	battery voltage is above 11 V for at least 3s							
P0490 - Exhaust Gas Recirculation (EGR) Motor Control Circuit 1 High Voltage	occurs after	battery voltage is above 11 V for at least 3s							
P0495 - Cooling Fan Speed High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P049D - EGR Control Position Not Learned	occurs after	battery voltage is above 11 V for at least 3s						-	

DTC	Ac	dditional B	asic Enabl	e Conditio	าร			
P0506 - Idle Speed Low	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)						
P0507 - Idle Speed High	than 10 seconds (engine speed greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)						
P0526 - Cooling Fan Speed Sensor Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm		
P0545 - Exhaust Gas Temperature (EGT) Sensor 1 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm			
P0546 - Exhaust Gas Temperature (EGT) Sensor 1 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm			

DTC	A	dditional B	asic Enabl	e Conditio	าร			
P0567 - Cruise Control Resume Switch Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0568 - Cruise Control Set Switch Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0575 - Cruise Control Input Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P057C - Brake Pedal Position Sensor Circuit High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following after- run)							
P057D - Brake Pedal Position Sensor Circuit Low Voltage	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)							

DTC	Α	dditional B	asic Enabl	e Conditio	าร	
P0606 - Control Module Internal Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	than 10 seconds (engine speed greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P0627 - Fuel Pump Relay Control Circuit	battery voltage is above 11 V for at least 3s	ļ				
P0628 - Fuel Pump Relay Control Circuit Low	battery voltage is above 11 V for at least 3s					
P0629 - Fuel Pump Relay Control Circuit High	battery voltage is above 11 V for at least 3s	[
P062F - Control Module Long Term Memory Performance	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)					
P0640 - Intake Air (IA) Heater Switch/Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				
P0641 - 5 Volt Reference 1 Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				

DTC	Λ	dditional P	asic Enabl	e Condition
P064C - Glow Plug Control Module Performance	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)		asic Eliabi	e Condition
P0650 - Malfunction Indicator Lamp Control Circuit	(defined as engine speed	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm
P0651 - 5 Volt Reference 2 Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s		
P0671 - Glow Plug 1 Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)			
P0672 - Glow Plug 2 Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)			
P0673 - Glow Plug 3 Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s		

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DTC		A	dditional B	asic Enable Conditions
P0674 - Glow Plug 4 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P0675 - Glow Plug 5 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P0676 - Glow Plug 6 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P0677 - Glow Plug 7 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P0678 - Glow Plug 8 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P0697 - 5 Volt Reference 3 Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	

DTC		المرادات المادات
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P06A3 - 5 Volt Reference 4 Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s
P06D2 - 5 Volt Reference 5 Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s
P0700 - Transmission Control Module Requested Malfunction Indicator Lamp Illumination	engine is not ir standby state (standby state occurs after ECM initialization or following afterrun)	
P0851 - Park/Neutral Position (PNP) Switch Circuit Low Voltage	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	
P0852 - Park/Neutral Position (PNP) Switch Circuit High Voltage	engine is not ir standby state (standby state occurs after ECM initialization or following afterrun)	

DTC	Additional	Basic Enable Condition	ons		
P1043 - Reductant Pump High Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm)	occurs after (engine spee	Engine is running which d means the engine speed the is greater than on	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P1044 - Reductant Pump High Control Circuit High Voltage	Engine speed greater than 600 to 850 rpm following after run)	than 10 Engine is running whice (engine speed greater than or 600 to 850 rpm is greater than	active when the ignition is on or following		
P1048 - Reductant Injector High Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 0 rpm)	occurs after is above 11	(engine speed) greater than e	Engine is running which means the engine speed s greater than 600 to 850 rpm engine is not ready state (which is active when the ignition is on or followin a stall of the engine)	s s
P1049 - Reductant Injector High Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine spee greater than 600 to 850 rp	occurs after is above 11	(engine speed		s s

DTC	Α	dditional B	asic Enabl	e Condition	าร
P10CC - Exhaust Aftertreatment Fuel Injector Control Circuit Shorted	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P10CD - Exhaust Aftertreatment Fuel Injector High Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P10CE - Exhaust Aftertreatment Fuel Injector High Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	
P10D0 - Reductant Injector Temperature - Exhaust Gas Temperature 2 Correlation	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P111F - Fuel Temperature Sensor 1 - Fuel Temperature Sensor 2 Not Plausible	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)		engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P113A - Exhaust Gas Temperature Sensors 3-4 Not Plausible	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

DTC	A	dditional B	asic Enabl	e Conditio	าร				
P11A6 - HO2S Performance - Signal High During Moderate Load Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P11A9 - HO2S Performance - Signal Low During Moderate Load Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P11AF - HO2S Performance - Signal High During Moderate Load Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P11B2 - HO2S Performance - Signal Low During Moderate Load Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	A	dditional B	asic Enabl	e Conditio	18						
P11B4 - HO2S Current Performance Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P11B5 - HO2S Current Performance Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P11CB - NOx Sensor Performance - Signal High Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P11CC - NOx Sensor Performance - Signal Low Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	regeneration	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

	DTC Additional Basic Enable Conditions													
DTC		Ad	dditional B	asic Enabl	e Conditior	าร								
P11DB - NOx Sensor Current Performance Bank 1 Sensor 1	a e	Engine not in fterrun mode (defined as engine speed reater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P11DC - NOx Sensor Current Performance Bank 1 Sensor 2	a e	Engine not in fterrun mode (defined as engine speed reater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P122C - Intake Air Flow Valve Control Circuit Shorted	s (s	ngine is not in standby state standby state occurs after ECM stalication or ollowing afterrun)	battery voltage is above 11 V for at least 3s											
P122D - Diesel Intake Air Flow Position Sensor Exceeded Learning Limit	s (s	ngine is not in standby state standby state occurs after ECM nitialization or ollowing afterrun)	battery voltage is above 11 V for at least 3s											
P122E - Intake Air Flow Valve Control Circuit 2 Low Voltage	s (s	ngine is not in standby state standby state occurs after ECM nitialization or	battery voltage is above 11 V for at least 3s											

following afterrun)

DTC	A	dditional B	asic Enabl	e Condition
P122F - Intake Air Flow Valve Control Circuit 2 High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s		
P125A - Fuel Pressure Regulator 2 High Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	(standby state occurs after	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm
P125B - Fuel Pressure Regulator 2 High Control Circuit High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following after- run)			
P128E - Fuel Rail Pressure Performance	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P1407 - Exhaust Gas Recirculation (EGR) Motor Control Circuit Shorted	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s		

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DTC	Δ	Additional B	asic Enabl	e Conditio	ns						
P140B - Exhaust Gas Recirculation Slow Response-Increasing Flow	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	ambient air temperature is above -7 deg	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	(engine speed	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P140C - Exhaust Gas Recirculation Slow Response-Decreasing Flow	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	(engine speed	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P140D - Exhaust Gas Recirculation (EGR) Motor Control Circuit 2 Low Voltage	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s									
P140E - Exhaust Gas Recirculation (EGR) Motor Control Circuit 2 High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following after run)	battery voltage is above 11 V for at least 3s									
P140F - Exhaust Gas Recirculation (EGR) Motor Current Performance	engine is not in standby state (standby state occurs after ECM										

initialization or following afterrun)

for at least 3s

DTC	A	dditional B	asic Enabl	e Conditio	าร	
P144B - Closed Loop Diesel Particulate Filter (DPF) Regeneration Control At Limit - Stage 1 Temperature Too Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P144C - Closed Loop Diesel Particulate Filter (DPF) Regeneration Control At Limit - Stage 1 Temperature Too High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P154A - Intake Air (IA) Heater Feedback Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				
P154B - Intake Air (IA) Heater Voltage Signal Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				
P154C - Intake Air (IA) Heater Current Signal Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				

DTC	Additional Basic Enable Conditions
P154D - Intake Air (IA) Heater Temperature Signal Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s
P160C - Engine Calibration Information Not Programed In The Control Module	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode) Manufacturer Enable Counter is zero (value of 0 means ECM is above 11 V for at least 3s
P161A - Glow Plug Control Module Not Programed	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s
P1631 - Theft Deterrent Fuel Enable Signal Not Correct	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) rpm) engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P163C - Glow Plug Control Module Primary Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s

DTC	Α	dditional B	asic Enabl	e Conditio	ns				
P163D - Glow Plug Control Module Secondary Circuit	Engine not in afterrun mode (defined as engine speed	engine is not in standby state	battery voltage is above 11 V for at least 3s						
P163E - Glow Plug Control ModuleOvertemperature	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s							
P166B - Intake Air (IA) Heater Over Temperature	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s							
P2002 - Diesel Particulate Filter (DPF) Low Efficiency	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg C	pressure is	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P202E - Reductant Injector Performance	SCR Reductant Level not in restriction or empty level state (see reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)		Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	Additional E	Basic Enable Condit	ons				
P2032 - Exhaust Gas Temperature (EGT) Sensor 2 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after-run)	V means the				
P2033 - Exhaust Gas Temperature (EGT) Sensor 2 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after-run)	v means the				
P203B - Reductant Level Sensor 1 Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	V temperature is	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	O .	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P203C - Reductant Level Sensor 1 Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	greater than 600 to 850 rpm	Engine is running which means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		

DTC	A	dditional B	asic Enabl	e Conditio	ns		
P203D - Reductant Level Sensor 1 Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2047 - Reductant Injector Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2048 - Reductant Injector Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2049 - Reductant Injector Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)

DTC	A	dditional B	asic Enabl	e Conditio	าร					
P204B - Reductant Pump Pressure Sensor Performance	engine is not in standby state (standby state occurs after ECM initialization or following after- run)									
P204C - Reductant Pump Pressure Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	_			
P204D - Reductant Pump Pressure Sensor Circuit High	engine is not in standby state (standby state occurs after ECM initialization or following after- run)									
P204F - Reductant System Performance Bank 1 (cannot build pump pressure)	SCR Reductant Level not in restriction or empty level state (see reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P205B - Reductant Tank Temperature Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	active when the ignition is on or following			

DTC	Additional	Basic Enab	le Conditio	ns		
P205C - Reductant Tank Temperature Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	οccurs aπer	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P205D - Reductant Tank Temperature Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine spe greater tha 600 to 850 r	occurs after	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2080 - Exhaust Temperature Sensor 1 Performance	Manufactur Enable Counter is Zero (value greater than 600 to 850 rpm is locked ar out of assembly pl mode)	Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P2084 - Exhaust Temperature Sensor 2 Performance	Manufactur Enable Counter is zero (value greater than 600 to 850 rpm assembly pl mode)	of M d Greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		

DTC	Additional	Basic Enabl	e Conditio	ns					
P208A - Reductant Pump Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine spe greater than 0 rpm)	n occurs after	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P208B - Reductant Pump Performance	engine is not in standby state (standby state occurs after ECM initialization or following afterrun) Manufactur Enable Counter is zero (value 0 means EC is locked arout of assembly pl mode)	of battery voltage M is above 11 V d for at least 3s	Status of the Reductant Tank is not Frozen which means ambient air temperature is >= -7°C and the reductatn tank temperature is >= -7°C				-		
P208D - Reductant Pump Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) Engine spe greater tha 600 to 850 r	n occurs after	than 10 seconds (engine speed greater than 600 to 850 rpm	engine speed is greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P20A0 - Reductant Purge Valve Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	n occurs after	than 10 seconds (engine speed greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				

DTC	Δ	dditional B	asic Fnahl	e Conditio	ns	
P20A1 - Reductant Purge Valve Performance	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s	375 E11401	o condition		
P20A2 - Reductant Purge Valve Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P20A3 - Reductant Purge Valve Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P20B9 - Reductant Heater 1 Control Circuit	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				•
P20BA - Reductant Heater 1 Performance	SCR Reductant Level not in restriction or empty level state (see reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm

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DTC		A	dditional B	asic Enable Conditions
P20BB - Reductant Heater 1 Control Circuit Low		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P20BC - Reductant Heater 1 Control Circuit High		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P20BD - Reductant Heater 2 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P20BF - Reductant Heater 2 Control Circuit Low		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P20C0 - Reductant Heater 2 Control Circuit High		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	
P20C1 - Reductant Heater 3 Control Circuit		engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	

DTC	A	dditional B	asic Enabl	e Conditio	าร				
P20C3 - Reductant Heater 3 Control Circuit Low	engine is not in standby state (standby state occurs after ECM initialization or following after- run)								
P20C4 - Reductant Heater 3 Control Circuit High	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s							
P20CB - Exhaust Aftertreatment Fuel Injector Control Circuit	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)		battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm					
P20CC - Exhaust Aftertreatment Fuel Injector Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine is running which means the engine speed is greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P20CD - Exhaust Aftertreatment Fuel Injector Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	(standby state occurs after ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm		_			
P20CE - Exhaust Aftertreatment Fuel Injector Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	(standby state occurs after ECM	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm					

DTC	A	dditional B	asic Enabl	e Conditio	ns						
P20E2 - Exhaust Gas Temperature (EGT) Sensors 1-2 not plausible	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	initialization or	Engine is	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)						
P20E8 - Reductant Pressure Too Low	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)		engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P20E9 - Reductant Pressure Too High	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	600 to 850 rpm	means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P20EE - SCR Nox Catalyst Efficiency Below Threshold Bank 1	SCR Reductant Level not in restriction or empty level state (see reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Status of the Reductant Tank is not Frozen which means ambient air temperature is >= -7°C and the reductatn tank temperature is >= -7°C	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed is greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	Λ	dditional B	asic Fnahl	e Condition	ne					
P214F - Reductant Heater 1 Current Too High	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)		Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P21AA - Reductant Level Sensor 2 Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm				
P21AB - Reductant Level Sensor 2 Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	U			
P21AF - Reductant Level Sensor 3 Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			

DTC	Ac	dditional B	asic Enabl	e Conditio	ns				
P21B0 - Reductant Level Sensor 3 Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	_		
P21DD - Reductant Heater 1 Current Too Low	restriction or empty level state (see parameter definitions for	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2200 - N0x Sensor Circuit Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2202 - N0x Sensor Circuit Low Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

DTC	Δ	dditional B	asic Fnahl	e Condition	าร				
P2203 - N0x Sensor Circuit High Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2205 - N0x Heater Control Circuit Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2209 - N0x Heater Performance Bank 1 Sensor 1	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Counter is zero (value of	for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P220A - N0x Sensor Supply Voltage Out Of Range Bank 1 Sensor 1	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s							
P220B - N0x Sensor Supply Voltage Out Of Range Bank 1 Sensor 2	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s							

DTC	A	dditional B	asic Enabl	e Conditio	าร				
P221C - Reductant Heater 2 Current Too Low	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P221D - Reductant Heater 2 Current Too High	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	-	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P221E - Reductant Heater 3 Current Too Low	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P221F - Reductant Heater 3 Current Too High	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	O .	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	

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DTC	A	aditional B	asic Enabl	e Condition	1S		
P2228 - Barometric Pressure Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2229 - Barometric Pressure Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2263 - Turbo Boost System Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2295 - Fuel Pressure Regulator 2 Control Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm			
P2296 - Fuel Pressure Regulator 2 Control Circuit High Voltage	Engine not in afterrun mode (defined as engine speed	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm			

DTC	A	dditional B	asic Enabl	e Conditio	ns						
P229E - NOx Sensor Circuit Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	is above 11 V for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P229F - NOx Sensor Performance Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed is greater than	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P22A0 - NOx Sensor Circuit Low Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	for at least 3s	greater than 600 to 850 rpm	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P22A1 - NOx Sensor Circuit High Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			

DTC	А	dditional B	asic Enabl	e Conditio	าร				
P22A3 - NOx Heater Control Circuit Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P22A7 - NOx Heater Performance Bank 1 Sensor 2	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P22FA - NOx Sensor 1 Performance - Slow Response High to Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Engine Run Time is greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	System is not in active regeneration mode	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2428 - Exhaust Gas High Temperature	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				

DTC	A	dditional B	asic Enabl	e Conditio	าร				
P242B - Exhaust Temperature Sensor 3 Performance	Engine speed greater than 600 to 850 rpm	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)		Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)				
P242C - Exhaust Gas Temperature (EGT) Sensor 3 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm				
P242D - Exhaust Gas Temperature (EGT) Sensor 3 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm				
P2453 - Diesel Particulate Filter Differential Pressure Sensor Performance	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Enable Counter is	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is runing which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2454 - Diesel Particulate Filter Differential Pressure Sensor Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		

DTC	Ac	dditional B	asic Enabl	e Conditio	าร					
P2455 - Diesel Particulate Filter Differential Pressure Sensor Circuit High Voltage	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	active when the ignition is on or following			
P2457 - Exhaust Gas (EGR) Cooler Performance	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	ambient air temperature is above -7 deg	ambient pressure is above 74.8kPa	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2459 - Diesel Particulate Filter Regeneration Frequency	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa								
P245A - Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit		battery voltage is above 11 V for at least 3s								
P245C - Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 1 Low Voltage	occurs after	battery voltage is above 11 V for at least 3s								

DTC	A	dditional B	asic Enabl	e Conditio	ns	
P245D - Exhaust Gas Recirculation (EGR) Cooler Bypass Valve Control Circuit 1 High Voltage	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				
P2459 - Diesel Particulate Filter Regeneration Frequency	ambient air temperature is above -7 deg C	ambient pressure is above 74.8kPa				
P2463 - Diesel Particulate Filter - Soot Accumulation	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	initialization or	than 10	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P246F - Exhaust Temperature Sensor 4 Performance	Engine speed greater than 600 to 850 rpm	0 means ECM	to indicate the	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P2470 - Exhaust Gas Temperature (EGT) Sensor 4 Circuit Low Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	

DTC	A	dditional B	asic Enabl	e Conditio	ns						
P2471 - Exhaust Gas Temperature (EGT) Sensor 4 Circuit High Voltage	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm						
P249D - Closed Loop Reductant Injection Control At Limit - Flow Too Low	SCR Reductant Level not in restriction or empty level state (see reductant leve warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	Status of the Reductant Tank is not Frozen which means ambient air temperature is >= -7°C and the reductatn tank temperature is >= -7°C	600 to 850 rpm to indicate the engine is		engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P249E - Closed Loop Reductant Injection Control At Limit - Flow Too High	SCR Reductant Level not in restriction or empty level state (see reductant leve warning definition)	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)	battery voltage is above 11 V for at least 3s	temperature is	engine is	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
P24A0 - Closed Loop Particulate Filter Regeneration Control At Limit - Temperature Too Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	greater than	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	than 10 seconds (engine speed greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)					

DTC	A	dditional B	asic Enabl	e Conditio	าร				
P24A1 - Closed Loop Particulate Filter Regeneration Control At Limit - Temperature Too High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			
P2510 - ECM Power Relay Circuit Performance	battery voltage is above 11 V for at least 3s								
P2564 - Turbocharger Boost Control Position Sensor Circuit Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P2565 - Turbocharger Boost Control Position Sensor Circuit High	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine Run Time greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running)	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)		
P2598 - Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck Low	Engine not in afterrun mode (defined as engine speed greater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)			

DTC	Α.	dditional D	ooio Enabl	o Condition	20	
DTC	A	daitional B	asic Enabl		15	
P2599 - Turbocharger Boost Control Position Sensor "A" Circuit Range/Performance - Stuck High	(defined as	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)
P2610 - Control Module Ignition Off Timer Performance	engine is not in standby state (standby state occurs after ECM initialization or following afterrun)	battery voltage is above 11 V for at least 3s				
P268A - Fuel Injector Calibration Not Programmed ECM	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)					
P268C - Cylinder 1 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)					
P268D - Cylinder 2 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)					

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DTC	Additional Basic Enable Conditions
P268E - Cylinder 3 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P268F - Cylinder 4 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P2690 - Cylinder 5 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P2691 - Cylinder 6 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P2692 - Cylinder 7 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)

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DTC	Additional Basic Enable Conditions
P2693 - Cylinder 8 Injector Data Incorrect	Manufacturer Enable Counter is zero (value of 0 means ECM is locked and out of assembly plant mode)
P2BAD - Exhaust NOx Concentration High - Unknown Reason	SCR Reductant Level not in restriction or empty level state (see parameter definitions for reductant level warning definition) Engine speed greater than of remaining definition) Engine speed greater than of the parameter definitions for reductant level warning definition) Engine speed engine is not in standby state (standby state (standby state (standby state) occurs after ECM initialization or following after-run) Engine speed engine is not in standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after ECM initialization or following after-run) Engine speed greater than of the standby state (standby state) occurs after the standby state (standby state) occurs after the standby state (standby state) occurs after the ambient air temperature is seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Status of the Reductant Tank is not Frozen which means the ambient air temperature is seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Engine speed greater than 10 seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running) Status of the Reductant Tank is not Frozen which means the ambient air temperature is seconds (engine speed greater than 600 to 850 rpm to indicate the engine is running which means the ambient air temperature is seconds (engine speed greater than 600 to 850 rpm to indicate the engine is not in Tank is not Frozen which means the a
U0073 - CAN A BUS OFF	Engine not in afterrun mode (defined as engine speed greater than 0 rpm) engine is not in standby state occurs after ECM initialization or following after-run) engine is not in standby state battery voltage is above 11 V for at least 3s
U0074 - CAN B BUS OFF	engine is not in standby state (standby state (defined as engine speed greater than 0 rpm) engine is not in standby state (standby state occurs after ECM initialization or following afterrun) engine is not in standby state (standby state occurs after ECM initialization or following afterrun) battery voltage is above 11 V for at least 3s
U0101 - Lost Communications With Transmission Control System	engine is not in standby state afterrun mode (defined as engine speed greater than 0 initialization or

greater than 0 initialization or

rpm)

following after-

run)

DTC		A	dditional B	asic Enabl	e Conditior	าร			
U0106 - Lost Communication With Glow Plug Control Module	afte (c en	ngine not in errun mode defined as gine speed eater than 0	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s					
U010E - Lost Communications With Reductant Control Module	afte (c en	ngine not in errun mode defined as gine speed eater than 0 rpm)	Engine speed greater than 600 to 850 rpm	engine is not in standby state (standby state occurs after ECM initialization or following after- run)	battery voltage is above 11 V for at least 3s	greater than 600 to 850 rpm	Engine is running which means the engine speed is greater than 600 to 850 rpm	engine is not in ready state (which is active when the ignition is on or following a stall of the engine)	
U029D - N0x 1 loss of comm	afte (c en	ngine not in errun mode defined as gine speed eater than 0 rpm)	Engine speed greater than 600 to 850 rpm	battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm				
U029E - N0x 2 loss of comm	afte (c en	ngine not in errun mode defined as gine speed eater than 0 rpm)		battery voltage is above 11 V for at least 3s	Engine is running which means the engine speed is greater than 600 to 850 rpm				